
python_ics Documentation

Release 910.10

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Intrepid Control Systems, Inc. open source Python module for interfacing to Intrepid hardware. Basic knowledge of using and installing Python modules is assumed. Please see <https://docs.python.org/3/installing/index.html> for documentation on how to install Python modules.

This module is essentially just a wrapper around icsneo40.dll. For more documentation please visit neoVI DLL Documentation under <https://intrepidcs.com/support/support-resources/>

CHAPTER 1

Whats New?

v903+ is a new release that implements features that break existing API in some areas.

1.1 ISO 15765-2

old naming conventions have been updated to reflex closer to the actual codebase.

```
# Old:
tx_msg = ics.CmISO157652TxMessage()
rx_msg = ics.CmISO157652RxMessage()

# New:
tx_msg = ics.st_cm_iso157652_tx_message.st_cm_iso157652_tx_message()
rx_msg = ics.st_cm_iso157652_rx_message.st_cm_iso157652_rx_message()
```

`ics.st_cm_iso157652_tx_message.st_cm_iso157652_tx_message()` data structure is now a `ctypes.c_ubyte` array instead of a python list.

```
# Old:
msg.data = [x for x in range(number_of_bytes)]

# New:
my_data = [x for x in range(number_of_bytes)]
msg.data = (ctypes.c_ubyte*len(msg.data))(*my_data)

>>> msg.data
<ics.structures.st_cm_iso157652_tx_message.c_ubyte_Array_4096 object at 0x0000023E534BE940>
```

1.2 Settings

v903 and up have converted over to a new auto generation of `icsnVC40.h`. This enables faster support for newer Intrepid devices and less error prone. With this switch we have moved to using `ics.s_device_settings`.

```
# Old behavior:
device = ics.open_device()
settings = ics.get_device_settings(device)
# settings is a Vcan3Settings type
settings.can1.Baudrate = 1
ics.set_device_settings(device, settings)

# New behavior
device = ics.open_device()
settings = ics.get_device_settings(device)
# settings is a s_device_settings type
settings.vcan3.can1.Baudrate = 1
ics.set_device_settings(device, settings)
```

1.3 PyInstaller

Due to the added complexity underneath when building PyInstaller `hidden_imports.py` should be used now in your spec script:

```
# -*- mode: python ; coding: utf-8 -*-

import ics

block_cipher = None

a = Analysis(['test.py'],
             pathex=['.'],
             binaries=[],
             datas=[],
             hiddenimports=ics.hiddenimports.hidden_imports,
             hookspath=[],
             runtime_hooks=[],
             excludes=[],
             win_no_prefer_redirects=False,
             win_private_assemblies=False,
             cipher=block_cipher,
             noarchive=False)
pyz = PYZ(a.pure, a.zipped_data,
          cipher=block_cipher)
exe = EXE(pyz,
          a.scripts,
          [],
          exclude_binaries=True,
          name='test',
          debug=False,
          bootloader_ignore_signals=False,
          strip=False,
          upx=True,
```

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```
        console=True )
coll = COLLECT(exe,
               a.binaries,
               a.zipfiles,
               a.datas,
               strip=False,
               upx=True,
               upx_exclude=[],
               name='test')
```

Versioning Information

Minor differences can occur between different icsnVC40.h versions. These differences are usually just structures and constant differences. Below is a list of how the python_ics version correlates to the icsnVC40.h version:

2.1 v903

Starting with 903, python_ics module will now match official upstream version releases.

```
pip install 'python_ics>=5.0,<904.0' --force-reinstall
```

Note: Refer to platform specific installation if not on Windows

2.2 Older Versions:

- **v802** `pip install 'python_ics>=2.0,<3.0' --force-reinstall`

Note: Refer to platform specific installation if not on Windows

- **v803** `pip install 'python_ics>=3.0,<4.0' --force-reinstall`

Note: Refer to platform specific installation if not on Windows

- **v900** `pip install 'python_ics>=4.0,<5.0' --force-reinstall`

Note: Refer to platform specific installation if not on Windows

Installation on Windows

PyPi provides binary packages for Windows. You can simply install the `python_ics` module by running the following command:

```
pip install python_ics
```

Note: `pip.exe` is usually located under the `Scripts` directory under the Python installation directory.

3.1 Building from source

Building from source on windows is not usually need so it won't really be covered here in detail. As a starting point you'll need to match the compiler version used to build the official Python binaries (MSVC). If the build environment is setup correctly, you should be able to run `python setup.py build` like usual.

3.2 Intrepid icsneo40 Library

`python_ics` module looks for `icsneo40.dll` in the normal windows DLL search paths. The module will throw an exception if its not found.

`python_ics` does not provide binaries for linux distributions so we will have to compile from source. This can be easily achieved by utilizing Python's PIP. First we need to make sure we have some base packages installed.

4.1 Fedora Dependencies (FC28)

```
sudo dnf install redhat-rpm-config gcc g++ python3-devel clang  
clang-tools-extra
```

4.2 Debian/Ubuntu Dependencies

```
sudo apt install build-essential python-dev clang-format
```

4.3 libicsneo library

The legacy version of libicsneo library (`libicsneolegacy.so`) is required, see the specific repo for details: <https://github.com/intrepidcs/libicsneo>

4.4 Others (Required dependencies)

- GCC
- G++
- Python Development packages (We Need to link to `Python.h`)
- Clang (llvm)
- clang-format

4.5 Installation

After dependencies are installed we can run the following pip command:

```
pip install python_ics
```

Note: A lot of distributions have Python 2 and 3 installed side by side. As of this writing without a version suffix the commands still default to version 2 of the Python binaries. In order to utilize the Python 3 binaries you must append a 3 after the binary names (python3 and pip3 instead of just python and pip).

CHAPTER 5

Getting Started

Please see https://github.com/intrepidcs/python_ics/tree/master/examples for simple examples on how to use this module. Most function documentation has a simple example on how its intended to be used. Every function was designed to be as close as possible to its C counterpart unless it was deemed to make the function more pythonic in nature.

For those experienced with the C API `ics.open_device (icsneoOpenNeoDevice())` behavior has been changed the most (no parameters makes it auto utilize `ics.find_devices (icsneoFindNeoDevices())` and open the first device). Also since python is a object oriented language the module utilizes this and auto cleans up device handles when going out of scope so there is usually no need to call `ics.close_device()`.

Examples can be found at https://github.com/intrepidcs/python_ics/tree/master/examples

For extra information on data structures and underlying functionality, please visit neoVI DLL Documentation under <https://intrepidcs.com/support/support-resources/>

6.1 Opening a device

The `open_device_example.py` example shows how to successfully open and close an Intrepid device.

6.2 Transmitting and Receiving a CAN message

The following examples show how to interact with CAN messages on an Intrepid device.

- `transmit_can_example.py`: Basic example showing how to transmit and receive standard CAN frame
- `transmit_can_xtd_example.py`: Builds off of the CAN example and adds extended Arbitration ID attributes
- `canfd_transmit_example.py`: Bare minimum example on how to transmit over CANFD.

6.3 ISO 15765-2 Example

The `iso15765_example.py` example shows how to setup basic ISO 15765-2 receive filters and transmitting an ISO 15765-2 message.

After opening an Intrepid device `ics.iso15765_enable_networks` should be called to enable ISO 15765-2.

Receive filtering can be established by passing a custom `ics.CmISO157652RxMessage()` to `ics.iso15765_receive_message()`.

Similarly transmitting an ISO 15765-2 frame can be accomplished by passing a custom `ics.CmISO157652TxMessage()` to `ics.iso15765_transmit_message()`.

6.4 Missing an example?

Need an example on something that isn't covered here? Please submit an issue on [github](#) or feel free to send over a Pull Request of your own.

Module Documentation

Python C Code module for interfacing to the icsneo40 dynamic library. Code tries to respect PEP 8 (<http://python.org/dev/peps/pep-0008>). Function naming convention does not follow the tradition c style icsneo40 naming convention as pyics module name acts as the namespace (icsneo portion of the function) and function names are suppose to be lowercase with underscores instead of mixedCase like icsneo API.

C API can be mimiced almost identically by doing the following:

```
>>> import ics as icsneo
>>> devices = icsneo.FindNeoDevices()
>>> for device in devices:
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

Recommended *Python* way by doing the following:

```
>>> import ics
>>> devices = ics.find_devices()
>>> for device in devices:
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

It should be noted that `ics.ics.NeoDevice` is used a little bit differently than the C API. `ics.ics.NeoDevice` contains two extra members: `ics.ics.NeoDevice.AutoHandleClose` and `ics.ics.NeoDevice._Handle`

The handle normally returned from `icsneoOpenNeoDevice()` is stored inside `_Handle` and setting `AutoHandleClose` to `True` (Default) will automatically close the handle when the `ics.ics.NeoDevice` goes out of scope.

Installation:

```
pip install python_ics
```

<https://pypi.python.org/pypi/python-ics>

exception ics.ics.**ArgumentError**

Bases: Exception

exception ics.ics.**RuntimeError**

Bases: Exception

class ics.ics.**NeoDevice**

Bases: object

NeoDevice object

AutoHandleClose

When NeoDevice is freed the handle will automatically be closed, if true.

DeviceType

Handle

IsOpen

This contains the handle returned from icsneoOpenDevice() API. If uncertain, don't use this.

MaxAllowedClients

Name

String describing DeviceType, extension to Python api only.

NumberOfClients

SerialNumber

class ics.ics.**SpyMessage**

Bases: object

SpyMessage object

AckBytes

ArbIDOrHeader

Data

DescriptionID

Not Used

ExtraDataPtr

ExtraDataPtrEnabled

MessagePieceID

Not Used

MiscData

NetworkID

This value is used to identify which network this message was received on.

NetworkID2

This value is used to identify which network this message was received on.

NodeID

Not Used

NumberBytesData

Holds the number of bytes in the Data(1 to 8) array or the number of bytes in a CAN remote frame (The DLC).

NumberBytesHeader

Used for J1850/ISO messages. It indicates how many bytes are stored in the Header(1 to 4) array.

Protocol

Valid values are SPY_PROTOCOL_CAN, SPY_PROTOCOL_J1850VPW, and SPY_PROTOCOL_ISO9141.

StatusBitField**StatusBitField2****StatusBitField3****StatusBitField4****TimeHardware**

Hardware time stamp. The TimeStamp is reset on device open

TimeHardware2

Hardware time stamp. The TimeStamp is reset on device open

TimeStampHardwareID

This is an identifier of what type of hardware timestamp is used. Since neoVI's timestamp is always the same, this doesn't change.

TimeStampSystemID

This is an identifier of what type of system timestamp is used. Since WIN32 neoVI's timestamp is always the same, from the timeGetTime API, this doesn't change.

TimeSystem

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

TimeSystem2

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

noExtraDataPtrCleanup

Tells Python to not clean up ExtraDataPtrMemory, If this is enabled. Ignore, if unsure.

class ics.ics.SpyMessageJ1850

Bases: object

SpyMessageJ1850 object

AckBytes**Data****DescriptionID**

Not Used

ExtraDataPtr**ExtraDataPtrEnabled****Header****MessagePieceID**

Not Used

MiscData**NetworkID**

This value is used to identify which network this message was received on.

NetworkID2

This value is used to identify which network this message was received on.

NodeID

Not Used

NumberBytesData

Holds the number of bytes in the Data(1 to 8) array or the number of bytes in a CAN remote frame (The DLC).

NumberBytesHeader

Used for J1850/ISO messages. It indicates how many bytes are stored in the Header(1 to 4) array.

Protocol

Valid values are SPY_PROTOCOL_CAN, SPY_PROTOCOL_J1850VPW, and SPY_PROTOCOL_ISO9141.

StatusBitField**StatusBitField2****StatusBitField3****StatusBitField4****TimeHardware**

Hardware time stamp. The TimeStamp is reset on device open

TimeHardware2

Hardware time stamp. The TimeStamp is reset on device open

TimeStampHardwareID

This is an identifier of what type of hardware timestamp is used. Since neoVI's timestamp is always the same, this doesn't change.

TimeStampSystemID

This is an identifier of what type of system timestamp is used. Since WIN32 neoVI's timestamp is always the same, from the timeGetTime API, this doesn't change.

TimeSystem

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

TimeSystem2

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

noExtraDataPtrCleanup

Tells Python to not clean up ExtraDataPtrMemory, If this is enabled. Ignore, if unsure.

```
ics.ics.ClosePort()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.close_device()` method.

```
ics.ics.EnableBusVoltageMonitor()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.enable_bus_voltage_monitor()` method.

```
ics.ics.EnableDOIPLine()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.enable_doip_line()` method.

`ics.ics.EnableNetworkCom()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.enable_network_com()` method.

`ics.ics.FindNeoDevices()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.find_devices()` method.

`ics.ics.FirmwareUpdateRequired()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.firmware_update_required()` method.

`ics.ics.ForceFirmwareUpdate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.force_firmware_update()` method.

`ics.ics.GenericAPIGetStatus()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.generic_api_get_status()` method.

`ics.ics.GenericAPIReadData()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.generic_api_read_data()` method.

`ics.ics.GenericAPISendCommand()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.generic_api_send_command()` method.

`ics.ics.GetActiveVNETChannel()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_active_vnet_channel()` method.

`ics.ics.GetBackupPowerEnabled()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_backup_power_enabled()` method.

`ics.ics.GetBackupPowerReady()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_backup_power_ready()` method.

`ics.ics.GetBusVoltage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_bus_voltage()` method.

`ics.ics.GetDLLFirmwareInfo()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_dll_firmware_info()` method.

`ics.ics.GetDLLVersion()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_dll_version()` method.

`ics.ics.GetDeviceSettings()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_device_settings()` method.

`ics.ics.GetDeviceStatus()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_device_status()` method.

`ics.ics.GetErrorMessages()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_error_messages()` method.

`ics.ics.GetHWFirmwareInfo()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_hw_firmware_info()` method.

`ics.ics.GetLastAPIError()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_last_api_error()` method.

`ics.ics.GetMessages()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_messages()` method.

`ics.ics.GetPCBSerialNumber()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_pcb_serial_number()` method.

`ics.ics.GetPerformanceParameters()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_performance_parameters()` method.

`ics.ics.GetRTC()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_rtc()` method.

`ics.ics.GetSerialNumber()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_serial_number()` method.

`ics.ics.GetTimeStampForMsg()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_timestamp_for_msg()`

method.

`ics.ics.ISO15765_DisableNetworks()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_disable_networks()` method.

`ics.ics.ISO15765_EnableNetworks()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_enable_networks()` method.

`ics.ics.ISO15765_ReceiveMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_receive_message()` method.

`ics.ics.ISO15765_TransmitMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_transmit_message()` method.

`ics.ics.IsDeviceFeatureSupported()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.is_device_feature_supported()` method.

`ics.ics.LoadDefaultSettings()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.load_default_settings()` method.

`ics.ics.OpenNeoDevice()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.open_device()` method.

`ics.ics.ReadJupiterFirmware()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.read_jupiter_firmware()` method.

`ics.ics.ReadSDCard()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.read_sdcard()` method.

`ics.ics.RequestDiskDetails()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_disk_details()` method.

`ics.ics.RequestDiskFormat()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.disk_format()` method.

`ics.ics.RequestDiskFormatCancel()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.disk_format_cancel()` method.

`ics.ics.RequestDiskFormatProgress()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_disk_format_progress()` method.

`ics.ics.RequestEnterSleepMode()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.request_enter_sleep_mode()` method.

`ics.ics.ScriptClear()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_clear()` method.

`ics.ics.ScriptGetFBlockStatus()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_get_fblock_status()` method.

`ics.ics.ScriptGetScriptStatus()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_get_status()` method.

`ics.ics.ScriptGetScriptStatusEx()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_script_status()` method.

`ics.ics.ScriptLoad()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_load()` method.

`ics.ics.ScriptReadAppSignal()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_app_signal()` method.

`ics.ics.ScriptReadRxMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_rx_message()` method.

`ics.ics.ScriptReadTxMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_tx_message()` method.

`ics.ics.ScriptStart()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_start()` method.

`ics.ics.ScriptStartFBlock()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_start_fblock()` method.

`ics.ics.ScriptStop()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_stop()` method.

`ics.ics.ScriptStopFBlock()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_stop_fblock()` method.

`ics.ics.ScriptWriteAppSignal()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_app_signal()` method.

`ics.ics.ScriptWriteRxMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_rx_message()` method.

`ics.ics.ScriptWriteTxMessage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_tx_message()` method.

`ics.ics.SetActiveVNETChannel()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_active_vnet_channel()` method.

`ics.ics.SetBackupPowerEnabled()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_backup_power_enabled()` method.

`ics.ics.SetBitRate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_bit_rate()` method.

`ics.ics.SetBitRateEx()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_bit_rate_ex()` method.

`ics.ics.SetContext()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_context()` method.

`ics.ics.SetDeviceSettings()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_device_settings()` method.

`ics.ics.SetFDBitRate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_fd_bit_rate()` method.

`ics.ics.SetLedProperty()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_led_property()` method.

`ics.ics.SetRTC()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_rtc()` method.

`ics.ics.SetReflashDisplayCallback()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_reflash_callback()` method.

`ics.ics.StartDHCPServer()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.start_dhcp_server()` method.

`ics.ics.StopDHCPServer()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.stop_dhcp_server()` method.

`ics.ics.TxMessages()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.transmit_messages()` method.

`ics.ics.UartGetBaudrate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_get_baudrate()` method.

`ics.ics.UartRead()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_read()` method.

`ics.ics.UartSetBaudrate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_set_baudrate()` method.

`ics.ics.UartWrite()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_write()` method.

`ics.ics.ValidateHObject()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.validate_hobject()` method.

`ics.ics.WriteJupiterFirmware()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.write_jupiter_firmware()` method.

`ics.ics.WriteSDCard()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.write_sdcard()` method.

`ics.ics.base36enc(serial)`

Converts a decimal serial number to base36.

Args: serial (int): serial number.

Raises: `ics.ics.RuntimeError`

Returns: Str: Serial Number

```
>>> ics.base36enc(device.SerialNumber)
CY0024
```

`ics.ics.close_device(device)`

Closes the device.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Error Count (int)

```
>>> for device in ics.find_devices():
...     ics.open_device(device)
...     # Do something with the device...
...     ics.close_device(device)
... 
```

Note: `ics.ics.NeoDevice` will automatically close the device when it goes out of scope.

`ics.ics.coremini_clear(device, location)`

Clears the CoreMini into the device.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

location (int): Accepts `ics.ics.SCRIPT_LOCATION_FLASH_MEM`, `ics.ics.SCRIPT_LOCATION_SDCARD`, or `ics.ics.SCRIPT_LOCATION_VCAN3_MEM`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> device = ics.open_device()
>>> ics.coremini_clear(device, ics.SCRIPT_LOCATION_SDCARD)
```

`ics.ics.coremini_get_fblock_status(device, index)`

Gets the status of a Coremini Function Block at *index* on *device*.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

index (int): Index of the function block.

Raises: `ics.ics.RuntimeError`

Returns: None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_get_fblock_status(device, 1)
True
```

ics.ics.coremini_get_status(*device*)

Gets the status of the CoreMini in the device.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: True if running, otherwise False.

```
>>> device = ics.open_device()
>>> ics.coremini_get_status(device)
>>>
```

ics.ics.coremini_load(*device*, *coremini*, *location*)

Loads the CoreMini into the device.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

coremini (str/tuple): Use string to load from file, Use Tuple if file data.

location (int): Accepts *ics.ics.SCRIPT_LOCATION_FLASH_MEM*, *ics.ics.SCRIPT_LOCATION_SDCARD*, or *ics.ics.SCRIPT_LOCATION_VCAN3_MEM*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> device = ics.open_device()
>>> ics.coremini_load(device, 'cmvspy.vs3cmb', ics.SCRIPT_LOCATION_SDCARD)
```

ics.ics.coremini_read_app_signal(*device*, *index*)

Gets the value of a Coremini application signal at *index* on *device*.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

index (int): Index of the application signal.

Raises: *ics.ics.RuntimeError*

Returns: float on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_read_app_signal(device, 1)
52
```

ics.ics.coremini_read_rx_message(*device*, *index*, *j1850=False*)

Gets the value of a Coremini Message at *index* on *device*.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

index (int): Index of the application signal.

j1850 (bool): Use *ics.ics.SpyMessageJ1850* instead.

Raises: *ics.ics.RuntimeError*

Returns: *ics.ics.SpyMessage* Success.

```
>>> device = ics.open_device()
>>> msg = ics.coremini_read_tx_message(device, 0)
```

ics.ics.coremini_read_tx_message (*device*, *index*, *j1850=False*)
Gets the value of a Coremini Message at *index* on *device*.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
index (int): Index of the application signal.
j1850 (bool): Use *ics.ics.SpyMessageJ1850* instead.

Raises: *ics.ics.RuntimeError*

Returns: *ics.ics.SpyMessage* Success.

```
>>> device = ics.open_device()
>>> msg = ics.coremini_read_tx_message(device, 0)
```

ics.ics.coremini_start (*device*, *location*)
Starts the CoreMini into the device.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
location (int): Accepts *ics.ics.SCRIPT_LOCATION_FLASH_MEM*, *ics.ics.SCRIPT_LOCATION_SDCARD*, or *ics.ics.SCRIPT_LOCATION_VCAN3_MEM*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> device = ics.open_device()
>>> ics.coremini_start(device, ics.SCRIPT_LOCATION_SDCARD)
```

ics.ics.coremini_start_fblock (*device*, *index*)
Starts a Coremini Function Block at *index* on *device*.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
index (int): Index of the function block.

Raises: *ics.ics.RuntimeError*

Returns: None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_start_fblock(device, 1)
```

ics.ics.coremini_stop (*device*)
Stops the CoreMini into the device.

Args: *device* (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> device = ics.open_device()
>>> ics.coremini_stop(device)
```

ics.ics.coremini_stop_fblock (*device*, *index*)
Stops a Coremini Function Block at *index* on *device*.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

index (int): Index of the function block.

Raises: *ics.ics.RuntimeError*

Returns: None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_stop_fblock(device, 1)
```

ics.ics.coremini_write_app_signal (*device, index, value*)

Sets the value of a Coremini application signal at *index* on *device*.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

index (int): Index of the application signal.

value (float): New value of the application signal.

Raises: *ics.ics.RuntimeError*

Returns: None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_write_app_signal(device, 1, 52)
>>>
```

ics.ics.coremini_write_rx_message (*device, index, TODO*)

TODO

ics.ics.coremini_write_tx_message (*device, index, msg*)

TODO

ics.ics.create_neovi_radio_message (*Relay1, Relay2, Relay3, Relay4, Relay5, LED6, LED5, MSB_report_rate, LSB_report_rate, analog_change_report_rate, relay_timeout*)

Python API only. Generates data bytes for use with neoVI RADIO CAN Messages

Kwargs: Relay1 (boolean): Enable/Disable Relay1

Relay2 (boolean): Enable/Disable Relay2

Relay3 (boolean): Enable/Disable Relay3

Relay4 (boolean): Enable/Disable Relay4

Relay5 (boolean): Enable/Disable Relay5

LED5 (boolean): Enable/Disable LED5

LED6 (boolean): Enable/Disable LED6

MSB_report_rate (int): MSB Report Rate in ms (0-255)

LSB_report_rate (int): LSB Report Rate in ms (0-255)

analog_change_report_rate (int): Analog change report rate

relay_timeout (int): Relay Timeout (0-255)*255ms

Returns:

Tuple of data bytes for use with *ics.ics.SpyMessage*

Raises: *ics.ics.RuntimeError*

```
>>> msg = ics.SpyMessage()
>>> msg.Data = ics.create_neovi_radio_message(Relay1=True, Relay4=False,
↳ LED6=True, MSB_report_rate=10)
>>> msg.Data
(65, 10, 0, 0, 0)
```

ics.ics.disk_format (*device*)

Starts disk formatting on the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> details = ics.get_disk_details(d)
>>> details. = ics.get_disk_details(d)
>>> ics.disk_format(d, details)
>>>
```

ics.ics.disk_format_cancel (*device*)

Cancel in progress disk formatting on the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> ics.disk_format(d, details)
>>> ics.disk_format_cancel(d)
>>>
```

ics.ics.enable_bus_voltage_monitor (*device, enable, reserved*)

Enable or disable bus voltage monitoring.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

enable (bool): int

reserved (int): int: Optional. Should be set to zero. Don't set, if unsure.

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.enable_bus_voltage_monitor(d, 1)
>>>
```

ics.ics.enable_doip_line (*device, enable*)

Activate or De-activate DOIP Line.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

enable (bool): bool

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.enable_doip_line(d, True)
>>>
```

`ics.ics.enable_network_com(device, enable, net_id)`

Enable or disable network communication.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

enable (bool): bool

net_id (int): int: Optional. If left blank, disables/enables all networks.

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.enable_network_com(d, True)
>>>
```

`ics.ics.find_devices(device_type=ics.ics.NEODEVICE_ALL)`

Finds all connected devices and returns a tuple of `ics.ics.NeoDevice` for use in `ics.ics.open_device()`

Args: device_type (int): Accepts `ics.ics.NEODEVICE_*` Macros

New in 3.0 (803):

device_types (List/Tuple): Accepts a Container of `ics.ics.NEODEVICE_*` Macros

network_id (int): OptionsFindNeoEx.CANOptions.iNetworkID. Usually `ics.NETID_CAN`, if needed

Raises: `ics.ics.RuntimeError`

Returns: Tuple of `ics.ics.NeoDevice` for use in `ics.ics.open_device()`

```
>>> for device in ics.find_devices():
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

New in 3.0 (803):

```
>>> for device in ics.find_devices([ics.NEODEVICE_FIRE, ics.NEODEVICE_VCAN3]):
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

`ics.ics.firmware_update_required(device)`

Determines if the device firmware needs flashing.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True on success, False on failure.

```
>>> ics.force_firmware_update(device)
True
```

`ics.ics.force_firmware_update(device)`

Forces the device to flash firmware.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Boolean: True on success, False on failure.

```
>>> ics.force_firmware_update(device)
True
```

`ics.ics.generic_api_get_status(device, api_index, instance_index)`

Reads data in a generic way.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

api_index (int): api_index.

instance_index (int): instance_index.

Raises: *ics.ics.RuntimeError*

Returns: tuple of (int): (functionIndex, callbackError, finishedProcessing)

`ics.ics.generic_api_read_data()`

`ics.ics.generic_api_send_command(device, api_index, instance_index, length)`

Reads data in a generic way.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

api_index (int): api_index.

instance_index (int): instance_index.

function_index (int): function_index.

length (int): Length of the data to read.

Raises: *ics.ics.RuntimeError*

Returns: tuple of (functionError, data)

`ics.ics.generic_api_send_command(device, api_index, instance_index, function_index, data)`

Sends a command in a generic way.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

api_index (int): api_index.

instance_index (int): instance_index.

function_index (int): function_index.

data (bytes): Data to be passed in.

Raises: *ics.ics.RuntimeError*

Returns: functionError (int): functionError.

`ics.ics.get_active_vnet_channel(device)`

Gets active vnet channel for the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Int: Returns active vnet channel.

ics.ics.get_backup_power_enabled(device)
Returns the device backup power enabled for the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Boolean: True on success, False on failure.

ics.ics.get_backup_power_ready(device)
Returns the device backup power is ready for the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Boolean: True on success, False on failure.

ics.ics.get_bus_voltage(device, reserved)
Reads bus voltage. (*ics.ics.enable_bus_voltage_monitor*) needs to be called first.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

reserved (int): int: Optional. Should be set to zero. Don't set, if unsure.

Raises: *ics.ics.RuntimeError*

Returns: Int: value returned is in mV.

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.enable_bus_voltage_monitor(d, 1)
>>> ics.get_bus_voltage(d)
12000
>>>
```

ics.ics.get_device_settings(device, device_type, vnet_slot)
Gets the settings in the device. vnet_slot defaults to *ics.ics.PlasmaIonVnetChannelMain*

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

device_type (EDeviceSettingsType): Optional: Overrides default device settings type. Defaults to '-1'

vnet_slot (PlasmaIonVnetChannelMain): Optional: Defaults to PlasmaIonVnetChannelMain, Used only for PLASMA/ION Devices.

Raises: *ics.ics.RuntimeError*

Returns: *ics.ics.device_settings*

```
>>> d = ics.open_device()
>>> d.Name
'neoVI ION'
>>> d.SerialNumber
404444
>>> s = ics.get_device_settings(d)
>>> s.DeviceSettingType
2
>>> s.cyan
```

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```
<ics.CyanSettings object at 0x01E61B40>
>>> s.cyan.canfd1.FDMode
4
>>> s2.cyan
<ics.CyanSettings object at 0x02B113C8>
>>> s2 = ics.get_device_settings(d, -1, ics.PlasmaIonVnetChannelA)
>>> s2.DeviceSettingType
2
>>> s2.cyan.canfd1.FDMode
4
```

ics.ics.get_device_status (*device*)

Returns the device status.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (ics.ics.ics_device_status).

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.get_device_status(d)
>>> status.fire2Status.ethernetActivationLineEnabled
0
```

ics.ics.get_disk_details (*device*)

Returns the device disk details.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (ics.ics.srad_gigalog_disk_details).

```
>>> import ics
>>> d = ics.open_device()
>>> details = ics.get_disk_details(d)
>>> details.structure.options
>>>
```

ics.ics.get_disk_format_progress (*device*)

Returns the device disk formatting progress.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (ics.ics.srad_gigalog_disk_format_progress).

```
>>> import ics
>>> d = ics.open_device()
>>> d = ics.disk_format(d, details)
>>> progress = ics.get_disk_format_progress(d)
>>> progress.sectorsRemaining
>>>
```

ics.ics.get_dll_firmware_info (*device*)

Returns the DLL firmware info for the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (*ics.ics.st_api_firmware_info*)

```
>>> device = ics.open_device()
>>> info = ics.get_dll_firmware_info(device)
>>> info.iAppMajor
7
>>> info.iAppMinor
55
>>>
```

ics.ics.get_dll_version (device)

Gets the DLL version.

Args: None

Raises: *ics.ics.RuntimeError*

Returns: Int: DLL Version

```
>>> ics.get_dll_version()
700
```

ics.ics.get_error_messages (device[, j1850, timeout])

Gets the error message(s) on the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: list of tuple`s. :class:`tuple` contents: (error_number, description_short, description_long, severity, restart_needed)

```
>>> device = ics.open_device()
>>> errors = ics.get_error_messages(device)
```

ics.ics.get_hw_firmware_info (device)

Returns the device firmware info for the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (*ics.ics.st_api_firmware_info*)

```
>>> device = ics.open_device()
>>> info = ics.get_hw_firmware_info(device)
>>> info.iAppMajor
7
>>> info.iAppMinor
55
>>>
```

ics.ics.get_last_api_error (device)

Gets the error message from the last API call.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Tuple: (error, description short, description long, severity, restart needed)

```
>>> device = ics.open_device()
>>> try:
...     msg = ics.coremini_read_tx_message(device, 0)
... except ics.RuntimeError as ex:
...     print(ex)
...     print(ics.get_last_api_error(device))
...
Error: coremini_read_tx_message(): icsneoScriptReadTxMessage() Failed
(224, 'Invalid Message Index for script.', 'Invalid Message Index for script.
→', 16, 0)
```

`ics.ics.get_library_path()`

`ics.ics.get_messages(device[, j1850, timeout])`

Gets the message(s) on the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

j1850 (bool): Return *ics.ics.SpyMessageJ1850* instead.

timeout (float): Optional timeout to wait for messages in seconds (0.1 = 100ms).

Raises: *ics.ics.RuntimeError*

Returns: tuple of two items. First item is a tuple of *ics.ics.SpyMessage* and second is the error count.

```
>>> device = ics.open_device()
>>> messages, errors = ics.get_messages(device)
>>> len(messages)
14
>>> hex(messages[0].ArbIDOrHeader)
'0x160'
>>> messages[0].Data
(36, 11, 11, 177, 37, 3, 11, 199)
>>> errors
0
```

`ics.ics.get_pcb_serial_number(device)`

Gets the unique PCB serial number of the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: (str): PCB Serial Number

```
>>> import ics
>>> d = ics.open_device()
>>> pcb_sn = ics.get_pcb_serial_number(d)
>>>
```

`ics.ics.get_performance_parameters(device)`

Gets the Performance Parameters on *device*.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Tuple on Success: (buffer count, buffer max, overflow count, reserved, reserved, reserved, reserved, reserved)

```
>>> device = ics.open_device()
>>> ics.get_performance_parameters(device)
(0, 24576, 0, 0, 0, 0, 0, 0)
```

`ics.ics.get_rtc(device)`

Gets the Real-Time Clock of the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Tuple: (datetime.datetime object, offset in seconds)

```
>>> device = ics.open_device()
>>> ics.get_rtc(device)
(datetime.datetime(2014, 9, 10, 17, 45, 45), 3)
```

`ics.ics.get_script_status()`

Accepts a *ics.ics.NeoDevice*, exception on error. Returns a list of values of what ulParameters would hold

`ics.ics.get_serial_number(device)`

Gets the serial number out of the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: Int: Serial Number Version

```
>>> ics.get_serial_number(device)
53123
```

`ics.ics.get_timestamp_for_msg(device, msg)`

Calculates the timestamp for a message.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

msg (*ics.ics.SpyMessage*): *ics.ics.SpyMessage*

Raises: *ics.ics.RuntimeError*

Returns: Float: Timestamp for the message.

```
>>> import ics
>>> d = ics.open_device()
>>> msgs, error_count = ics.get_messages(d)
>>> ics.get_timestamp_for_msg(d, msgs[0])
354577568.9145524
```

`ics.ics.icsneoClosePort()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.close_device()* method.

`ics.ics.icsneoEnableBusVoltageMonitor()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.enable_bus_voltage_monitor()* method.

`ics.ics.icsneoEnableDOIPLine()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.enable_doip_line()* method.

`ics.ics.icsneoEnableNetworkCom()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.enable_network_com()* method.

`ics.ics.icsneoFindNeoDevices()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.find_devices()* method.

`ics.ics.icsneoFirmwareUpdateRequired()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.firmware_update_required()* method.

`ics.ics.icsneoForceFirmwareUpdate()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.force_firmware_update()* method.

`ics.ics.icsneoGenericAPIGetStatus()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.generic_api_get_status()* method.

`ics.ics.icsneoGenericAPIReadData()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.generic_api_read_data()* method.

`ics.ics.icsneoGenericAPISendCommand()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.generic_api_send_command()` method.

`ics.ics.icsneoGetActiveVNETChannel()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_active_vnet_channel()` method.

`ics.ics.icsneoGetBackupPowerEnabled()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_backup_power_enabled()` method.

`ics.ics.icsneoGetBackupPowerReady()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_backup_power_ready()` method.

`ics.ics.icsneoGetBusVoltage()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_bus_voltage()` method.

`ics.ics.icsneoGetDLLFirmwareInfo()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_dll_firmware_info()` method.

`ics.ics.icsneoGetDLLVersion()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_dll_version()` method.

`ics.ics.icsneoGetDeviceSettings()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_device_settings()` method.

`ics.ics.icsneoGetDeviceStatus()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_device_status()* method.

`ics.ics.icsneoGetErrorMessages()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_error_messages()* method.

`ics.ics.icsneoGetHWFirmwareInfo()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_hw_firmware_info()* method.

`ics.ics.icsneoGetLastAPIError()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_last_api_error()* method.

`ics.ics.icsneoGetMessages()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_messages()* method.

`ics.ics.icsneoGetPCBSerialNumber()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_pcb_serial_number()* method.

`ics.ics.icsneoGetPerformanceParameters()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_performance_parameters()* method.

`ics.ics.icsneoGetRTC()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_rtc()* method.

`ics.ics.icsneoGetSerialNumber()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_serial_number()* method.

```
ics.ics.icsneoGetTimeStampForMsg()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_timestamp_for_msg()* method.

```
ics.ics.icsneoISO15765_DisableNetworks()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.iso15765_disable_networks()* method.

```
ics.ics.icsneoISO15765_EnableNetworks()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.iso15765_enable_networks()* method.

```
ics.ics.icsneoISO15765_ReceiveMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.iso15765_receive_message()* method.

```
ics.ics.icsneoISO15765_TransmitMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.iso15765_transmit_message()* method.

```
ics.ics.icsneoIsDeviceFeatureSupported()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.is_device_feature_supported()* method.

```
ics.ics.icsneoLoadDefaultSettings()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.load_default_settings()* method.

```
ics.ics.icsneoOpenNeoDevice()
```

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.open_device()* method.

`ics.ics.icsneoReadJupiterFirmware()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.read_jupiter_firmware()* method.

`ics.ics.icsneoReadSDCard()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.read_sdcard()* method.

`ics.ics.icsneoRequestDiskDetails()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_disk_details()* method.

`ics.ics.icsneoRequestDiskFormat()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.disk_format()* method.

`ics.ics.icsneoRequestDiskFormatCancel()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.disk_format_cancel()* method.

`ics.ics.icsneoRequestDiskFormatProgress()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.get_disk_format_progress()* method.

`ics.ics.icsneoRequestEnterSleepMode()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.request_enter_sleep_mode()* method.

`ics.ics.icsneoScriptClear()`

Note: Compatibility Function: Identical to PEP8 compliant *ics.ics.coremini_clear()* method.

```
ics.ics.icsneoScriptGetFBlockStatus()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_get_fblock_status()` method.

```
ics.ics.icsneoScriptGetScriptStatus()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_get_status()` method.

```
ics.ics.icsneoScriptGetScriptStatusEx()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.get_script_status()` method.

```
ics.ics.icsneoScriptLoad()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_load()` method.

```
ics.ics.icsneoScriptReadAppSignal()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_app_signal()` method.

```
ics.ics.icsneoScriptReadRxMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_rx_message()` method.

```
ics.ics.icsneoScriptReadTxMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_read_tx_message()` method.

```
ics.ics.icsneoScriptStart()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_start()` method.

```
ics.ics.icsneoScriptStartFBlock()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_start_fblock()` method.

```
ics.ics.icsneoScriptStop()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_stop()` method.

```
ics.ics.icsneoScriptStopFBlock()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_stop_fblock()` method.

```
ics.ics.icsneoScriptWriteAppSignal()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_app_signal()` method.

```
ics.ics.icsneoScriptWriteRxMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_rx_message()` method.

```
ics.ics.icsneoScriptWriteTxMessage()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.coremini_write_tx_message()` method.

```
ics.ics.icsneoSetActiveVNETChannel()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_active_vnet_channel()` method.

```
ics.ics.icsneoSetBackupPowerEnabled()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_backup_power_enabled()`

method.

`ics.ics.icsneoSetBitRate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_bit_rate()` method.

`ics.ics.icsneoSetBitRateEx()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_bit_rate_ex()` method.

`ics.ics.icsneoSetContext()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_context()` method.

`ics.ics.icsneoSetDeviceSettings()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_device_settings()` method.

`ics.ics.icsneoSetFDBitRate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_fd_bit_rate()` method.

`ics.ics.icsneoSetLedProperty()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_led_property()` method.

`ics.ics.icsneoSetRTC()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_rtc()` method.

`ics.ics.icsneoSetReflashDisplayCallbacks()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.set_reflash_callback()` method.

`ics.ics.icsneoStartDHCPServer()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.start_dhcp_server()` method.

`ics.ics.icsneoStopDHCPServer()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.stop_dhcp_server()` method.

`ics.ics.icsneoTxMessages()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.transmit_messages()` method.

`ics.ics.icsneoUartGetBaudrate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_get_baudrate()` method.

`ics.ics.icsneoUartRead()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_read()` method.

`ics.ics.icsneoUartSetBaudrate()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_set_baudrate()` method.

`ics.ics.icsneoUartWrite()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.uart_write()` method.

`ics.ics.icsneoValidateHObject()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.validate_hobject()` method.

`ics.ics.icsneoWriteJupiterFirmware()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.write_jupiter_firmware()`

method.

`ics.ics.icsneoWriteSDCard()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.write_sdcard()` method.

`ics.ics.icsneowBMSManagerReset()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.wbms_manager_reset()` method.

`ics.ics.icsneowBMSManagerWriteLock()`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.wbms_manager_write_lock()` method.

`ics.ics.is_device_feature_supported(device, feature)`

Polls firmware in device to see if the feature is supported. As of 908 only ValueCAN4-2EL, ValueCAN4-4 and ValueCAN4-Industrial are supported.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

enable (DeviceFeature): DeviceFeature

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.device_feature import DeviceFeature
>>> d = ics.open_device()
>>> supported = ics.is_device_feature_supported(d, DeviceFeature.
↪networkTerminationDWCAN01)
>>>
```

`ics.ics.iso15765_disable_networks(device)`

Disables ISO15765 networks.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: None

`ics.ics.iso15765_enable_networks(device, networks)`

Enables ISO15765 networks.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: None

`ics.ics.iso15765_receive_message(device, netid, rx_msg)`

Setup rx ISO15765 Message.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

prx_msg (ics.ics.st_cm_iso157652_rx_message): ics.ics.
st_cm_iso157652_rx_message

Raises: *ics.ics.RuntimeError*

Returns: Boolean: True on success, False on failure.

ics.ics.iso15765_transmit_message (device, ulNetworkID, pMsg, ulBlockingTimeout)
Transmits an ISO15765 Message.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

pMsg (ics.ics.st_cm_iso157652_tx_message): ics.ics.
st_cm_iso157652_tx_message

Raises: *ics.ics.RuntimeError*

Returns: Boolean: True on success, False on failure.

ics.ics.load_default_settings (device)
Load the default settings in the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> device = ics.open_device()
>>> ics.load_default_settings(device)
>>>
```

ics.ics.open_device (device)

Opens the device. *device* can be omitted to return a *ics.ics.NeoDevice* of the first free available device, a *ics.ics.NeoDevice*, or a serial number of the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

device (int): Serial Number of the device

network_ids (List/Tuple): This is an array of number IDs which specify the NetworkID parameter of each network. This allows you to assign a custom network ID to each network. Normally, you will assign consecutive IDs to each of the networks. See NetworkIDList for a list of current network ID's. You may also set this parameter to NULL (zero) and the default network ID's will be used.

config_read (int): Specifies whether the DLL should read the neoVI's device configuration before enabling the device. It is recommended that this value be set to 1.

options (int): DEVICE_OPTION_* defines

network_id (int): OptionsFindNeoEx.CANOptions.iNetworkID. Usually ics.NETID_CAN, if needed

use_server (int): Defaults to False, Setting to True allows opening the same device more than once.

Raises: *ics.ics.RuntimeError*

Returns: If *ics.ics.NeoDevice* is passed as a parameter, None. If serial number is passed as a parameter, a *ics.ics.NeoDevice* will be returned. If *device* parameter is omitted, a *ics.ics.NeoDevice* will be returned with the first available free device.

```
>>> for device in ics.find_devices():
...     ics.open_device(device)
... 
```

Note: `ics.ics.NeoDevice` will automatically close the device when it goes out of scope.

`ics.ics.override_library_name(new_name)`

Overrides the default search for loading the icsneo40 library

Args: name: Absolute path or relative path including filename.

Raises: `ics.ics.RuntimeError`

Returns: None

```
>>> import ics
>>> ics.find_devices()
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
ics.RuntimeError: Error: find_devices(): Failed to open library: 'icsneo40.dll
↪' with error code: #126
>>> ics.override_library_name(r"C:\Windows\SysWOW64\icsneo40-different.dll")
>>> ics.find_devices()
(<ics.NeoDevice object at 0x00284C50>, <ics.NeoDevice object at 0x007C9A10>)
```

`ics.ics.read_jupiter_firmware(device, size[, vnetChannel])`

Reads firmware binary from a RAD-Jupiter. If not sure, don't use this method

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

size (int): int: size of the bytes to read of the firmware binary.

vnetChannel (int): int: Optional. Don't set, if unsure.

Raises: `ics.ics.RuntimeError`

Returns: None

`ics.ics.read_sdcard()`

icsneoReadSDCard(), Accepts a `ics.ics.NeoDevice` and sector index. Returns a bytearray of 512 bytes max. Exception on error.

`ics.ics.request_enter_sleep_mode(device, timeout_ms, mode, reserved_zero)`

Signal neoVI to immediate go to sleep. Currently only supported by FIREVNET/PLASMA. If using over USB this will likely return true but never cause PLASMA to sleep since USB insertion keeps it alive. This API allows Android/Linux applications to invoke power management.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

timeout_ms (int): 16bit word for how long to wait on idle bus before going to sleep. If caller does not want to change it pass in 65535 (0xFFFF) and it will stay whatever it was set to in explorer/coremini.

mode (int): 16bit word for power mode to enter. If caller does not want to change it pass in 65535 (0xFFFF) and it will stay whatever it was set to in explorer/coremini. If it is zero then neoVI will do 'normal sleep'. 0 - power mode off but calling this function will do 'normal sleep'. 1 - normal sleep. 2 - instant sleep. 3 - comatose sleep.

reserved_zero (int): Reserved, Keep as zero.

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True on success, False on failure.

```
>>> ics.request_enter_sleep_mode(device, 1, 0)
True
```

`ics.ics.set_active_vnet_channel(device, channel)`

Sets active vnet channel for the device.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True on success, False on failure.

`ics.ics.set_backup_power_enabled(device, enable)`

Sets the device backup power enabled for the device.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True on success, False on failure.

`ics.ics.set_bit_rate(device, BitRate, NetworkID)`

Specifies bit rate setting. Valid values depend on the network specified.

For the networks NETID_HSCAN, NETID_MSCAN, NETID_SWCAN, NETID_FIRE_HSCAN2, NETID_HSCAN3, NETID_LSFTCAN, valid bit rates are 2000, 33333, 50000, 62500, 83333, 100000, 125000, 250000, 500000, 800000, 1000000

For the networks NETID_LIN, NETID_ISO2, NETID_FIRE_LIN2, NETID_FIRE_LIN3, NETID_FIRE_LIN4, valid bit rates are

For the network NETID_FIRE_CGI valid bit rates are 625000 and 115200

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Int: None.

`ics.ics.set_bit_rate_ex(device, BitRate, NetworkID, iOptions)`

Sets the bitrate for a given Network ID on the device with extended options.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Int: None.

`ics.ics.set_context(device)`

Sets the “context” of how `icsneoFindNeoDevices(Ex)` and `icsneoOpenNeoDevice(Ex)` function. If the context is 0 (null) than `icsneoFindNeoDevices(Ex)` will be system wide, searching USB and other supported computer interfaces. `icsneoFindNeoDevices` can then be used to connect to devices found in this manner. If the context is a handle to connected CAN tool than `icsneoFindNeoDevices(Ex)` will search a specific CAN bus for supported IntrepidCS CAN Nodes. Again `icsneoOpenNeoDevice(Ex)` would be used create logical connections to found CAN Nodes.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True on success, False on failure.

```
>>> ics.set_context(device)
True
```

`ics.ics.set_device_settings(device, settings, save_to_eeprom, vnet_slot)`

Sets the settings in the device. vnet_slot defaults to `ics.ics.PlasmaIonVnetChannelMain`

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
 settings (*ics.ics.device_settings*): *ics.ics.device_settings*
Raises: *ics.ics.RuntimeError*
Returns: None.

```
>>> d = ics.open_device()
>>> d.Name
'neoVI ION'
>>> d.SerialNumber
404444
>>> s = ics.get_device_settings(d, ics.PlasmaIonVnetChannelA) # Get Slave_
↳ settings, channel selection not needed if not a Plasma/Ion
>>> s.DeviceSettingType
2
>>> s.cyan.can_switch_mode
1
>>> s.cyan.can_switch_mode = 2
>>> ics.set_device_settings(d, s, True, ics.PlasmaIonVnetChannelA)
>>>
```

ics.ics.set_fd_bit_rate (*device, BitRate, NetworkID*)
 Sets the FD bitrate for a given Network ID on the device..

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
Raises: *ics.ics.RuntimeError*
Returns: Int: None.

ics.ics.set_led_property (*device, led, prop, value*)
 Sets the LED property on the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*
 led (int): Index or position of the LED
 prop (int): Property of the LED
 value (int): Value of the LED Property

Raises: *ics.ics.RuntimeError*
Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> ics.set_led_property(d, TODO, TODO, TODO)
>>>
```

ics.ics.set_reflash_callback (*callback*)
 Sets the reflash display callback.

Args: callback (function): Must be a callable Python function (*def callback(msg, progress)*)
Raises: *ics.ics.RuntimeError*
Returns: None.

```
>>> def callback(msg, progress):
...     print(msg, progress)
```

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```
...
>>> ics.set_reflash_callback(callback)
>>>
```

`ics.ics.set_rtc(device[, time])`

Sets the Real-Time Clock of the device.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

time (datetime.datetime): Optional. Sets to current time, if omitted.

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> device = ics.open_device()
>>> ics.set_rtc(device)
```

`ics.ics.start_dhcp_server(device, network_id, device_ip_address, subnet_mask, gateway, start_address, end_address, overwrite_dhcp_settings, lease_time, reserved)`

Starts a DHCP Server.

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

network_id (int): NetworkID

device_ip_address (str): Device IP Address

subnet_mask (str): Subnet Mask

gateway (str): Gateway

start_address (str): Start Address

end_address (str): End Address

overwrite_dhcp_settings (bool): Overwrite DHCP Settings

lease_time (int): Lease time

reserved (int): (Optional) Reserved, set to 0

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> ics.start_dhcp_server(d, TODO)
>>>
```

`ics.ics.stop_dhcp_server(device, network_id)`

Stops the DHCP Server

Args: device (*ics.ics.NeoDevice*): *ics.ics.NeoDevice*

network_id (int): NetworkID

Raises: *ics.ics.RuntimeError*

Returns: None.

```
>>> import ics
>>> d = ics.open_device()
>>> ics.stop_dhcp_server(d, TODO)
>>>
```

`ics.ics.transmit_messages(device, messages)`

Transmits message(s) on the device. *messages* can be a tuple of `ics.ics.SpyMessage`

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

messages (`ics.ics.SpyMessage`): `ics.ics.SpyMessage`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> device = ics.open_device()
>>> msg = ics.SpyMessage()
>>> msg.ArbIDOrHeader = 0xFF
>>> msg.NetworkID = ics.NETID_HSCAN
>>> msg.Data = (0,1,2,3,4,5,6,7)
>>> ics.transmit_messages(device, msg)
>>>
```

`ics.ics.uart_get_baudrate(device, port)`

Gets the UART baudrate on the given port.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

port (`ics.ics.structures.e_uart_port_t.e_uart_port_t`): `ics.ics.structures.e_uart_port_t.e_uart_port_t`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.e_uart_port_t import e_uart_port_t
>>> d = ics.open_device()
>>> baudrate = ics.uart_set_baudrate(d, e_uart_port_t.eUART0)
>>>
```

`ics.ics.uart_read(device, port, bytes_to_read, flags)`

Reads UART on the given port.

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

port (`ics.ics.structures.e_uart_port_t.e_uart_port_t`): `ics.ics.structures.e_uart_port_t.e_uart_port_t`

bytes_to_read (int): Optional. How many bytes to read from the UART, 256 if omitted.

flags (int): Optional. Flags to be used. Don't use if unsure.

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.e_uart_port_t import e_uart_port_t
>>> d = ics.open_device()
>>> data = ics.uart_read(d, e_uart_port_t.eUART0)
```

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```
>>> print(f"Read {len(data)} bytes: {data}")
>>>
```

`ics.ics.uart_set_baudrate` (*device*, *port*, *baudrate*)

Sets the UART baudrate on the given port.

Args: *device* (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

port (`ics.ics.structures.e_uart_port_t.e_uart_port_t`): `ics.ics.structures.e_uart_port_t.e_uart_port_t`

baudrate (`int`): Baudrate of the UART to set.

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.e_uart_port_t import e_uart_port_t
>>> d = ics.open_device()
>>> ics.uart_set_baudrate(d, e_uart_port_t.eUART0, 115200)
>>> print(f"Read {len(data)} bytes: {data}")
>>>
```

`ics.ics.uart_write` (*device*, *port*, *data*, *flags*)

Writes UART on the given port

Args: *device* (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

port (`ics.ics.structures.e_uart_port_t.e_uart_port_t`): `ics.ics.structures.e_uart_port_t.e_uart_port_t`

data (`:class:'bytes'`): `:class:'bytes'`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.e_uart_port_t import e_uart_port_t
>>> d = ics.open_device()
>>> ics.uart_write(d, e_uart_port_t.eUART0, b'my uart data goes here')
>>>
```

`ics.ics.validate_hobject` (*device*)

Validates the handle is valid for a *device*. Handles are only valid when the device is open.

Args: *device* (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

or:

device (`int`): c style integer handle to the device.

Raises: `ics.ics.RuntimeError`

Returns: Boolean: True if valid, false otherwise.

```
>>> device = ics.open_device()
>>> ics.validate_hobject(device)
1
>>> ics.validate_hobject(device._Handle)
1
```

```
ics.ics.wBMSManagerReset()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.wbms_manager_reset()` method.

```
ics.ics.wBMSManagerWriteLock()
```

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.wbms_manager_write_lock()` method.

```
ics.ics.wbms_manager_reset(device, manager)
```

Resets the manager

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

manager (`ics.ics.structures.ew_bms_manager_port_t.ew_bms_manager_port_t`):
`ics.ics.structures.ew_bms_manager_port_t.ew_bms_manager_port_t`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.ew_bms_manager_port_t import ew_bms_manager_port_t
>>> d = ics.open_device()
>>> ics.wbms_manager_reset(d, ew_bms_manager_port_t.eManagerPortA.value)
>>>
```

```
ics.ics.wbms_manager_write_lock(device, manager, lock_state)
```

Sets the lock state on the manager

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

manager (`ics.ics.structures.ew_bms_manager_port_t.ew_bms_manager_port_t`):
`ics.ics.structures.ew_bms_manager_port_t.ew_bms_manager_port_t`

lock_state (`ics.ics.structures.ew_bms_manager_lock_state_t.ew_bms_manager_lock_state_t`):
`ics.ics.structures.ew_bms_manager_lock_state_t.ew_bms_manager_lock_state_t`

Raises: `ics.ics.RuntimeError`

Returns: None.

```
>>> import ics
>>> from ics.structures.ew_bms_manager_port_t import ew_bms_manager_port_t
>>> from ics.structures.ew_bms_manager_lock_state_t import ew_bms_manager_
↳lock_state_t
>>> d = ics.open_device()
>>> ics.wbms_manager_write_lock(d, ew_bms_manager_port_t.eManagerPortA.value,
↳ew_bms_manager_lock_state_t.eLockManager.value)
>>>
```

```
ics.ics.write_jupiter_firmware(device, bytes[, vnetChannel])
```

Writes firmware binary to a RAD-Jupiter. If not sure, don't use this method

Args: device (`ics.ics.NeoDevice`): `ics.ics.NeoDevice`

bytes (bytes): bytes: bytes of the firmware binary.

vnetChannel (int): int: Optional. Don't set, if unsure.

Raises: *ics.ics.RuntimeError*

Returns: None

`ics.ics.write_sdcard()`

`icsneoReadSDCard()`, Accepts a `ics.ics.NeoDevice`, sector index, and a bytearray of 512 bytes. Exception on error.

CHAPTER 8

Module Functions

`ics.ISO15765_DisableNetworks`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_disable_networks()` method.

`ics.ISO15765_EnableNetworks`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_enable_networks()` method.

`ics.ISO15765_ReceiveMessage`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_receive_message()` method.

`ics.ISO15765_TransmitMessage`

Note: Compatibility Function: Identical to PEP8 compliant `ics.ics.iso15765_transmit_message()` method.

`ics.close_device(device)`

Closes the device.

`ics.coremini_clear(device, location)`

Clears the CoreMini into the device.

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<code>ics.coremini_get_fblock_status(device, index)</code>	Gets the status of a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_get_status(device)</code>	Gets the status of the CoreMini in the device.
<code>ics.coremini_load(device, coremini, location)</code>	Loads the CoreMini into the device.
<code>ics.coremini_read_app_signal(device, index)</code>	Gets the value of a Coremini application signal at <i>index</i> on <i>device</i> .
<code>ics.coremini_read_rx_message(device, index)</code>	Gets the value of a Coremini Message at <i>index</i> on <i>device</i> .
<code>ics.coremini_read_tx_message(device, index)</code>	Gets the value of a Coremini Message at <i>index</i> on <i>device</i> .
<code>ics.coremini_start(device, location)</code>	Starts the CoreMini into the device.
<code>ics.coremini_start_fblock(device, index)</code>	Starts a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_stop(device)</code>	Stops the CoreMini into the device.
<code>ics.coremini_stop_fblock(device, index)</code>	Stops a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_write_app_signal(device, index, ...)</code>	Sets the value of a Coremini application signal at <i>index</i> on <i>device</i> .
<code>ics.coremini_write_rx_message(device, index, ...)</code>	TODO
<code>ics.coremini_write_tx_message(device, index, msg)</code>	TODO
<code>ics.create_neovi_radio_message(Relay1, ...)</code>	Python API only.
<code>ics.disk_format(device)</code>	Starts disk formatting on the device.
<code>ics.disk_format_cancel(device)</code>	Cancel in progress disk formatting on the device.
<code>ics.enable_bus_voltage_monitor(device, ...)</code>	Enable or disable bus voltage monitoring.
<code>ics.enable_doip_line(device, enable)</code>	Activate or De-activate DOIP Line.
<code>ics.enable_network_com(device, enable, net_id)</code>	Enable or disable network communication.
<code>ics.find_devices([device_type])</code>	Finds all connected devices and returns a tuple of <code>ics.ics.NeoDevice</code> for use in <code>ics.ics.open_device()</code>
<code>ics.firmware_update_required(device)</code>	Determines if the device firmware needs flashing.
<code>ics.force_firmware_update(device)</code>	Forces the device to flash firmware.
<code>ics.generic_api_get_status(device, ...)</code>	Reads data in a generic way.
<code>ics.generic_api_read_data</code>	<code>ics.ics.generic_api_send_command(device, api_index, instance_index, length)</code>
<code>ics.generic_api_send_command(device, ...)</code>	Sends a command in a generic way.
<code>ics.get_active_vnet_channel(device)</code>	Gets active vnet channel for the device.
<code>ics.get_backup_power_enabled(device)</code>	Returns the device backup power enabled for the device.
<code>ics.get_backup_power_ready(device)</code>	Returns the device backup power is ready for the device.
<code>ics.get_bus_voltage(device, reserved)</code>	Reads bus voltage.
<code>ics.get_device_settings(device, device_type, ...)</code>	Gets the settings in the device.
<code>ics.get_device_status(device)</code>	Returns the device status.
<code>ics.get_disk_details(device)</code>	Returns the device disk details.
<code>ics.get_disk_format_progress(device)</code>	Returns the device disk formatting progress.
<code>ics.get_dll_firmware_info(device)</code>	Returns the DLL firmware info for the device.
<code>ics.get_dll_version(device)</code>	Gets the DLL version.
<code>ics.get_error_messages(device[, j1850, timeout])</code>	Gets the error message(s) on the device.

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<code>ics.get_hw_firmware_info(device)</code>	Returns the device firmware info for the device.
<code>ics.get_last_api_error(device)</code>	Gets the error message from the last API call.
<code>ics.get_library_path</code>	
<code>ics.get_messages(device[, j1850, timeout])</code>	Gets the message(s) on the device.
<code>ics.get_pcb_serial_number(device)</code>	Gets the unique PCB serial number of the device.
<code>ics.get_performance_parameters(device)</code>	Gets the Performance Parameters on <i>device</i> .
<code>ics.get_rtc(device)</code>	Gets the Real-Time Clock of the device.
<code>ics.get_script_status</code>	Accepts a <code>ics.ics.NeoDevice</code> , exception on error.
<code>ics.get_serial_number(device)</code>	Gets the serial number out of the device.
<code>ics.get_timestamp_for_msg(device, msg)</code>	Calculates the timestamp for a message.
<code>ics.is_device_feature_supported(device, feature)</code>	Polls firmware in device to see if the feature is supported.
<code>ics.iso15765_disable_networks(device)</code>	Disables ISO15765 networks.
<code>ics.iso15765_enable_networks(device, networks)</code>	Enables ISO15765 networks.
<code>ics.iso15765_receive_message(device, netid, ...)</code>	Setup rx ISO15765 Message.
<code>ics.iso15765_transmit_message(device, ...)</code>	Transmits an ISO15765 Message.
<code>ics.load_default_settings(device)</code>	Load the default settings in the device.
<code>ics.open_device(device)</code>	Opens the device.
<code>ics.override_library_name(new_name)</code>	Overrides the default search for loading the <code>icsneo40</code> library
<code>ics.read_jupiter_firmware(device, size, ...)</code>	Reads firmware binary from a RAD-Jupiter.
<code>ics.read_sdcard</code>	<code>icsneoReadSDCard()</code> , Accepts a <code>ics.ics.NeoDevice</code> and sector index.
<code>ics.request_enter_sleep_mode(device, ...)</code>	Signal neoVI to immediate go to sleep.
<code>ics.set_active_vnet_channel(device, channel)</code>	Sets active vnet channel for the device.
<code>ics.set_backup_power_enabled(device, enable)</code>	Sets the device backup power enabled for the device.
<code>ics.set_bit_rate(device, BitRate, NetworkID)</code>	Specifies bit rate setting.
<code>ics.set_bit_rate_ex(device, BitRate, ...)</code>	Sets the bitrate for a given Network ID on the device with extended options.
<code>ics.set_context(device)</code>	Sets the “context” of how <code>icsneoFindNeoDevices(Ex)</code> and <code>icsneoOpenNeoDevice(Ex)</code> function.
<code>ics.set_device_settings(device, settings, ...)</code>	Sets the settings in the device.
<code>ics.set_fd_bit_rate(device, BitRate, NetworkID)</code>	Sets the FD bitrate for a given Network ID on the device..
<code>ics.set_led_property(device, led, prop, value)</code>	Sets the LED property on the device.
<code>ics.set_reflash_callback(callback)</code>	Sets the reflash display callback.
<code>ics.set_rtc(device[, time])</code>	Sets the Real-Time Clock of the device.
<code>ics.start_dhcp_server(device, network_id, ...)</code>	Starts a DHCP Server.
<code>ics.stop_dhcp_server(device, network_id)</code>	Stops the DHCP Server
<code>ics.transmit_messages(device, messages)</code>	Transmits message(s) on the device.
<code>ics.uart_get_baudrate(device, port)</code>	Gets the UART baudrate on the given port.
<code>ics.uart_read(device, port, bytes_to_read, flags)</code>	Reads UART on the given port.
<code>ics.uart_set_baudrate(device, port, baudrate)</code>	Sets the UART baudrate on the given port.
<code>ics.uart_write(device, port, data, flags)</code>	Writes UART on the given port
<code>ics.validate_hobject(device)</code>	Validates the handle is valid for a <i>device</i> .

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<code>ics.wbms_manager_reset(device, manager)</code>	Resets the manager
<code>ics.wbms_manager_write_lock(device, manager, ...)</code>	Sets the lock state on the manager
<code>ics.write_jupiter_firmware(device, bytes, ...)</code>	Writes firmware binary to a RAD-Jupiter.
<code>ics.write_sdcard</code>	<code>icsneoReadSDCard()</code> , Accepts a <code>ics.ics.NeoDevice</code> , sector index, and a bytearray of 512 bytes.
<code>ics.ClosePort</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.close_device()</code> method.
<code>ics.EnableBusVoltageMonitor</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_bus_voltage_monitor()</code> method.
<code>ics.EnabledDOIPLine</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_doip_line()</code> method.
<code>ics.EnableNetworkCom</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_network_com()</code> method.
<code>ics.FindNeoDevices</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.find_devices()</code> method.
<code>ics.FirmwareUpdateRequired</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.firmware_update_required()</code> method.

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<code>ics.ForceFirmwareUpdate</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.force_firmware_update()</code> method.
<code>ics.GenericAPIGetStatus</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_get_status()</code> method.
<code>ics.GenericAPIReadData</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_read_data()</code> method.
<code>ics.GenericAPISendCommand</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_send_command()</code> method.
<code>ics.GetActiveVNETChannel</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_active_vnet_channel()</code> method.
<code>ics.GetBackupPowerEnabled</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_backup_power_enabled()</code> method.
<code>ics.GetBackupPowerReady</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_backup_power_ready()</code> method.

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<code>ics.GetBusVoltage</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_bus_voltage()</code> method.
<code>ics.GetDLLFirmwareInfo</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_dll_firmware_info()</code> method.
<code>ics.GetDLLVersion</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_dll_version()</code> method.
<code>ics.GetDeviceSettings</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_device_settings()</code> method.
<code>ics.GetDeviceStatus</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_device_status()</code> method.
<code>ics.GetErrorMessages</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_error_messages()</code> method.
<code>ics.GetHWFirmwareInfo</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_hw_firmware_info()</code> method.

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<code>ics.GetLastError</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_last_api_error()</code> method.
<code>ics.GetMessages</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_messages()</code> method.
<code>ics.GetPCBSerialNumber</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_pcb_serial_number()</code> method.
<code>ics.GetPerformanceParameters</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_performance_parameters()</code> method.
<code>ics.GetRTC</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_rtc()</code> method.
<code>ics.GetSerialNumber</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_serial_number()</code> method.
<code>ics.GetTimeStampForMsg</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_timestamp_for_msg()</code> method.

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<code>ics.IsDeviceFeatureSupported</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.is_device_feature_supported()</code> method.
<code>ics.LoadDefaultSettings</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.load_default_settings()</code> method.
<code>ics.OpenNeoDevice</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.open_device()</code> method.
<code>ics.ReadJupiterFirmware</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.read_jupiter_firmware()</code> method.
<code>ics.ReadSDCard</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.read_sdcard()</code> method.
<code>ics.RequestDiskDetails</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_disk_details()</code> method.
<code>ics.RequestDiskFormat</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.disk_format()</code> method.
<code>ics.RequestDiskFormatCancel</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.disk_format_cancel()</code> method.

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<code>ics.RequestDiskFormatProgress</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_disk_format_progress()</code> method.
<code>ics.RequestEnterSleepMode</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.request_enter_sleep_mode()</code> method.
<code>ics.ScriptClear</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_clear()</code> method.
<code>ics.ScriptGetFBlockStatus</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_get_fblock_status()</code> method.
<code>ics.ScriptGetScriptStatus</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_get_status()</code> method.
<code>ics.ScriptGetScriptStatusEx</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_script_status()</code> method.
<code>ics.ScriptLoad</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_load()</code> method.

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<code>ics.ScriptReadAppSignal</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_app_signal()</code> method. <hr/>
<code>ics.ScriptReadRxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_rx_message()</code> method. <hr/>
<code>ics.ScriptReadTxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_tx_message()</code> method. <hr/>
<code>ics.ScriptStart</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_start()</code> method. <hr/>
<code>ics.ScriptStartFBlock</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_start_fblock()</code> method. <hr/>
<code>ics.ScriptStop</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_stop()</code> method. <hr/>
<code>ics.ScriptStopFBlock</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_stop_fblock()</code> method. <hr/>

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<code>ics.ScriptWriteAppSignal</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_app_signal()</code> method. <hr/>
<code>ics.ScriptWriteRxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_rx_message()</code> method. <hr/>
<code>ics.ScriptWriteTxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_tx_message()</code> method. <hr/>
<code>ics.SetActiveVNETChannel</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_active_vnet_channel()</code> method. <hr/>
<code>ics.SetBackupPowerEnabled</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_backup_power_enabled()</code> method. <hr/>
<code>ics.SetBitRate</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_bit_rate()</code> method. <hr/>
<code>ics.SetBitRateEx</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_bit_rate_ex()</code> method. <hr/>

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<code>ics.SetContext</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_context()</code> method. <hr/>
<code>ics.SetDeviceSettings</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_device_settings()</code> method. <hr/>
<code>ics.SetFDBitRate</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_fd_bit_rate()</code> method. <hr/>
<code>ics.SetLedProperty</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_led_property()</code> method. <hr/>
<code>ics.SetRTC</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_rtc()</code> method. <hr/>
<code>ics.SetReflashDisplayCallback</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_reflash_callback()</code> method. <hr/>
<code>ics.StartDHCP Server</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.start_dhcp_server()</code> method. <hr/>
<code>ics.StopDHCP Server</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.stop_dhcp_server()</code> method. <hr/>

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<code>ics.TxMessages</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.transmit_messages()</code> method.
<code>ics.UartGetBaudrate</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_get_baudrate()</code> method.
<code>ics.UartRead</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_read()</code> method.
<code>ics.UartSetBaudrate</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_set_baudrate()</code> method.
<code>ics.UartWrite</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_write()</code> method.
<code>ics.ValidateHObject</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.validate_hobject()</code> method.
<code>ics.WriteJupiterFirmware</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.write_jupiter_firmware()</code> method.
<code>ics.WriteSDCard</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.write_sdcards()</code> method.
<code>ics.base36enc(serial)</code>	Converts a decimal serial number to base36.

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<code>ics.wBMSManagerReset</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.wbms_manager_reset()</code> method.
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<code>ics.wBMSManagerWriteLock</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.wbms_manager_write_lock()</code> method.
<hr/>	
<code>ics.icsneoClosePort</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.close_device()</code> method.
<hr/>	
<code>ics.icsneoEnableBusVoltageMonitor</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_bus_voltage_monitor()</code> method.
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<code>ics.icsneoEnableDOIPLine</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_doip_line()</code> method.
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<code>ics.icsneoEnableNetworkCom</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.enable_network_com()</code> method.
<hr/>	
<code>ics.icsneoFindNeoDevices</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.find_devices()</code> method.
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<code>ics.icsneoFirmwareUpdateRequired</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.firmware_update_required()</code> method.
<code>ics.icsneoForceFirmwareUpdate</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.force_firmware_update()</code> method.
<code>ics.icsneoGenericAPIGetStatus</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_get_status()</code> method.
<code>ics.icsneoGenericAPIReadData</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_read_data()</code> method.
<code>ics.icsneoGenericAPISendCommand</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.generic_api_send_command()</code> method.
<code>ics.icsneoGetActiveVNETChannel</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_active_vnet_channel()</code> method.
<code>ics.icsneoGetBackupPowerEnabled</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_backup_power_enabled()</code> method.

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<code>ics.icsneoGetBackupPowerReady</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_backup_power_ready()</code> method. <hr/>
<code>ics.icsneoGetBusVoltage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_bus_voltage()</code> method. <hr/>
<code>ics.icsneoGetDLLFirmwareInfo</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_dll_firmware_info()</code> method. <hr/>
<code>ics.icsneoGetDLLVersion</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_dll_version()</code> method. <hr/>
<code>ics.icsneoGetDeviceSettings</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_device_settings()</code> method. <hr/>
<code>ics.icsneoGetDeviceStatus</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_device_status()</code> method. <hr/>
<code>ics.icsneoGetErrorMessages</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_error_messages()</code> method. <hr/>

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<code>ics.icsneoGetHWFirmwareInfo</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_hw_firmware_info()</code> method.
<code>ics.icsneoGetLastAPIError</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_last_api_error()</code> method.
<code>ics.icsneoGetMessages</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_messages()</code> method.
<code>ics.icsneoGetPCBSerialNumber</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_pcb_serial_number()</code> method.
<code>ics.icsneoGetPerformanceParameters</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_performance_parameters()</code> method.
<code>ics.icsneoGetRTC</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_rtc()</code> method.
<code>ics.icsneoGetSerialNumber</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_serial_number()</code> method.

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<code>ics.icsneoGetTimeStampForMsg</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_timestamp_for_msg()</code> method.
<code>ics.icsneoISO15765_DisableNetworks</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.iso15765_disable_networks()</code> method.
<code>ics.icsneoISO15765_EnableNetworks</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.iso15765_enable_networks()</code> method.
<code>ics.icsneoISO15765_ReceiveMessage</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.iso15765_receive_message()</code> method.
<code>ics.icsneoISO15765_TransmitMessage</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.iso15765_transmit_message()</code> method.
<code>ics.icsneoIsDeviceFeatureSupported</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.is_device_feature_supported()</code> method.
<code>ics.icsneoLoadDefaultSettings</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.load_default_settings()</code> method.

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<code>ics.icsneoOpenNeoDevice</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.open_device()</code> method.
<code>ics.icsneoReadJupiterFirmware</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.read_jupiter_firmware()</code> method.
<code>ics.icsneoReadSDCard</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.read_sdcard()</code> method.
<code>ics.icsneoRequestDiskDetails</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_disk_details()</code> method.
<code>ics.icsneoRequestDiskFormat</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.disk_format()</code> method.
<code>ics.icsneoRequestDiskFormatCancel</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.disk_format_cancel()</code> method.
<code>ics.icsneoRequestDiskFormatProgress</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_disk_format_progress()</code> method.
<code>ics.icsneoRequestEnterSleepMode</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.request_enter_sleep_mode()</code> method.

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<code>ics.icsneoScriptClear</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_clear()</code> method. <hr/>
<code>ics.icsneoScriptGetFBlockStatus</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_get_fblock_status()</code> method. <hr/>
<code>ics.icsneoScriptGetScriptStatus</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_get_status()</code> method. <hr/>
<code>ics.icsneoScriptGetScriptStatusEx</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.get_script_status()</code> method. <hr/>
<code>ics.icsneoScriptLoad</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_load()</code> method. <hr/>
<code>ics.icsneoScriptReadAppSignal</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_app_signal()</code> method. <hr/>
<code>ics.icsneoScriptReadRxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_rx_message()</code> method. <hr/>

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Table 1 – continued from previous page

<code>ics.icsneoScriptReadTxMessage</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_read_tx_message()</code> method.
<code>ics.icsneoScriptStart</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_start()</code> method.
<code>ics.icsneoScriptStartFBlock</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_start_fblock()</code> method.
<code>ics.icsneoScriptStop</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_stop()</code> method.
<code>ics.icsneoScriptStopFBlock</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_stop_fblock()</code> method.
<code>ics.icsneoScriptWriteAppSignal</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_app_signal()</code> method.
<code>ics.icsneoScriptWriteRxMessage</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_rx_message()</code> method.

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<code>ics.icsneoScriptWriteTxMessage</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.coremini_write_tx_message()</code> method. <hr/>
<code>ics.icsneoSetActiveVNETChannel</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_active_vnet_channel()</code> method. <hr/>
<code>ics.icsneoSetBackupPowerEnabled</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_backup_power_enabled()</code> method. <hr/>
<code>ics.icsneoSetBitRate</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_bit_rate()</code> method. <hr/>
<code>ics.icsneoSetBitRateEx</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_bit_rate_ex()</code> method. <hr/>
<code>ics.icsneoSetContext</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_context()</code> method. <hr/>
<code>ics.icsneoSetDeviceSettings</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_device_settings()</code> method. <hr/>
<code>ics.icsneoSetFDBitRate</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_fd_bit_rate()</code> method. <hr/>

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<code>ics.icsneoSetLedProperty</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_led_property()</code> method.
<code>ics.icsneoSetRTC</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_rtc()</code> method.
<code>ics.icsneoSetReflashDisplayCallbacks</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.set_reflash_callback()</code> method.
<code>ics.icsneoStartDHCP Server</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.start_dhcp_server()</code> method.
<code>ics.icsneoStopDHCP Server</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.stop_dhcp_server()</code> method.
<code>ics.icsneoTxMessages</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.transmit_messages()</code> method.
<code>ics.icsneoUartGetBaudrate</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_get_baudrate()</code> method.
<code>ics.icsneoUartRead</code>	Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_read()</code> method.

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<code>ics.icsneoUartSetBaudrate</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_set_baudrate()</code> method. <hr/>
<code>ics.icsneoUartWrite</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.uart_write()</code> method. <hr/>
<code>ics.icsneoValidateHObject</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.validate_hobject()</code> method. <hr/>
<code>ics.icsneoWriteJupiterFirmware</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.write_jupiter_firmware()</code> method. <hr/>
<code>ics.icsneoWriteSDCard</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.write_sdcard()</code> method. <hr/>
<code>ics.icsneowBMSManagerReset</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.wbms_manager_reset()</code> method. <hr/>
<code>ics.icsneowBMSManagerWriteLock</code>	<hr/> Note: Compatibility Function: Identical to PEP8 compliant <code>ics.ics.wbms_manager_write_lock()</code> method. <hr/>

CHAPTER 9

Module Structures

```
class ics.structures.a2_b_monitor_settings.a2_b_monitor_settings

    downstreamChannelOffset
        Structure/Union member

    flags
        Structure/Union member

    nodeType
        Structure/Union member

    reserved
        Structure/Union member

    tdmMode
        Structure/Union member

    upstreamChannelOffset
        Structure/Union member

class ics.structures.a2_b_node_type.a2_b_node_type
    A ctypes-compatible IntEnum superclass.

    a2bNodeTypeMaster = 1
    a2bNodeTypeMonitor = 0
    a2bNodeTypeSlave = 2

    from_param = <bound method a2_b_node_type.from_param of <enum 'a2_b_node_type'>>

class ics.structures.a2_btdm_mode.a2_btdm_mode
    A ctypes-compatible IntEnum superclass.

    from_param = <bound method a2_btdm_mode.from_param of <enum 'a2_btdm_mode'>>

    tdmModeTDM12 = 3
    tdmModeTDM16 = 4
```

```
tdmModeTDM2 = 0
tdmModeTDM20 = 5
tdmModeTDM24 = 6
tdmModeTDM32 = 7
tdmModeTDM4 = 1
tdmModeTDM8 = 2
```

```
class ics.structures.can_settings.can_settings
```

```
BRP
    Structure/Union member

Baudrate
    Structure/Union member

Mode
    Structure/Union member

SetBaudrate
    Structure/Union member

TqProp
    Structure/Union member

TqSeg1
    Structure/Union member

TqSeg2
    Structure/Union member

TqSync
    Structure/Union member

auto_baud
    Structure/Union member

innerFrameDelay25us
    Structure/Union member

transceiver_mode
    Structure/Union member
```

```
class ics.structures.canfd_settings.canfd_settings
```

```
FDBRP
    Structure/Union member

FDBaudrate
    Structure/Union member

FDMode
    Structure/Union member

FDTDC
    Structure/Union member

FDTqProp
    Structure/Union member
```

FDTqSeg1
Structure/Union member

FDTqSeg2
Structure/Union member

FDTqSync
Structure/Union member

reserved
Structure/Union member

class ics.structures.canterm_settings.canterm_settings

reserved
Structure/Union member

term_enabled
Structure/Union member

term_network
Structure/Union member

class ics.structures.clock_quality_.clock_quality_

clock_accuracy
Structure/Union member

clock_class
Structure/Union member

offset_scaled_log_variance
Structure/Union member

class ics.structures.device_feature.device_feature

A ctypes-compatible IntEnum superclass.

NUM_VALID_DEVICE_FEATURES = 16

from_param = <bound method device_feature.from_param of <enum 'device_feature'>>

networkDWCAN01 = 0

networkDWCAN02 = 1

networkDWCAN03 = 2

networkDWCAN04 = 3

networkDWCAN05 = 4

networkDWCAN06 = 5

networkDWCAN07 = 6

networkDWCAN08 = 7

networkTerminationDWCAN01 = 8

networkTerminationDWCAN02 = 9

networkTerminationDWCAN03 = 10

networkTerminationDWCAN04 = 11

```
networkTerminationDWCAN05 = 12
networkTerminationDWCAN06 = 13
networkTerminationDWCAN07 = 14
networkTerminationDWCAN08 = 15
supportedFeatureMax = 65535

class ics.structures.disk_settings.disk_settings

    disk_enables
        Structure/Union member

    disk_format
        Structure/Union member

    disk_layout
        Structure/Union member

    rsvd
        Structure/Union member

class ics.structures.e_device_settings_type.e_device_settings_type
    A ctypes-compatible IntEnum superclass.

    DeviceCANHUBSettingsType = 19
    DeviceCMPProbeSettingsType = 22
    DeviceECU_AVBSettingsType = 9
    DeviceEEVBSSettingsType = 15
    DeviceEtherBadgeSettingsType = 30
    DeviceFire2SettingsType = 2
    DeviceFire3SettingsType = 28
    DeviceFireSettingsType = 0
    DeviceFireVnetSettingsType = 1
    DeviceFlexVnetzSettingsType = 18
    DeviceIEVBSSettingsType = 20
    DeviceNeoECU12SettingsType = 17
    DeviceOBD2LCSettingsType = 33
    DeviceOBD2ProSettingsType = 23
    DeviceOBD2SimSettingsType = 21
    DeviceRADA2BSettingsType = 31
    DeviceRADBMSSettingsType = 34
    DeviceRADEpsilonSettingsType = 32
    DeviceRADGalaxySettingsType = 4
    DeviceRADGigalogSettingsType = 13
    DeviceRADGigastarSettingsType = 26
```

```
DeviceRADJupiterSettingsType = 27
DeviceRADMoon2SettingsType = 11
DeviceRADPlutoSettingsType = 12
DeviceRADPlutoSwitchSettingsType = 25
DeviceRADStar2SettingsType = 5
DeviceRADSuperMoonSettingsType = 10
DeviceRadMoonDuoSettingsType = 29
DeviceRedSettingsType = 24
DeviceSettingsNone = 4294967295
DeviceSettingsTypeMax = 35
DeviceVCAN3SettingsType = 3
DeviceVCAN412SettingsType = 7
DeviceVCAN4IndSettingsType = 16
DeviceVCAN4SettingsType = 6
DeviceVCANRFSettingsType = 14
DeviceVividCANSettingsType = 8
from_param = <bound method e_device_settings_type.from_param of <enum 'e_device_set

class ics.structures.e_disk_format.e_disk_format
    A ctypes-compatible IntEnum superclass.

    DiskFormatFAT32 = 1
    DiskFormatUnknown = 0
    DiskFormatexFAT = 2
    from_param = <bound method e_disk_format.from_param of <enum 'e_disk_format'>>

class ics.structures.e_disk_layout.e_disk_layout
    A ctypes-compatible IntEnum superclass.

    DiskLayoutIndividual = 4
    DiskLayoutRAID0 = 1
    DiskLayoutRAID1 = 2
    DiskLayoutRAID5 = 3
    DiskLayoutSpanned = 0
    from_param = <bound method e_disk_layout.from_param of <enum 'e_disk_layout'>>

class ics.structures.e_generic_api_options.e_generic_api_options
    A ctypes-compatible IntEnum superclass.

    eADI_WIL_API = 1
    eGENERIC_API = 0
    from_param = <bound method e_generic_api_options.from_param of <enum 'e_generic_api
```

```
class ics.structures.e_gptp_port.e_gptp_port
    A ctypes-compatible IntEnum superclass.

    ePortDisabled = 0
    ePortOpEth1 = 1
    ePortOpEth10 = 10
    ePortOpEth11 = 11
    ePortOpEth12 = 12
    ePortOpEth2 = 2
    ePortOpEth3 = 3
    ePortOpEth4 = 4
    ePortOpEth5 = 5
    ePortOpEth6 = 6
    ePortOpEth7 = 7
    ePortOpEth8 = 8
    ePortOpEth9 = 9
    ePortStdEth1 = 13
    ePortStdEth2 = 14

    from_param = <bound method e_gptp_port.from_param of <enum 'e_gptp_port'>>

class ics.structures.e_gptp_role.e_gptp_role
    A ctypes-compatible IntEnum superclass.

    eRoleDisabled = 0
    eRoleMaster = 2
    eRolePassive = 1
    eRoleSlave = 3

    from_param = <bound method e_gptp_role.from_param of <enum 'e_gptp_role'>>

class ics.structures.e_plasma_ion_vnet_channel_t.e_plasma_ion_vnet_channel_t
    A ctypes-compatible IntEnum superclass.

    PlasmaIonVnetChannelA = 1
    PlasmaIonVnetChannelB = 2
    PlasmaIonVnetChannelMain = 0
    eFpgaStatusResp = 4
    eSoftCore = 3

    from_param = <bound method e_plasma_ion_vnet_channel_t.from_param of <enum 'e_plasma_ion_vnet_channel_t'>>

class ics.structures.e_uart_port_t.e_uart_port_t
    A ctypes-compatible IntEnum superclass.

    eUART0 = 0
    eUART1 = 1
```

```
from_param = <bound method e_uart_port_t.from_param of <enum 'e_uart_port_t'>>

class ics.structures.ethernet10_g_settings.ethernet10_g_settings

    flags
        Structure/Union member

    gateway
        Structure/Union member

    ip_addr
        Structure/Union member

    link_speed
        Structure/Union member

    netmask
        Structure/Union member

    rsvd2
        Structure/Union member

class ics.structures.ethernet_network_status_t.ethernet_network_status_t

    linkFullDuplex
        Structure/Union member

    linkMode
        Structure/Union member

    linkSpeed
        Structure/Union member

    linkStatus
        Structure/Union member

    networkId
        Structure/Union member

class ics.structures.ethernet_settings.ethernet_settings

    auto_neg
        Structure/Union member

    duplex
        Structure/Union member

    led_mode
        Structure/Union member

    link_speed
        Structure/Union member

    rsvd
        Structure/Union member

class ics.structures.ethernet_settings2.ethernet_settings2

    flags
        Structure/Union member
```

```
gateway
    Structure/Union member

ip_addr
    Structure/Union member

link_speed
    Structure/Union member

netmask
    Structure/Union member

rsvd
    Structure/Union member

class ics.structures.ew_bms_instance_t.ew_bms_instance_t
    A ctypes-compatible IntEnum superclass.

    ewBMSInstance0 = 0
    ewBMSInstance1 = 1
    from_param = <bound method ew_bms_instance_t.from_param of <enum 'ew_bms_instance_t'>

class ics.structures.ew_bms_manager_lock_state_t.ew_bms_manager_lock_state_t
    A ctypes-compatible IntEnum superclass.

    eLockManager = 0
    eUnlockManager = 1
    from_param = <bound method ew_bms_manager_lock_state_t.from_param of <enum 'ew_bms_manager_lock_state_t'>

class ics.structures.ew_bms_manager_port_t.ew_bms_manager_port_t
    A ctypes-compatible IntEnum superclass.

    eManagerPortA = 0
    eManagerPortB = 1
    from_param = <bound method ew_bms_manager_port_t.from_param of <enum 'ew_bms_manager_port_t'>

class ics.structures.extended_response_code.extended_response_code
    A ctypes-compatible IntEnum superclass.

    EXTENDED_RESPONSE_INVALID_COMMAND = -1
    EXTENDED_RESPONSE_INVALID_PARAMETER = -5
    EXTENDED_RESPONSE_INVALID_STATE = -2
    EXTENDED_RESPONSE_OK = 0
    EXTENDED_RESPONSE_OPERATION_FAILED = -3
    EXTENDED_RESPONSE_OPERATION_PENDING = -4
    from_param = <bound method extended_response_code.from_param of <enum 'extended_response_code'>

class ics.structures.extended_response_generic.extended_response_generic

    commandType
        Structure/Union member

    returnCode
        Structure/Union member
```



```
class ics.structures.fire3_linux_settings.fire3_linux_settings
```

```
    allowBoot
```

```
        Structure/Union member
```

```
    ethConfigurationPort
```

```
        Structure/Union member
```

```
    reserved
```

```
        Structure/Union member
```

```
    useExternalWifiAntenna
```

```
        Structure/Union member
```

```
class ics.structures.flex_vnet_mode.flex_vnet_mode
```

```
    A ctypes-compatible IntEnum superclass.
```

```
    flexVnetModeColdStart = 4
```

```
    flexVnetModeDisabled = 0
```

```
    flexVnetModeOneDual = 2
```

```
    flexVnetModeOneSingle = 1
```

```
    flexVnetModeTwoSingle = 3
```

```
    from_param = <bound method flex_vnet_mode.from_param of <enum 'flex_vnet_mode'>>
```

```
class ics.structures.generic_api_data.generic_api_data
```

```
    api
```

```
        Structure/Union member
```

```
    bData
```

```
        Structure/Union member
```

```
    length
```

```
        Structure/Union member
```

```
class ics.structures.generic_api_selector.generic_api_selector
```

```
    apiIndex
```

```
        Structure/Union member
```

```
    functionID
```

```
        Structure/Union member
```

```
    instance
```

```
        Structure/Union member
```

```
class ics.structures.generic_api_status.generic_api_status
```

```
    api
```

```
        Structure/Union member
```

```
    callbackError
```

```
        Structure/Union member
```

```
    finishedProcessing
```

```
        Structure/Union member
```

```
functionError
    Structure/Union member

class ics.structures.get_component_versions.get_component_versions

    reserved
        Structure/Union member

class ics.structures.get_component_versions_response.get_component_versions_response

    numVersions
        Structure/Union member

    versions
        Structure/Union member

class ics.structures.get_supported_features_response.get_supported_features_response

    cmdVersion
        Structure/Union member

    featureBitFields
        Structure/Union member

    numValidBits
        Structure/Union member

class ics.structures.global_settings.global_settings

    Nameless46561
        Structure/Union member

    canhub
        Structure/Union member

    chksum
        Structure/Union member

    cmpprobe
        Structure/Union member

    cyan
        Structure/Union member

    ecu
        Structure/Union member

    eevb
        Structure/Union member

    epsilon
        Structure/Union member

    etherBadge
        Structure/Union member

    fire
        Structure/Union member
```

fire3
Structure/Union member

firevnet
Structure/Union member

flexvnetz
Structure/Union member

ievb
Structure/Union member

jupiter
Structure/Union member

len
Structure/Union member

neoecu12
Structure/Union member

neoecu_avb
Structure/Union member

neoobd2_sim
Structure/Union member

obd21c
Structure/Union member

obd2pro
Structure/Union member

pendant
Structure/Union member

pluto
Structure/Union member

rad_a2b
Structure/Union member

rad_bms
Structure/Union member

radgalaxy
Structure/Union member

radgigalog
Structure/Union member

radgigastar
Structure/Union member

radmoon2
Structure/Union member

radmoonduo
Structure/Union member

radstar2
Structure/Union member

radsupermoon
Structure/Union member

red
Structure/Union member

vcan3
Structure/Union member

vcan4
Structure/Union member

vcan412
Structure/Union member

vcan4_12
Structure/Union member

vcan4_ind
Structure/Union member

vcanrf
Structure/Union member

version
Structure/Union member

vividcan
Structure/Union member

class ics.structures.gptp_status.gptp_status

as_capable
Structure/Union member

current_time
Structure/Union member

gm_priority
Structure/Union member

is_sync
Structure/Union member

is_syntonized
Structure/Union member

link_delay_ns
Structure/Union member

link_status
Structure/Union member

ms_offset_ns
Structure/Union member

reserved
Structure/Union member

selected_role
Structure/Union member

```
class ics.structures.hw_eth_settings.hw_eth_settings
```

General_Settings

Structure/Union member

```
class ics.structures.ics_device_status.ics_device_status
```

fire2Status

Structure/Union member

fire3Status

Structure/Union member

flexVnetzStatus

Structure/Union member

jupiterStatus

Structure/Union member

obd2proStatus

Structure/Union member

plutoStatus

Structure/Union member

radBMSStatus

Structure/Union member

radMoonDuoStatus

Structure/Union member

vcan4Status

Structure/Union member

vcan4indStatus

Structure/Union member

```
class ics.structures.ics_fire2_device_status.ics_fire2_device_status
```

backupPowerEnabled

Structure/Union member

backupPowerGood

Structure/Union member

ethernetActivationLineEnabled

Structure/Union member

ethernetStatus

Structure/Union member

usbHostPowerEnabled

Structure/Union member

```
class ics.structures.ics_fire2_vnet_device_status.ics_fire2_vnet_device_status
```

ethernetActivationLineEnabled

Structure/Union member

ethernetStatus

Structure/Union member

unused

Structure/Union member

class ics.structures.ics_fire3_device_status.ics_fire3_device_status

ethernetActivationLineEnabled

Structure/Union member

ethernetStatus

Structure/Union member

unused

Structure/Union member

class ics.structures.ics_flex_vnetz_device_status.ics_flex_vnetz_device_status

ethernetActivationLineEnabled

Structure/Union member

ethernetStatus

Structure/Union member

unused

Structure/Union member

class ics.structures.ics_obd2_pro_device_status.ics_obd2_pro_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_rad_bms_device_status.ics_rad_bms_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_rad_epsilon_device_status.ics_rad_epsilon_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_rad_jupiter_device_status.ics_rad_jupiter_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_rad_moon_duo_device_status.ics_rad_moon_duo_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_rad_pluto_device_status.ics_rad_pluto_device_status

ethernetStatus

Structure/Union member

class ics.structures.ics_spy_message_flex_ray.ics_spy_message_flex_ray**AckBytes**

Structure/Union member

ArbIDOrHeader

Structure/Union member

Data

Structure/Union member

DescriptionID

Structure/Union member

ExtraDataPtr

Structure/Union member

ExtraDataPtrEnabled

Structure/Union member

MessagePieceID

Structure/Union member

MiscData

Structure/Union member

Nameless61974

Structure/Union member

Nameless7100

Structure/Union member

NetworkID

Structure/Union member

NetworkID2

Structure/Union member

NodeID

Structure/Union member

NumberBytesData

Structure/Union member

NumberBytesHeader

Structure/Union member

Protocol

Structure/Union member

Reserved

Structure/Union member

StatusBitField

Structure/Union member

StatusBitField2

Structure/Union member

StatusBitField3
Structure/Union member

StatusBitField4
Structure/Union member

TimeHardware
Structure/Union member

TimeHardware2
Structure/Union member

TimeStampHardwareID
Structure/Union member

TimeStampSystemID
Structure/Union member

TimeSystem
Structure/Union member

TimeSystem2
Structure/Union member

chA
Structure/Union member

chB
Structure/Union member

cycle
Structure/Union member

dynamic
Structure/Union member

fcrc0
Structure/Union member

fcrc1
Structure/Union member

fcrc2
Structure/Union member

frame_len_12_5ns
Structure/Union member

frame_reserved
Structure/Union member

hcrc_lsbs
Structure/Union member

hcrc_msbs
Structure/Union member

id
Structure/Union member

null_frame
Structure/Union member

payload_preamble
Structure/Union member

res1
Structure/Union member

res2
Structure/Union member

startup
Structure/Union member

sync
Structure/Union member

tss_len_12_5ns
Structure/Union member

class ics.structures.ics_spy_message_long.ics_spy_message_long

AckBytes
Structure/Union member

ArbIDOrHeader
Structure/Union member

DataLsb
Structure/Union member

DataMsb
Structure/Union member

DescriptionID
Structure/Union member

ExtraDataPtr
Structure/Union member

ExtraDataPtrEnabled
Structure/Union member

MessagePieceID
Structure/Union member

MiscData
Structure/Union member

Nameless65087
Structure/Union member

NetworkID
Structure/Union member

NetworkID2
Structure/Union member

NodeID
Structure/Union member

NumberBytesData
Structure/Union member

NumberBytesHeader
Structure/Union member

Protocol
Structure/Union member

Reserved
Structure/Union member

StatusBitField
Structure/Union member

StatusBitField2
Structure/Union member

StatusBitField3
Structure/Union member

StatusBitField4
Structure/Union member

TimeHardware
Structure/Union member

TimeHardware2
Structure/Union member

TimeStampHardwareID
Structure/Union member

TimeStampSystemID
Structure/Union member

TimeSystem
Structure/Union member

TimeSystem2
Structure/Union member

class ics.structures.ics_spy_message_vsb.ics_spy_message_vsb

AckBytes
Structure/Union member

ArbIDOrHeader
Structure/Union member

Data
Structure/Union member

DescriptionID
Structure/Union member

ExtraDataPtr
Structure/Union member

ExtraDataPtrEnabled
Structure/Union member

MessagePieceID
Structure/Union member

MiscData
Structure/Union member

Nameless18906
Structure/Union member

NetworkID
Structure/Union member

NetworkID2
Structure/Union member

NodeID
Structure/Union member

NumberBytesData
Structure/Union member

NumberBytesHeader
Structure/Union member

Protocol
Structure/Union member

Reserved
Structure/Union member

StatusBitField
Structure/Union member

StatusBitField2
Structure/Union member

StatusBitField3
Structure/Union member

StatusBitField4
Structure/Union member

TimeHardware
Structure/Union member

TimeHardware2
Structure/Union member

TimeStampHardwareID
Structure/Union member

TimeStampSystemID
Structure/Union member

TimeSystem
Structure/Union member

TimeSystem2
Structure/Union member

class ics.structures.ics_vcan4_device_status.ics_vcan4_device_status

ethernetActivationLineEnabled
Structure/Union member

ethernetStatus

Structure/Union member

unused

Structure/Union member

```
class ics.structures.ics_vcan4_industrial_device_status.ics_vcan4_industrial_device_st.
```

ethernetStatus

Structure/Union member

```
class ics.structures.iso15765_2015_tx_message.iso15765_2015_tx_message
```

Nameless59426

Structure/Union member

blockSize

Structure/Union member

data

Structure/Union member

ext_address_enable

Structure/Union member

extendedAddress

Structure/Union member

fc_ext_address_enable

Structure/Union member

fc_id

Structure/Union member

fc_id_29_bit_enable

Structure/Union member

fc_id_mask

Structure/Union member

flags

Structure/Union member

flowControlExtendedAddress

Structure/Union member

fs_timeout

Structure/Union member

fs_wait

Structure/Union member

id

Structure/Union member

id_29_bit_enable

Structure/Union member

isBRSEnabled

Structure/Union member

iscanFD
Structure/Union member

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Structure/Union member

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Structure/Union member

overrideSTmin
Structure/Union member

padding
Structure/Union member

paddingEnable
Structure/Union member

stMin
Structure/Union member

tx_dl
Structure/Union member

tx_index
Structure/Union member

vs_netid
Structure/Union member

class ics.structures.iso9141_keyword2000_init_step.**iso9141_keyword2000_init_step**

k
Structure/Union member

l
Structure/Union member

time_500us
Structure/Union member

class ics.structures.iso9141_keyword2000_settings.**iso9141_keyword2000_settings**

Baudrate
Structure/Union member

brgh
Structure/Union member

chksum_enabled
Structure/Union member

init_step_count
Structure/Union member

init_steps
Structure/Union member

p2_500us
Structure/Union member

p3_500us
Structure/Union member

p4_500us
Structure/Union member

spbrg
Structure/Union member

class ics.structures.j1708_settings.j1708_settings

enable_convert_mode
Structure/Union member

class ics.structures.lin_settings.lin_settings

Baudrate
Structure/Union member

MasterResistor
Structure/Union member

Mode
Structure/Union member

brgh
Structure/Union member

numBitsDelay
Structure/Union member

spbrg
Structure/Union member

class ics.structures.logger_settings.logger_settings

extraction_timeout
Structure/Union member

rsvd
Structure/Union member

class ics.structures.ndis_adapter_information.ndis_adapter_information

EthernetPinConfig
Structure/Union member

Status
Structure/Union member

bIPV4_Address
Structure/Union member

bIPV6_Address
Structure/Union member

bMAC_Address
Structure/Union member

```
szDeviceName
    Structure/Union member

szName
    Structure/Union member

class ics.structures.op_eth_general_settings.op_eth_general_settings

    Nameless19471
        Structure/Union member

    flags
        Structure/Union member

    reserved0
        Structure/Union member

    tapPair0
        Structure/Union member

    tapPair1
        Structure/Union member

    tapPair2
        Structure/Union member

    tapPair3
        Structure/Union member

    tapPair4
        Structure/Union member

    tapPair5
        Structure/Union member

    uFlags
        Structure/Union member

    ucInterfaceType
        Structure/Union member

class ics.structures.op_eth_link_mode.op_eth_link_mode
    A ctypes-compatible IntEnum superclass.

    OPETH_LINK_AUTO = 0

    OPETH_LINK_MASTER = 1

    OPETH_LINK_SLAVE = 2

    from_param = <bound method op_eth_link_mode.from_param of <enum 'op_eth_link_mode'>

class ics.structures.op_eth_settings.op_eth_settings

    Nameless14996
        Structure/Union member

    link_spd
        Structure/Union member

    mac_addr1
        Structure/Union member
```

```
mac_addr2
    Structure/Union member

mac_spoofing_en
    Structure/Union member

mac_spoofing_isDstOrSrc
    Structure/Union member

preemption_en
    Structure/Union member

q2112_phy_mode
    Structure/Union member

reserved
    Structure/Union member

reserved0
    Structure/Union member

ucConfigMode
    Structure/Union member

class ics.structures.port_identity.port_identity

    clock_identity
        Structure/Union member

    port_number
        Structure/Union member

class ics.structures.priority_vector.priority_vector

    port_number
        Structure/Union member

    portid
        Structure/Union member

    steps_removed
        Structure/Union member

    sysid
        Structure/Union member

class ics.structures.rad_moon_duo_converter_settings.rad_moon_duo_converter_settings

    converter1Mode
        Structure/Union member

    ipAddress
        Structure/Union member

    ipGateway
        Structure/Union member

    ipMask
        Structure/Union member
```


linkMode0
Structure/Union member

linkMode1
Structure/Union member

class ics.structures.rad_reporting_settings.rad_reporting_settings

fan_speed_interval_ms
Structure/Union member

flags
Structure/Union member

gps_interval_ms
Structure/Union member

io_interval_ms
Structure/Union member

rsvd
Structure/Union member

serdes_interval_ms
Structure/Union member

temp_interval_ms
Structure/Union member

class ics.structures.s_cm_probe_settings.s_cm_probe_settings

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

class ics.structures.s_cyan_settings.s_cyan_settings

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

can5
Structure/Union member

can6
Structure/Union member

can7
Structure/Union member

can8
Structure/Union member

can_switch_mode
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
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canfd4
Structure/Union member

canfd5
Structure/Union member

canfd6
Structure/Union member

canfd7
Structure/Union member

canfd8
Structure/Union member

digitalIoThresholdEnable
Structure/Union member

digitalIoThresholdTicks
Structure/Union member

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Structure/Union member

ethernet
Structure/Union member

ethernet2
Structure/Union member

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idle_wakeup_network_enables_1
Structure/Union member

idle_wakeup_network_enables_2
Structure/Union member

idle_wakeup_network_enables_3
Structure/Union member

iso15765_separation_time_offset

Structure/Union member

iso9141_kwp_settings_1

Structure/Union member

iso9141_kwp_settings_2

Structure/Union member

iso9141_kwp_settings_3

Structure/Union member

iso9141_kwp_settings_4

Structure/Union member

iso_9141_kwp_enable_reserved

Structure/Union member

iso_msg_termination_1

Structure/Union member

iso_msg_termination_2

Structure/Union member

iso_msg_termination_3

Structure/Union member

iso_msg_termination_4

Structure/Union member

iso_parity_1

Structure/Union member

iso_parity_2

Structure/Union member

iso_parity_3

Structure/Union member

iso_parity_4

Structure/Union member

lin1

Structure/Union member

lin2

Structure/Union member

lin3

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lin4

Structure/Union member

lin5

Structure/Union member

lin6

Structure/Union member

lsftcan1

Structure/Union member

lsftcan2
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

network_enables_3
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

slaveVnetA
Structure/Union member

slaveVnetB
Structure/Union member

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Structure/Union member

swcan2
Structure/Union member

termination_enables
Structure/Union member

text_api
Structure/Union member

timeSync
Structure/Union member

class ics.structures.s_device_settings.**s_device_settings**

DeviceSettingType
Structure/Union member

Settings
Structure/Union member

class ics.structures.s_disk_details.**s_disk_details**

status
Structure/Union member

structure
Structure/Union member

class ics.structures.s_disk_format_progress.**s_disk_format_progress**

sectorsRemaining
Structure/Union member

state
Structure/Union member

class ics.structures.s_disk_status.**s_disk_status**

bytesPerSector
Structure/Union member

sectors
Structure/Union member

status
Structure/Union member

class ics.structures.s_disk_structure.**s_disk_structure**

options
Structure/Union member

settings
Structure/Union member

class ics.structures.s_ether_badge_settings.**s_ether_badge_settings**

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

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Structure/Union member

ethernet2
Structure/Union member

flags
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_enable_reserved
Structure/Union member

iso9141_kwp_settings
Structure/Union member

iso_msg_termination
Structure/Union member

iso_parity
Structure/Union member

iso_tester_pullup_enable
Structure/Union member

lin1
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

network_enables_3
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

termination_enables
Structure/Union member

text_api
Structure/Union member

class ics.structures.s_ext_sub_cmd_comm.**s_ext_sub_cmd_comm**

extension
Structure/Union member

header
Structure/Union member

class ics.structures.s_ext_sub_cmd_hdr.**s_ext_sub_cmd_hdr**

command
Structure/Union member

length
Structure/Union member

class ics.structures.s_extended_data_flash_header.**s_extended_data_flash_header**

chksum
Structure/Union member

len
Structure/Union member

version
Structure/Union member

class ics.structures.s_fire3_settings.**s_fire3_settings**

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

can5
Structure/Union member

can6
Structure/Union member

can7
Structure/Union member

can8
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
Structure/Union member

canfd4
Structure/Union member

canfd5
Structure/Union member

canfd6
Structure/Union member

canfd7
Structure/Union member

canfd8
Structure/Union member

digitalIoThresholdEnable
Structure/Union member

digitalIoThresholdTicks
Structure/Union member

disk
Structure/Union member

ethernet2_1
Structure/Union member

ethernet2_2
Structure/Union member

ethernet_1
Structure/Union member

ethernet_2
Structure/Union member

flags
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_settings_1
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso_msg_termination_1
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_parity_1
Structure/Union member

iso_parity_2
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

os_settings
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

reserved
Structure/Union member

slaveVnetA
Structure/Union member

termination_enables
Structure/Union member

text_api
Structure/Union member

timeSync
Structure/Union member

class ics.structures.s_fire_settings.s_fire_settings

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

cgi_baud
Structure/Union member

cgi_chksum_enable
Structure/Union member

cgi_enable_reserved
Structure/Union member

cgi_rx_ifs_bit_times
Structure/Union member

cgi_tx_ifs_bit_times
Structure/Union member

fast_init_network_enables_1
Structure/Union member

fast_init_network_enables_2
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_enable_reserved
Structure/Union member

iso9141_kwp_settings
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso9141_kwp_settings_3
Structure/Union member

iso9141_kwp_settings_4
Structure/Union member

iso_msg_termination
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_msg_termination_3
Structure/Union member

iso_msg_termination_4
Structure/Union member

iso_parity
Structure/Union member

iso_parity_2
Structure/Union member

iso_parity_3
Structure/Union member

iso_parity_4
Structure/Union member

iso_tester_pullup_enable
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

lin3
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lin4
Structure/Union member

lsftcan
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

neoMostGateway
Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

network_enables_2

Structure/Union member

perf_en

Structure/Union member

pwm_man_timeout

Structure/Union member

pwr_man_enable

Structure/Union member

swcan

Structure/Union member

text_api

Structure/Union member

uart

Structure/Union member

uart2

Structure/Union member

vnetBits

Structure/Union member

class ics.structures.s_fire_vnet_settings.s_fire_vnet_settings

ain_sample_period

Structure/Union member

ain_threshold

Structure/Union member

can1

Structure/Union member

can2

Structure/Union member

can3

Structure/Union member

can4

Structure/Union member

can5

Structure/Union member

can6

Structure/Union member

cgi_baud

Structure/Union member

cgi_chksum_enable
Structure/Union member

cgi_enable_reserved
Structure/Union member

cgi_rx_ifs_bit_times
Structure/Union member

cgi_tx_ifs_bit_times
Structure/Union member

fast_init_network_enables_1
Structure/Union member

fast_init_network_enables_2
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_enable_reserved
Structure/Union member

iso9141_kwp_settings
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso9141_kwp_settings_3
Structure/Union member

iso9141_kwp_settings_4
Structure/Union member

iso_msg_termination
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_msg_termination_3
Structure/Union member

iso_msg_termination_4
Structure/Union member

iso_parity
Structure/Union member

iso_parity_2
Structure/Union member

iso_parity_3
Structure/Union member

iso_parity_4
Structure/Union member

iso_tester_pullup_enable
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

lin3
Structure/Union member

lin4
Structure/Union member

lin5
Structure/Union member

lsftcan
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

neoMostGateway
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

perf_en
Structure/Union member

pwm_man_timeout
Structure/Union member

pwr_man_enable
Structure/Union member

swcan
Structure/Union member

swcan2
Structure/Union member

text_api
Structure/Union member

uart
Structure/Union member

uart2
Structure/Union member

vnetBits
Structure/Union member

class ics.structures.s_flex_vnetz_settings.**s_flex_vnetz_settings**

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

can5
Structure/Union member

can6
Structure/Union member

can7
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
Structure/Union member

canfd4
Structure/Union member

canfd5
Structure/Union member

canfd6
Structure/Union member

canfd7
Structure/Union member

disk
Structure/Union member

ethernet
Structure/Union member

ethernet2
Structure/Union member

flags
Structure/Union member

flex_mode
Structure/Union member

flex_termination
Structure/Union member

iso15765_separation_time_offset
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network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

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Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

slaveVnetA
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slaveVnetB
Structure/Union member

termination_enables
Structure/Union member

text_api
Structure/Union member

timeSync
Structure/Union member

class ics.structures.s_jupiter_ptp_params_s.s_jupiter_ptp_params_s

gPTPportRole
Structure/Union member

initLogPDelayReqInterval
Structure/Union member

initLogSyncInterval
Structure/Union member

neighborPropDelay
Structure/Union member

operationLogPDelayReqInterval
Structure/Union member

operationLogSyncInterval

Structure/Union member

class ics.structures.s_neo_ecu12_settings.s_neo_ecu12_settings

ain_sample_period

Structure/Union member

ain_threshold

Structure/Union member

can1

Structure/Union member

can2

Structure/Union member

can_switch_mode

Structure/Union member

canfd1

Structure/Union member

canfd2

Structure/Union member

ecu_id

Structure/Union member

flags

Structure/Union member

iso15765_separation_time_offset

Structure/Union member

iso9141_kwp_settings

Structure/Union member

iso_9141_kwp_enable_reserved

Structure/Union member

iso_msg_termination

Structure/Union member

iso_parity

Structure/Union member

lin1

Structure/Union member

lsftcan1

Structure/Union member

lsftcan2

Structure/Union member

misc_io_analog_enable

Structure/Union member

misc_io_initial_ddr

Structure/Union member

misc_io_initial_latch

Structure/Union member

misc_io_on_report_events

Structure/Union member

misc_io_report_period

Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

perf_en

Structure/Union member

pwr_man_enable

Structure/Union member

pwr_man_timeout

Structure/Union member

reserved_field

Structure/Union member

swcan1

Structure/Union member

swcan2

Structure/Union member

termination_enables

Structure/Union member

text_api

Structure/Union member

class ics.structures.s_neo_most_gateway_settings.**s_neo_most_gateway_settings**

Config

Structure/Union member

netId

Structure/Union member

zero0

Structure/Union member

class ics.structures.s_pendant_settings.**s_pendant_settings**

ain_sample_period

Structure/Union member

ain_threshold

Structure/Union member

can1

Structure/Union member

can2
Structure/Union member

ecu_id
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iso15765_separation_time_offset
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iso9141_kwp_settings
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iso9141_kwp_settings_2
Structure/Union member

iso_msg_termination
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_parity
Structure/Union member

iso_parity_2
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lin1
Structure/Union member

lin2
Structure/Union member

lsftcan
Structure/Union member

lsftcan2
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misc_io_analog_enable
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misc_io_initial_ddr
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misc_io_initial_latch
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misc_io_on_report_events
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network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

selected_network
Structure/Union member

swcan
Structure/Union member

swcan2
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text_api
Structure/Union member

uart
Structure/Union member

uart2
Structure/Union member

class ics.structures.s_phy_reg_pkt.s_phy_reg_pkt

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Structure/Union member

Clause45Enable
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Enabled
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Nameless14534
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Nameless45381
Structure/Union member

WriteEnable
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Structure/Union member

flags
Structure/Union member

reserved
Structure/Union member

status
Structure/Union member

version
Structure/Union member

```
class ics.structures.s_phy_reg_pkt_clause22_mess.s_phy_reg_pkt_clause22_mess
```

```
    page  
        Structure/Union member  
  
    phyAddr  
        Structure/Union member  
  
    regAddr  
        Structure/Union member  
  
    regVal  
        Structure/Union member
```

```
class ics.structures.s_phy_reg_pkt_clause45_mess.s_phy_reg_pkt_clause45_mess
```

```
    device  
        Structure/Union member  
  
    port  
        Structure/Union member  
  
    regAddr  
        Structure/Union member  
  
    regVal  
        Structure/Union member
```

```
class ics.structures.s_phy_reg_pkt_hdr.s_phy_reg_pkt_hdr
```

```
    entryBytes  
        Structure/Union member  
  
    numEntries  
        Structure/Union member  
  
    version  
        Structure/Union member
```

```
class ics.structures.s_phy_reg_pkt_rw.s_phy_reg_pkt_rw
```

A ctypes-compatible IntEnum superclass.

```
PHYREG_BOTH = 2
```

```
PHYREG_READ = 0
```

```
PHYREG_WRITE = 1
```

```
from_param = <bound method s_phy_reg_pkt_rw.from_param of <enum 's_phy_reg_pkt_rw'>
```

```
class ics.structures.s_phy_reg_pkt_status.s_phy_reg_pkt_status
```

A ctypes-compatible IntEnum superclass.

```
PHYREG_FAILURE = 1
```

```
PHYREG_INVALID_MDIO_BUS_INDEX = 2
```

```
PHYREG_INVALID_PHY_ADDR = 3
```

```
PHYREG_RESERVED0 = 4
```

```
PHYREG_RESERVED1 = 5
```

```
PHYREG_RESERVED2 = 6
PHYREG_RESERVED3 = 7
PHYREG_SUCCESS = 0

from_param = <bound method s_phy_reg_pkt_status.from_param of <enum 's_phy_reg_pkt_
class ics.structures.s_pluto_avb_params_s.s_pluto_avb_params_s

    destmeta
        Structure/Union member

    srcmeta
        Structure/Union member

class ics.structures.s_pluto_clock_sync_params_s.s_pluto_clock_sync_params_s

    accdevwin
        Structure/Union member

    asytensyen
        Structure/Union member

    caentmout
        Structure/Union member

    etssrcpcf
        Structure/Union member

    fullcbg
        Structure/Union member

    intcydur
        Structure/Union member

    inttosyncth
        Structure/Union member

    inttotenth
        Structure/Union member

    ipcframesy
        Structure/Union member

    listentmout
        Structure/Union member

    maxintegcy
        Structure/Union member

    maxtranspcclk
        Structure/Union member

    numstbcy
        Structure/Union member

    numunstbcy
        Structure/Union member

    obvwinsz
        Structure/Union member
```

pad1
Structure/Union member

pad2
Structure/Union member

pad3
Structure/Union member

pcfpriority
Structure/Union member

pcfsze
Structure/Union member

srcport
Structure/Union member

stabasyen
Structure/Union member

stth
Structure/Union member

sttointth
Structure/Union member

swmaster
Structure/Union member

syasyen
Structure/Union member

sydomain
Structure/Union member

sypriority
Structure/Union member

syrelen
Structure/Union member

sysyen
Structure/Union member

syth
Structure/Union member

sytostben
Structure/Union member

sytousyth
Structure/Union member

tentsyrelen
Structure/Union member

tsyth
Structure/Union member

tsyotosyth
Structure/Union member

tsytousyth
Structure/Union member

unsytosyth
Structure/Union member

unsytotsyth
Structure/Union member

vldimnmin
Structure/Union member

vldinmax
Structure/Union member

vlidout
Structure/Union member

vlidselect
Structure/Union member

waitthsync
Structure/Union member

wfintmout
Structure/Union member

class ics.structures.s_pluto_custom_params_s.**s_pluto_custom_params_s**

ae1Select
Structure/Union member

enablePhy
Structure/Union member

mode
Structure/Union member

pad
Structure/Union member

ptpParams
Structure/Union member

speed
Structure/Union member

usbSelect
Structure/Union member

class ics.structures.s_pluto_general_params_s.**s_pluto_general_params_s**

casc_port
Structure/Union member

host_port
Structure/Union member

hostprio
Structure/Union member

ignore2stf
Structure/Union member

incl_srcpt0
Structure/Union member

incl_srcpt1
Structure/Union member

macflt0
Structure/Union member

macflt1
Structure/Union member

macfltres0
Structure/Union member

macfltres1
Structure/Union member

mirr_port
Structure/Union member

mirr_ptacu
Structure/Union member

send_meta0
Structure/Union member

send_meta1
Structure/Union member

switchid
Structure/Union member

tpid
Structure/Union member

tpid2
Structure/Union member

vllupformat
Structure/Union member

vlmarker
Structure/Union member

vlmask
Structure/Union member

class ics.structures.s_pluto_l2_address_lookup_entry_s.**s_pluto_l2_address_lookup_entry**

destports
Structure/Union member

enfport
Structure/Union member

index
Structure/Union member

learnedEntry
Structure/Union member

macaddr
Structure/Union member

pad1
Structure/Union member

pad2
Structure/Union member

pad3
Structure/Union member

vlanID
Structure/Union member

class ics.structures.s_pluto_l2_address_lookup_params_s.s_pluto_l2_address_lookup_params_s

dyn_tbsz
Structure/Union member

maxage
Structure/Union member

no_enf_hostprt
Structure/Union member

no_mgmt_learn
Structure/Union member

pad
Structure/Union member

poly
Structure/Union member

shared_learn
Structure/Union member

class ics.structures.s_pluto_l2_forwarding_entry_s.s_pluto_l2_forwarding_entry_s

bc_domain
Structure/Union member

fl_domain
Structure/Union member

pad
Structure/Union member

reach_port
Structure/Union member

vlan_pmap
Structure/Union member

class ics.structures.s_pluto_l2_forwarding_params_s.s_pluto_l2_forwarding_params_s

max_dynp
Structure/Union member

pad
Structure/Union member

part_spc
Structure/Union member

class ics.structures.s_pluto_l2_policing_s.s_pluto_l2_policing_s

maxlen
Structure/Union member

partition
Structure/Union member

rate
Structure/Union member

sharindx
Structure/Union member

smax
Structure/Union member

class ics.structures.s_pluto_mac_config_s.s_pluto_mac_config_s

base
Structure/Union member

drpdtag
Structure/Union member

drpnona664
Structure/Union member

drpuntag
Structure/Union member

dyn_learn
Structure/Union member

egr_mirr
Structure/Union member

egress
Structure/Union member

enabled
Structure/Union member

ifg
Structure/Union member

ing_mirr
Structure/Union member

ingress
Structure/Union member

maxage
Structure/Union member

pad
Structure/Union member

retag
Structure/Union member

speed
Structure/Union member

top
Structure/Union member

tp_delin
Structure/Union member

tp_delout
Structure/Union member

vlanid
Structure/Union member

vlanprio
Structure/Union member

class ics.structures.s_pluto_ptp_params_s.s_pluto_ptp_params_s

clockaccuracy
Structure/Union member

clockclass
Structure/Union member

gPTPportRole
Structure/Union member

logAnnounceInterval
Structure/Union member

logPDelayReqInterval
Structure/Union member

logSyncInterval
Structure/Union member

neighborPropDelayThresh
Structure/Union member

offset_scaled_log_variance
Structure/Union member

portEnable
Structure/Union member

priority1
Structure/Union member

priority2
Structure/Union member

profile
Structure/Union member

sys_phc_sync_interval
Structure/Union member

class ics.structures.s_pluto_retagging_entry_s.s_pluto_retagging_entry_s

destports
Structure/Union member

do_not_learn
Structure/Union member

egr_port
Structure/Union member

ing_port
Structure/Union member

pad
Structure/Union member

use_dest_ports
Structure/Union member

vlan_egr
Structure/Union member

vlan_ing
Structure/Union member

class ics.structures.s_pluto_switch_settings_s.s_pluto_switch_settings_s

flashHeader
Structure/Union member

generalParams
Structure/Union member

12_ForwardingEntries
Structure/Union member

12_addressLookupEntries
Structure/Union member

12_addressLookupParams
Structure/Union member

12_forwardingParams
Structure/Union member

12_policing
Structure/Union member

macConfig
Structure/Union member

retagging
Structure/Union member

```
vlan_LookupEntries
    Structure/Union member

class ics.structures.s_pluto_vl_forwarding_entry_s.s_pluto_vl_forwarding_entry_s

    destports
        Structure/Union member

    partition
        Structure/Union member

    priority
        Structure/Union member

    type
        Structure/Union member

class ics.structures.s_pluto_vl_forwarding_params_s.s_pluto_vl_forwarding_params_s

    debugen
        Structure/Union member

    pad
        Structure/Union member

    partspc
        Structure/Union member

class ics.structures.s_pluto_vl_lookup_entry_s.s_pluto_vl_lookup_entry_s

    Nameless6024
        Structure/Union member

    vllupformat0
        Structure/Union member

    vllupformat1
        Structure/Union member

class ics.structures.s_pluto_vl_policing_entry_s.s_pluto_vl_policing_entry_s

    bag
        Structure/Union member

    jitter
        Structure/Union member

    maxlen
        Structure/Union member

    sharindx
        Structure/Union member

    type
        Structure/Union member

class ics.structures.s_pluto_vlan_lookup_s.s_pluto_vlan_lookup_s
```

pad
Structure/Union member

tag_port
Structure/Union member

vegr_mirr
Structure/Union member

ving_mirr
Structure/Union member

vlan_bc
Structure/Union member

vlanid
Structure/Union member

vmemb_port
Structure/Union member

class ics.structures.s_rad_moon_duo_settings.**s_rad_moon_duo_settings**

converter
Structure/Union member

flags
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

class ics.structures.s_red_settings.**s_red_settings**

can1
Structure/Union member

can2
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

class ics.structures.s_text_api_settings.**s_text_api_settings**

can1_options
Structure/Union member

can1_rx_id
Structure/Union member

can1_tx_id
Structure/Union member

can2_options
Structure/Union member

can2_rx_id
Structure/Union member

can2_tx_id
Structure/Union member

can3_options
Structure/Union member

can3_rx_id
Structure/Union member

can3_tx_id
Structure/Union member

can4_options
Structure/Union member

can4_rx_id
Structure/Union member

can4_tx_id
Structure/Union member

network_enables
Structure/Union member

reserved
Structure/Union member

class ics.structures.s_vivid_can_settings.s_vivid_can_settings

can1
Structure/Union member

can_switch_mode
Structure/Union member

ecu_id
Structure/Union member

flags
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

lsftcan1
Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

perf_en

Structure/Union member

pwr_man_enable

Structure/Union member

pwr_man_timeout

Structure/Union member

swcan1

Structure/Union member

termination_enables

Structure/Union member

class ics.structures.scan_hub_settings.scan_hub_settings

can1

Structure/Union member

canfd1

Structure/Union member

ecu_id

Structure/Union member

iso15765_separation_time_offset

Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

pwr_man_enable

Structure/Union member

pwr_man_timeout

Structure/Union member

sleep_id

Structure/Union member

termination_enables

Structure/Union member

class ics.structures.scan_sleep_id.scan_sleep_id

id

Structure/Union member

word

Structure/Union member

```
class ics.structures.secu_avb_settings.secu_avb_settings
```

```
    can1  
        Structure/Union member  
  
    can2  
        Structure/Union member  
  
    canfd1  
        Structure/Union member  
  
    canfd2  
        Structure/Union member  
  
    flags  
        Structure/Union member  
  
    iso15765_separation_time_offset  
        Structure/Union member  
  
    network_enabled_on_boot  
        Structure/Union member  
  
    network_enables  
        Structure/Union member  
  
    perf_en  
        Structure/Union member  
  
    pwr_man_enable  
        Structure/Union member  
  
    pwr_man_timeout  
        Structure/Union member  
  
    termination_enables  
        Structure/Union member  
  
    text_api  
        Structure/Union member
```

```
class ics.structures.secu_settings.secu_settings
```

```
    ain_sample_period  
        Structure/Union member  
  
    ain_threshold  
        Structure/Union member  
  
    can1  
        Structure/Union member  
  
    can2  
        Structure/Union member  
  
    ecu_id  
        Structure/Union member  
  
    iso15765_separation_time_offset  
        Structure/Union member
```

iso9141_kwp_settings
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso_msg_termination
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_parity
Structure/Union member

iso_parity_2
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

lsftcan
Structure/Union member

lsftcan2
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

selected_network
Structure/Union member

swcan
Structure/Union member

swcan2
Structure/Union member

text_api
Structure/Union member

uart
Structure/Union member

uart2
Structure/Union member

class ics.structures.seevb_settings.seevb_settings

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

ecu_id
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

perf_en
Structure/Union member

rsvd
Structure/Union member

class ics.structures.serdescam_settings.serdescam_settings

bitPos
Structure/Union member

flags
Structure/Union member

frameSkip
Structure/Union member

mode
Structure/Union member

resHeight
Structure/Union member

resWidth
Structure/Union member

rsvd1
Structure/Union member

rsvd2
Structure/Union member

videoFormat
Structure/Union member

class ics.structures.serdesgen_settings.**serdesgen_settings**

flags
Structure/Union member

mod_id
Structure/Union member

rsvd1
Structure/Union member

rsvd2
Structure/Union member

rx_speed
Structure/Union member

tx_speed
Structure/Union member

class ics.structures.serdespoc_settings.**serdespoc_settings**

chksum
Structure/Union member

mode
Structure/Union member

rsvd
Structure/Union member

voltage
Structure/Union member

class ics.structures.sievb_settings.**sievb_settings**

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

ecu_id
Structure/Union member

idle_wakeup_network_enables_1
Structure/Union member

idle_wakeup_network_enables_2
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_settings
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso_msg_termination
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_parity
Structure/Union member

iso_parity_2
Structure/Union member

iso_tester_pullup_enable
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_analog_enable_2
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

network_enables_2
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

reserved_1
Structure/Union member

reserved_2
Structure/Union member

selected_network
Structure/Union member

text_api
Structure/Union member

uart
Structure/Union member

uart2
Structure/Union member

class ics.structures.sobd2_lc_settings.sobd2_lc_settings

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

can_switch_mode
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
Structure/Union member

canfd4
Structure/Union member

disk
Structure/Union member

ethernet
Structure/Union member

ethernet2

Structure/Union member

flags

Structure/Union member

iso15765_separation_time_offset

Structure/Union member

iso9141_kwp_settings_1

Structure/Union member

iso_msg_termination_1

Structure/Union member

iso_parity_1

Structure/Union member

lin1

Structure/Union member

misc_io_on_report_events

Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

perf_en

Structure/Union member

pwr_man_enable

Structure/Union member

pwr_man_timeout

Structure/Union member

swcan1

Structure/Union member

text_api

Structure/Union member

class ics.structures.sobd2_pro_settings.sobd2_pro_settings

can1

Structure/Union member

can2

Structure/Union member

can3

Structure/Union member

can4

Structure/Union member

can_switch_mode

Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
Structure/Union member

canfd4
Structure/Union member

ethernet
Structure/Union member

ethernet2
Structure/Union member

flags
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

iso9141_kwp_settings_1
Structure/Union member

iso9141_kwp_settings_2
Structure/Union member

iso_msg_termination_1
Structure/Union member

iso_msg_termination_2
Structure/Union member

iso_parity_1
Structure/Union member

iso_parity_2
Structure/Union member

lin1
Structure/Union member

lin2
Structure/Union member

misc_io_analog_enable
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

swcan1
Structure/Union member

text_api
Structure/Union member

class ics.structures.sobd2_sim_settings.sobd2_sim_settings

ain_sample_period
Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

flags
Structure/Union member

iso15765_separation_time_offset
Structure/Union member

misc_io_analog_enable
Structure/Union member

misc_io_initial_ddr
Structure/Union member

misc_io_initial_latch
Structure/Union member

misc_io_on_report_events
Structure/Union member

misc_io_report_period
Structure/Union member

network_enabled_on_boot
Structure/Union member

network_enables
Structure/Union member

perf_en
Structure/Union member

text_api
Structure/Union member

```
class ics.structures.software_update_command.software_update_command
```

commandData

Structure/Union member

commandSizeOrProgress

Structure/Union member

commandType

Structure/Union member

componentIdentifier

Structure/Union member

offset

Structure/Union member

```
class ics.structures.spy_filter_long.spy_filter_long
```

ByteDataLSB

Structure/Union member

ByteDataLength

Structure/Union member

ByteDataMSB

Structure/Union member

ByteDataMaskLSB

Structure/Union member

ByteDataMaskMSB

Structure/Union member

ExpectedLength

Structure/Union member

FrameMaster

Structure/Union member

Header

Structure/Union member

HeaderLength

Structure/Union member

HeaderMask

Structure/Union member

MiscData

Structure/Union member

MiscDataMask

Structure/Union member

NetworkID

Structure/Union member

NodeID

Structure/Union member

Status2Mask

Structure/Union member

Status2Value

Structure/Union member

StatusMask

Structure/Union member

StatusValue

Structure/Union member

bStuff2

Structure/Union member

bUseArbIdRangeFilter

Structure/Union member

class ics.structures.srad_epsilon_settings.srad_epsilon_settings

can1

Structure/Union member

can2

Structure/Union member

canfd1

Structure/Union member

canfd2

Structure/Union member

ethernet

Structure/Union member

ethernet2

Structure/Union member

flags

Structure/Union member

iso15765_separation_time_offset

Structure/Union member

iso9141_kwp_enable_reserved

Structure/Union member

iso9141_kwp_settings

Structure/Union member

iso_msg_termination

Structure/Union member

iso_parity

Structure/Union member

iso_tester_pullup_enable

Structure/Union member

lin1

Structure/Union member

misc_io_analog_enable

Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

network_enables_2

Structure/Union member

network_enables_3

Structure/Union member

perf_en

Structure/Union member

pwr_man_enable

Structure/Union member

pwr_man_timeout

Structure/Union member

switchSettings

Structure/Union member

termination_enables

Structure/Union member

text_api

Structure/Union member

class ics.structures.srad_epsilon_switch_settings.**srad_epsilon_switch_settings**

enablePhy

Structure/Union member

legacy

Structure/Union member

pad

Structure/Union member

phyMode

Structure/Union member

speed

Structure/Union member

spoofMacFlag

Structure/Union member

spoofedMac

Structure/Union member

class ics.structures.srad_galaxy_settings.**srad_galaxy_settings**

ain_sample_period

Structure/Union member

ain_threshold
Structure/Union member

can1
Structure/Union member

can2
Structure/Union member

can3
Structure/Union member

can4
Structure/Union member

can5
Structure/Union member

can6
Structure/Union member

can7
Structure/Union member

can8
Structure/Union member

can_switch_mode
Structure/Union member

canfd1
Structure/Union member

canfd2
Structure/Union member

canfd3
Structure/Union member

canfd4
Structure/Union member

canfd5
Structure/Union member

canfd6
Structure/Union member

canfd7
Structure/Union member

canfd8
Structure/Union member

disk
Structure/Union member

ethernet1
Structure/Union member

ethernet2
Structure/Union member

gPTP

Structure/Union member

hwComLatencyTestEn

Structure/Union member

idle_wakeup_network_enables_1

Structure/Union member

idle_wakeup_network_enables_2

Structure/Union member

idle_wakeup_network_enables_3

Structure/Union member

iso15765_separation_time_offset

Structure/Union member

iso9141_kwp_settings_1

Structure/Union member

iso_9141_kwp_enable_reserved

Structure/Union member

iso_msg_termination_1

Structure/Union member

iso_parity_1

Structure/Union member

lin1

Structure/Union member

logger

Structure/Union member

misc_io_analog_enable

Structure/Union member

misc_io_initial_ddr

Structure/Union member

misc_io_initial_latch

Structure/Union member

misc_io_on_report_events

Structure/Union member

misc_io_report_period

Structure/Union member

network_enabled_on_boot

Structure/Union member

network_enables

Structure/Union member

network_enables_2

Structure/Union member

network_enables_3

Structure/Union member

network_enables_4
Structure/Union member

opEth1
Structure/Union member

opEth10
Structure/Union member

opEth11
Structure/Union member

opEth12
Structure/Union member

opEth2
Structure/Union member

opEth3
Structure/Union member

opEth4
Structure/Union member

opEth5
Structure/Union member

opEth6
Structure/Union member

opEth7
Structure/Union member

opEth8
Structure/Union member

opEth9
Structure/Union member

opEthGen
Structure/Union member

perf_en
Structure/Union member

pwr_man_enable
Structure/Union member

pwr_man_timeout
Structure/Union member

reporting
Structure/Union member

swcan1
Structure/Union member

swcan2
Structure/Union member

text_api
Structure/Union member

timeSyncSettings

Structure/Union member

class ics.structures.srad_gigalog_settings.srad_gigalog_settings

can1

Structure/Union member

can2

Structure/Union member

can3

Structure/Union member

can4

Structure/Union member

can5

Structure/Union member

can6

Structure/Union member

can7

Structure/Union member

can8

Structure/Union member

canfd1

Structure/Union member

canfd2

Structure/Union member

canfd3

Structure/Union member

canfd4

Structure/Union member

canfd5

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serdespoc
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CHAPTER 10

Module Variables

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ics.ics.BPS4000 = 13
ics.ics.BPS50 = 2
ics.ics.BPS500 = 8
ics.ics.BPS5000 = 0
ics.ics.BPS50000 = 3
ics.ics.BPS62 = 3
ics.ics.BPS62500 = 4
ics.ics.BPS666 = 11
ics.ics.BPS71429 = 5
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ics.ics.BPS800 = 9
ics.ics.BPS83 = 4
ics.ics.BPS83333 = 6
ics.ics.BUILD_DATETIME = Oct 27 2022 12:46:26
ics.ics.CANFD_BRS_ENABLED = 2
ics.ics.CANFD_BRS_ENABLED_ISO = 4
ics.ics.CANFD_ENABLED = 1
ics.ics.CANFD_ENABLED_ISO = 3
ics.ics.CANFD_SETTINGS_SIZE = 10
ics.ics.CANNODE_STATUS_COREMINI_IS_RUNNING = 1
ics.ics.CANNODE_STATUS_IN_BOOTLOADER = 2
ics.ics.CANTERM_SETTINGS_SIZE = 6
ics.ics.CAN_BPS10000 = 17
ics.ics.CAN_BPS5000 = 14
ics.ics.CAN_BPS6667 = 15
ics.ics.CAN_BPS8000 = 16
ics.ics.CAN_SETTINGS_SIZE = 12
ics.ics.DEVICECOUNT_FOR_EXPLORER = 42
ics.ics.DISABLE = 1
ics.ics.DISK_SETTINGS_SIZE = 14
ics.ics.DISK_STATUS_FLAG_INITIALIZED = 2
ics.ics.DISK_STATUS_FLAG_PRESENT = 1
ics.ics.DISK_STRUCTURE_FLAG_FULL_FORMAT = 1
ics.ics.ETHERNET10G_SETTINGS_SIZE = 24
ics.ics.ETHERNET_SETTINGS10G_FLAG_AUTO_NEG = 2
ics.ics.ETHERNET_SETTINGS10G_FLAG_COMM_IN_USE = -2147483648
ics.ics.ETHERNET_SETTINGS10G_FLAG_DEVICE_HOSTING_ENABLE = 16
ics.ics.ETHERNET_SETTINGS10G_FLAG_FULL_DUPLEX = 1
ics.ics.ETHERNET_SETTINGS10G_FLAG_RTSP_ENABLE = 8
ics.ics.ETHERNET_SETTINGS10G_FLAG_TCPIP_ENABLE = 4
ics.ics.ETHERNET_SETTINGS2_FLAG_AUTO_NEG = 2
ics.ics.ETHERNET_SETTINGS2_FLAG_COMM_IN_USE = 128
ics.ics.ETHERNET_SETTINGS2_FLAG_CONFIG_NOT_ALLOWED = 32
ics.ics.ETHERNET_SETTINGS2_FLAG_DEVICE_HOSTING_ENABLE = 16
ics.ics.ETHERNET_SETTINGS2_FLAG_FULL_DUPLEX = 1
ics.ics.ETHERNET_SETTINGS2_FLAG_RTSP_ENABLE = 8
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ics.ics.ETHERNET_SETTINGS2_FLAG_TCPIP_ENABLE = 4
ics.ics.ETHERNET_SETTINGS2_SIZE = 16
ics.ics.ETHERNET_SETTINGS_SIZE = 8
ics.ics.EXTENDED_RESPONSE_INVALID_COMMAND = -1
ics.ics.EXTENDED_RESPONSE_INVALID_PARAMETER = -5
ics.ics.EXTENDED_RESPONSE_INVALID_STATE = -2
ics.ics.EXTENDED_RESPONSE_OK = 0
ics.ics.EXTENDED_RESPONSE_OPERATION_FAILED = -3
ics.ics.EXTENDED_RESPONSE_OPERATION_PENDING = -4
ics.ics.FAST_MODE = 3
ics.ics.GENERIC_API_DATA_BUFFER_SIZE = 513
ics.ics.GET_SUPPORTED_FEATURES_COMMAND_VERSION = 1
ics.ics.GLOBAL_SETTINGS_SIZE = 942
ics.ics.GS_VERSION = 5
ics.ics.HARDWARE_TIMESTAMP_ID_AVT_716 = 2
ics.ics.HARDWARE_TIMESTAMP_ID_AVT_717 = 5
ics.ics.HARDWARE_TIMESTAMP_ID_DOUBLE_SEC = 7
ics.ics.HARDWARE_TIMESTAMP_ID_NEORED_10NS = 10
ics.ics.HARDWARE_TIMESTAMP_ID_NEORED_10US = 8
ics.ics.HARDWARE_TIMESTAMP_ID_NEORED_25NS = 9
ics.ics.HARDWARE_TIMESTAMP_ID_NEOVI = 4
ics.ics.HARDWARE_TIMESTAMP_ID_NI_CAN = 3
ics.ics.HARDWARE_TIMESTAMP_ID_NONE = 0
ics.ics.HARDWARE_TIMESTAMP_ID_VSI = 1
ics.ics.HW_ETH_SETTINGS_SIZE = 20
ics.ics.ISO15765_2_NETWORK_HSCAN = 1
ics.ics.ISO15765_2_NETWORK_HSCAN2 = 4
ics.ics.ISO15765_2_NETWORK_HSCAN3 = 8
ics.ics.ISO15765_2_NETWORK_HSCAN4 = 20
ics.ics.ISO15765_2_NETWORK_HSCAN5 = 24
ics.ics.ISO15765_2_NETWORK_HSCAN6 = 28
ics.ics.ISO15765_2_NETWORK_HSCAN7 = 32
ics.ics.ISO15765_2_NETWORK_MSCAN = 2
ics.ics.ISO15765_2_NETWORK_SWCAN = 16
ics.ics.ISO15765_2_NETWORK_SWCAN2 = 36
ics.ics.ISO9141_KEYWORD2000_SETTINGS_SIZE = 114
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ics.ics.ISO9141_KEYWORD2000__INIT_STEP_SIZE = 6
ics.ics.J1708_SETTINGS_SIZE = 2
ics.ics.JUPITER_PTP_ROLE_DISABLED = 0
ics.ics.JUPITER_PTP_ROLE_MASTER = 1
ics.ics.JUPITER_PTP_ROLE_SLAVE = 2
ics.ics.LINK_SPEED_100MBPS_FULL_DUPLEX = 3
ics.ics.LINK_SPEED_100MBPS_HALF_DUPLEX = 4
ics.ics.LINK_SPEED_10MBPS_FULL_DUPLEX = 5
ics.ics.LINK_SPEED_10MBPS_HALF_DUPLEX = 6
ics.ics.LINK_SPEED_1GBPS_FULL_DUPLEX = 1
ics.ics.LINK_SPEED_1GBPS_HALF_DUPLEX = 2
ics.ics.LINK_SPEED_AUTO_NEGOTIATION = 0
ics.ics.LINK_SPEED_COUNT = 7
ics.ics.LINUX_BOOT_ALLOWED = 1
ics.ics.LINUX_CONFIG_PORT_ETH_01 = 1
ics.ics.LINUX_CONFIG_PORT_ETH_02 = 2
ics.ics.LINUX_CONFIG_PORT_NONE = 0
ics.ics.LIN_SETTINGS_SIZE = 10
ics.ics.LISTEN_ALL = 7
ics.ics.LISTEN_ONLY = 3
ics.ics.LOGGER_SETTINGS_SIZE = 4
ics.ics.LOOPBACK = 2
ics.ics.MAIN_VNET = 1
ics.ics.MAX_NUMBYTES_PHYSETTINGS = 512
ics.ics.MAX_PHY_REG_PKT_ENTRIES = 128
ics.ics.MAX_PHY_SETTINGS_STRUCT = 128
ics.ics.MAX_REPORTED_VERSIONS = 16
ics.ics.MAX_VL_FORWARDING_ENTRIES = 1024
ics.ics.MAX_VL_POLICING_ENTRIES = 1024
ics.ics.NEODEVICE_ANY_ION = 262144
ics.ics.NEODEVICE_ANY_PLASMA = 4096
ics.ics.NEODEVICE_BLUE = 1
ics.ics.NEODEVICE_CMPROBE = 8388608
ics.ics.NEODEVICE_CT_OBD = 32768
ics.ics.NEODEVICE_DONT_REUSE0 = 8192
ics.ics.NEODEVICE_DONT_REUSE1 = 65536
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ics.ics.NEODEVICE_DONT_REUSE2 = 131072
ics.ics.NEODEVICE_DONT_REUSE3 = 1048576
ics.ics.NEODEVICE_DW_VCAN = 4
ics.ics.NEODEVICE_ECU = 128
ics.ics.NEODEVICE_ECU22 = 27
ics.ics.NEODEVICE_ECUCHIP_UART = 2048
ics.ics.NEODEVICE_ECU_AVB = 2
ics.ics.NEODEVICE_EEVB = 16777216
ics.ics.NEODEVICE_ETHER_BADGE = 22
ics.ics.NEODEVICE_FIRE = 8
ics.ics.NEODEVICE_FIRE2 = 67108864
ics.ics.NEODEVICE_FIRE2_REDLINE = 21
ics.ics.NEODEVICE_FIRE3 = 15
ics.ics.NEODEVICE_FLEX = 134217728
ics.ics.NEODEVICE_GIGASTAR = 19
ics.ics.NEODEVICE_IEVB = 256
ics.ics.NEODEVICE_ION = 262144
ics.ics.NEODEVICE_NEOANALOG = 16384
ics.ics.NEODEVICE_NEOECU12 = 12
ics.ics.NEODEVICE_NEOECUCHIP = 256
ics.ics.NEODEVICE_NEW_DEVICE_58 = 31
ics.ics.NEODEVICE_NEW_DEVICE_59 = 33
ics.ics.NEODEVICE_OBD2_DEV = 26
ics.ics.NEODEVICE_OBD2_LC = 13
ics.ics.NEODEVICE_OBD2_PRO = 1024
ics.ics.NEODEVICE_OBD2_SIM = -2147483648
ics.ics.NEODEVICE_OBD2_SIM_DOIP = 25
ics.ics.NEODEVICE_PENDANT = 512
ics.ics.NEODEVICE_PLASMA = 4096
ics.ics.NEODEVICE_RADEPSILON = 24
ics.ics.NEODEVICE_RADEPSILON_EXPRESS = 29
ics.ics.NEODEVICE_RADEPSILON_T = 28
ics.ics.NEODEVICE_RADGALAXY = 268435456
ics.ics.NEODEVICE_RADGIGALOG = 6
ics.ics.NEODEVICE_RADIO_CANHUB = 11
ics.ics.NEODEVICE_RADJUPITER = 17
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ics.ics.NEODEVICE_RADMOON2 = 5
ics.ics.NEODEVICE_RADMOON3 = 35
ics.ics.NEODEVICE_RADPLUTO = 9
ics.ics.NEODEVICE_RADPROXIMA = 30
ics.ics.NEODEVICE_RADSTAR = 524288
ics.ics.NEODEVICE_RADSTAR2 = 536870912
ics.ics.NEODEVICE_RADSUPERMOON = 3
ics.ics.NEODEVICE_RAD_A2B = 23
ics.ics.NEODEVICE_RAD_BMS = 34
ics.ics.NEODEVICE_RAD_MOON_DUO = 14
ics.ics.NEODEVICE_RED = 64
ics.ics.NEODEVICE_RED2 = 20
ics.ics.NEODEVICE_UNKNOWN = 0
ics.ics.NEODEVICE_VCAN3 = 16
ics.ics.NEODEVICE_VCAN41 = 7
ics.ics.NEODEVICE_VCAN42 = 4194304
ics.ics.NEODEVICE_VCAN42_EL = 10
ics.ics.NEODEVICE_VCAN44 = 2097152
ics.ics.NEODEVICE_VCAN4_IND = 18
ics.ics.NEODEVICE_VCANRF = 33554432
ics.ics.NEODEVICE_VIVIDCAN = 1073741824
ics.ics.NEOVI6_VCAN_TIMESTAMP_1 = 1e-06
ics.ics.NEOVI6_VCAN_TIMESTAMP_2 = 0.065536
ics.ics.NEOVIPRO_VCAN_TIMESTAMP_1 = 1e-06
ics.ics.NEOVIPRO_VCAN_TIMESTAMP_2 = 0.065536
ics.ics.NEOVI_3G_MAX_SETTINGS_SIZE = 942
ics.ics.NEOVI_COMMTYPE_FIRE_USB = 5
ics.ics.NEOVI_COMMTYPE_RS232 = 0
ics.ics.NEOVI_COMMTYPE_TCPIP = 3
ics.ics.NEOVI_COMMTYPE_USB_BULK = 1
ics.ics.NEOVI_RED_TIMESTAMP_1_10NS = 1e-08
ics.ics.NEOVI_RED_TIMESTAMP_1_25NS = 2.5e-08
ics.ics.NEOVI_RED_TIMESTAMP_2_10NS = 429.4967296
ics.ics.NEOVI_RED_TIMESTAMP_2_25NS = 107.3741824
ics.ics.NEOVI_TIMESTAMP_1 = 1.6e-06
ics.ics.NEOVI_TIMESTAMP_2 = 0.1048576
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ics.ics.NEO_CFG_MPIC_HS_CAN_CNF1 = 522
ics.ics.NEO_CFG_MPIC_HS_CAN_CNF2 = 521
ics.ics.NEO_CFG_MPIC_HS_CAN_CNF3 = 520
ics.ics.NEO_CFG_MPIC_HS_CAN_MODE = 566
ics.ics.NEO_CFG_MPIC_LSFT_CAN_CNF1 = 558
ics.ics.NEO_CFG_MPIC_LSFT_CAN_CNF2 = 557
ics.ics.NEO_CFG_MPIC_LSFT_CAN_CNF3 = 556
ics.ics.NEO_CFG_MPIC_MS_CAN_CNF1 = 534
ics.ics.NEO_CFG_MPIC_MS_CAN_CNF2 = 533
ics.ics.NEO_CFG_MPIC_MS_CAN_CNF3 = 532
ics.ics.NEO_CFG_MPIC_SW_CAN_CNF1 = 546
ics.ics.NEO_CFG_MPIC_SW_CAN_CNF2 = 545
ics.ics.NEO_CFG_MPIC_SW_CAN_CNF3 = 544
ics.ics.NETID_3G_APP_SIGNAL_STATUS = 56
ics.ics.NETID_3G_FB_STATUS = 55
ics.ics.NETID_3G_LOGGING_OVERFLOW = 59
ics.ics.NETID_3G_READ_DATALINK_CM_RX_MSG = 58
ics.ics.NETID_3G_READ_DATALINK_CM_TX_MSG = 57
ics.ics.NETID_3G_READ_SETTINGS_EX = 60
ics.ics.NETID_3G_RESET_STATUS = 54
ics.ics.NETID_A2B_01 = 522
ics.ics.NETID_A2B_02 = 523
ics.ics.NETID_AUTOSAR = 515
ics.ics.NETID_AUX = 7
ics.ics.NETID_CAN_SWITCH = 526
ics.ics.NETID_CGI = 53
ics.ics.NETID_DATA_TO_HOST = 70
ics.ics.NETID_DEVICE = 0
ics.ics.NETID_DEVICE_STATUS = 513
ics.ics.NETID_ETHERNET = 93
ics.ics.NETID_ETHERNET2 = 520
ics.ics.NETID_ETHERNET3 = 524
ics.ics.NETID_ETHERNET_DAQ = 69
ics.ics.NETID_ETHERNET_TX_WRAP = 521
ics.ics.NETID_FLEXRAY = 85
ics.ics.NETID_FLEXRAY1A = 80
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ics.ics.NETID_FLEXRAY1B = 81
ics.ics.NETID_FLEXRAY2 = 86
ics.ics.NETID_FLEXRAY2A = 82
ics.ics.NETID_FLEXRAY2B = 83
ics.ics.NETID_FORDSCP = 5
ics.ics.NETID_FORWARDED_MESSAGE = 516
ics.ics.NETID_GMFSA = 94
ics.ics.NETID_HSCAN = 1
ics.ics.NETID_HSCAN2 = 42
ics.ics.NETID_HSCAN3 = 44
ics.ics.NETID_HSCAN4 = 61
ics.ics.NETID_HSCAN5 = 62
ics.ics.NETID_HSCAN6 = 96
ics.ics.NETID_HSCAN7 = 97
ics.ics.NETID_HW_COM_LATENCY_TEST = 512
ics.ics.NETID_I2C1 = 88
ics.ics.NETID_I2C2 = 517
ics.ics.NETID_I2C3 = 518
ics.ics.NETID_I2C4 = 519
ics.ics.NETID_INVALID = 65535
ics.ics.NETID_ISM_LOGGER = 525
ics.ics.NETID_ISO = 9
ics.ics.NETID_ISO14230 = 15
ics.ics.NETID_ISO2 = 14
ics.ics.NETID_ISO3 = 41
ics.ics.NETID_ISO4 = 47
ics.ics.NETID_ISOPIC = 10
ics.ics.NETID_J1708 = 6
ics.ics.NETID_JVPW = 8
ics.ics.NETID_LIN = 16
ics.ics.NETID_LIN2 = 48
ics.ics.NETID_LIN3 = 49
ics.ics.NETID_LIN4 = 50
ics.ics.NETID_LIN5 = 84
ics.ics.NETID_LIN6 = 98
ics.ics.NETID_LSFTCAN = 4
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ics.ics.NETID_LSFTCAN2 = 99
ics.ics.NETID_MAIN51 = 11
ics.ics.NETID_MAX = 100
ics.ics.NETID_MOST = 51
ics.ics.NETID_MOST150 = 92
ics.ics.NETID_MOST25 = 90
ics.ics.NETID_MOST50 = 91
ics.ics.NETID_MSCAN = 2
ics.ics.NETID_OP_ETHERNET1 = 17
ics.ics.NETID_OP_ETHERNET10 = 78
ics.ics.NETID_OP_ETHERNET11 = 79
ics.ics.NETID_OP_ETHERNET12 = 87
ics.ics.NETID_OP_ETHERNET2 = 18
ics.ics.NETID_OP_ETHERNET3 = 19
ics.ics.NETID_OP_ETHERNET4 = 45
ics.ics.NETID_OP_ETHERNET5 = 46
ics.ics.NETID_OP_ETHERNET6 = 73
ics.ics.NETID_OP_ETHERNET7 = 75
ics.ics.NETID_OP_ETHERNET8 = 76
ics.ics.NETID_OP_ETHERNET9 = 77
ics.ics.NETID_RED = 12
ics.ics.NETID_RED_APP_ERROR = 52
ics.ics.NETID_RED_VBAT = 74
ics.ics.NETID_RS232 = 63
ics.ics.NETID_SCI = 13
ics.ics.NETID_SPI1 = 72
ics.ics.NETID_SWCAN = 3
ics.ics.NETID_SWCAN2 = 68
ics.ics.NETID_TCP = 95
ics.ics.NETID_TEXTAPI_TO_HOST = 71
ics.ics.NETID_UART = 64
ics.ics.NETID_UART2 = 65
ics.ics.NETID_UART3 = 66
ics.ics.NETID_UART4 = 67
ics.ics.NETID_UDP = 514
ics.ics.NETID_WBMS = 532
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ics.ics.NORMAL = 0
ics.ics.NORMAL_MODE = 2
ics.ics.NO_CANFD = 0
ics.ics.NUM_DEVICE_FEATURE_BITFIELDS = 1
ics.ics.NUM_VALID_DEVICE_FEATURES = 16
ics.ics.OPETH_FUNC_MEDIACONVERTER = 1
ics.ics.OPETH_FUNC_RAW_MEDIA_CONVERTER = 3
ics.ics.OPETH_FUNC_RAW_MEDIA_CONVERTER2 = 4
ics.ics.OPETH_FUNC_RAW_MEDIA_CONVERTER2_LOW_LATENCY = 5
ics.ics.OPETH_FUNC_TAP = 0
ics.ics.OPETH_FUNC_TAP_LOW_LATENCY = 2
ics.ics.OPETH_LINK_AUTO = 0
ics.ics.OPETH_LINK_MASTER = 1
ics.ics.OPETH_LINK_SLAVE = 2
ics.ics.OPETH_MAC_SPOOF_DST_ADDR = 0
ics.ics.OPETH_MAC_SPOOF_SRC_ADDR = 1
ics.ics.OP_ETH_GENERAL_SETTINGS_SIZE = 20
ics.ics.OP_ETH_SETTINGS_SIZE = 16
ics.ics.PHYREG_BOTH = 2
ics.ics.PHYREG_FAILURE = 1
ics.ics.PHYREG_INVALID_MDIO_BUS_INDEX = 2
ics.ics.PHYREG_INVALID_PHY_ADDR = 3
ics.ics.PHYREG_READ = 0
ics.ics.PHYREG_RESERVED0 = 4
ics.ics.PHYREG_RESERVED1 = 5
ics.ics.PHYREG_RESERVED2 = 6
ics.ics.PHYREG_RESERVED3 = 7
ics.ics.PHYREG_SUCCESS = 0
ics.ics.PHYREG_WRITE = 1
ics.ics.PHY_REG_PKT_VERSION = 1
ics.ics.PLASMA_SLAVE1_OFFSET = 100
ics.ics.PLASMA_SLAVE1_OFFSET_RANGE2 = 4608
ics.ics.PLASMA_SLAVE2_OFFSET = 200
ics.ics.PLASMA_SLAVE2_OFFSET_RANGE2 = 8704
ics.ics.PLASMA_SLAVE3_OFFSET_RANGE2 = 12800
ics.ics.PLASMA_SLAVE_NUM = 51
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ics.ics.PLUTO_MAX_FORWARDING_ENTRIES = 13
ics.ics.PLUTO_MAX_L2_ADDRESS_LOOKUP = 1024
ics.ics.PLUTO_MAX_L2_POLICING = 45
ics.ics.PLUTO_MAX_MAC_CONFIG_ENTRIES = 5
ics.ics.PLUTO_MAX_RETAGGING_ENTRIES = 32
ics.ics.PLUTO_MAX_VLAN_LOOKUP = 4096
ics.ics.PLUTO_NUM_PORTS = 5
ics.ics.PLUTO_NUM_PRIORITY = 8
ics.ics.RADEPSILON_MAX_PHY = 18
ics.ics.RADJUPITER_NUM_PORTS = 8
ics.ics.RADMOONDUO_CONVERTER_SETTINGS_SIZE = 16
ics.ics.RAD_GPTP_AND_TAP_SETTINGS_SIZE = 40
ics.ics.RAD_GPTP_SETTINGS_SIZE = 36
ics.ics.RAD_REPORTING_SETTINGS_FLAG_AIN1 = 256
ics.ics.RAD_REPORTING_SETTINGS_FLAG_FAN_SPEED_ENABLE = 1024
ics.ics.RAD_REPORTING_SETTINGS_FLAG_INT_GPS_ENABLE = 4
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MIC2_GPS_ENABLE = 2
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MIC2_GPS_ENABLE2 = 8
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MISC1_DIN = 16
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MISC1_PWMIN = 64
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MISC2_DIN = 32
ics.ics.RAD_REPORTING_SETTINGS_FLAG_MISC2_PWMIN = 128
ics.ics.RAD_REPORTING_SETTINGS_FLAG_SERDES_ENABLE = 512
ics.ics.RAD_REPORTING_SETTINGS_FLAG_TEMP_ENABLE = 1
ics.ics.RAD_REPORTING_SETTINGS_SIZE = 16
ics.ics.REGISTER_BY_SERIAL = 16
ics.ics.REPORT_ON_GPS = 15
ics.ics.REPORT_ON_KLINE = 9
ics.ics.REPORT_ON_LED1 = 7
ics.ics.REPORT_ON_LED2 = 8
ics.ics.REPORT_ON_MISC1 = 1
ics.ics.REPORT_ON_MISC2 = 2
ics.ics.REPORT_ON_MISC3 = 3
ics.ics.REPORT_ON_MISC3_AIN = 10
ics.ics.REPORT_ON_MISC4 = 4
ics.ics.REPORT_ON_MISC4_AIN = 11
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ics.ics.REPORT_ON_MISC5 = 5
ics.ics.REPORT_ON_MISC5_AIN = 12
ics.ics.REPORT_ON_MISC6 = 6
ics.ics.REPORT_ON_MISC6_AIN = 13
ics.ics.REPORT_ON_PERIODIC = 0
ics.ics.RESISTOR_OFF = 1
ics.ics.RESISTOR_ON = 0
ics.ics.SCRIPT_LOCATION_EMMC = 6
ics.ics.SCRIPT_LOCATION_FLASH_MEM = 0
ics.ics.SCRIPT_LOCATION_INTERNAL_FLASH = 2
ics.ics.SCRIPT_LOCATION_SDCARD = 1
ics.ics.SCRIPT_LOCATION_VCAN3_MEM = 4
ics.ics.SCRIPT_STATUS_RUNNING = 1
ics.ics.SCRIPT_STATUS_STOPPED = 0
ics.ics.SERDESCAM_MODE_COUNT = 4
ics.ics.SERDESCAM_MODE_CUSTOM = 3
ics.ics.SERDESCAM_MODE_LOG_ONLY = 2
ics.ics.SERDESCAM_MODE_SPLITTER = 1
ics.ics.SERDESCAM_MODE_TAP_REPEATER = 0
ics.ics.SERDESCAM_PIXEL_BIT_POS_0 = 0
ics.ics.SERDESCAM_PIXEL_BIT_POS_1 = 1
ics.ics.SERDESCAM_PIXEL_BIT_POS_2 = 2
ics.ics.SERDESCAM_PIXEL_BIT_POS_3 = 3
ics.ics.SERDESCAM_SETTINGS_FLAG_AUTO_DET_RES_ENABLE = 4
ics.ics.SERDESCAM_SETTINGS_FLAG_CONFIG_ENABLE = 8
ics.ics.SERDESCAM_SETTINGS_FLAG_ENABLE = 1
ics.ics.SERDESCAM_SETTINGS_FLAG_LOGGING_ENABLE = 16
ics.ics.SERDESCAM_SETTINGS_FLAG_RTSP_ENABLE = 2
ics.ics.SERDESCAM_SETTINGS_FLAG_TX0_ENABLE = 32
ics.ics.SERDESCAM_SETTINGS_FLAG_TX1_ENABLE = 64
ics.ics.SERDESCAM_SETTINGS_FLAG_TX2_ENABLE = 128
ics.ics.SERDESCAM_SETTINGS_FLAG_TX3_ENABLE = 256
ics.ics.SERDESCAM_SETTINGS_SIZE = 32
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_BGGR_10LE_PACKED = 19
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_BGGR_12LE_PACKED = 20
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_BGGR_16BE = 22
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ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_BGGR_16LE = 21
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_BGGR_8 = 4
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GBRG_10LE_PACKED = 74
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GBRG_12LE_PACKED = 75
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GBRG_16BE = 77
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GBRG_16LE = 76
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GBRG_8 = 73
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GRBG_10LE_PACKED = 82
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GRBG_12LE_PACKED = 83
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GRBG_16BE = 85
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GRBG_16LE = 84
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_GRBG_8 = 81
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_RGGB_10LE_PACKED = 66
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_RGGB_12LE_PACKED = 67
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_RGGB_16BE = 69
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_RGGB_16LE = 68
ics.ics.SERDESCAM_VIDEO_FORMAT_BAYER_RGGB_8 = 65
ics.ics.SERDESCAM_VIDEO_FORMAT_COUNT = 89
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_BGGR_10LE_PACKED = 51
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_BGGR_12LE_PACKED = 52
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_BGGR_8 = 50
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GBRG_10LE_PACKED = 79
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GBRG_12LE_PACKED = 80
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GBRG_8 = 78
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GRBG_10LE_PACKED = 87
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GRBG_12LE_PACKED = 88
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_GRBG_8 = 86
ics.ics.SERDESCAM_VIDEO_FORMAT_CSI2_BAYER_RGGB_10LE_PACKED = 71
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ics.ics.SPY_STATUS2_END_OF_LONG_MESSAGE = 1048576
ics.ics.SPY_STATUS2_ERROR_FRAME = 131072
ics.ics.SPY_STATUS2_ETHERNET_CRC_ERROR = 2097152
ics.ics.SPY_STATUS2_ETHERNET_FCS_VERIFIED = 268435456
ics.ics.SPY_STATUS2_ETHERNET_FRAME_TOO_SHORT = 4194304
ics.ics.SPY_STATUS2_ETHERNET_MANUALFCS_ENABLED = 134217728
ics.ics.SPY_STATUS2_ETHERNET_NO_PADDING = 16777216
ics.ics.SPY_STATUS2_ETHERNET_PREEMPTION_ENABLED = 33554432
ics.ics.SPY_STATUS2_ETHERNET_UPDATE_CHECKSUMS = 67108864
ics.ics.SPY_STATUS2_FLEXRAY_NO_CRC = 33554432
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ics.ics.SPY_STATUS2_FLEXRAY_NO_HEADERCRC = 67108864
ics.ics.SPY_STATUS2_FLEXRAY_TX_AB = 2097152
ics.ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_A = 4194304
ics.ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_B = 8388608
ics.ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_MATCH = 16777216
ics.ics.SPY_STATUS2_GLOBAL_CHANGE = 65536
ics.ics.SPY_STATUS2_HAS_VALUE = 1
ics.ics.SPY_STATUS2_HIGH_VOLTAGE = 4
ics.ics.SPY_STATUS2_I2C_DIR_READ = 8388608
ics.ics.SPY_STATUS2_I2C_ERR_NACK = 4194304
ics.ics.SPY_STATUS2_I2C_ERR_TIMEOUT = 2097152
ics.ics.SPY_STATUS2_I2C_NODE_FAULT = 4194304
ics.ics.SPY_STATUS2_ISO_FRAME_ERROR = 134217728
ics.ics.SPY_STATUS2_ISO_OVERFLOW_ERROR = 268435456
ics.ics.SPY_STATUS2_ISO_PARITY_ERROR = 536870912
ics.ics.SPY_STATUS2_LIN_ERR_MSG_ID_PARITY = 67108864
ics.ics.SPY_STATUS2_LIN_ERR_RX_BREAK_NOT_0 = 2097152
ics.ics.SPY_STATUS2_LIN_ERR_RX_BREAK_TOO_SHORT = 4194304
ics.ics.SPY_STATUS2_LIN_ERR_RX_DATA_GREATER_8 = 16777216
ics.ics.SPY_STATUS2_LIN_ERR_RX_SYNC_NOT_55 = 8388608
ics.ics.SPY_STATUS2_LIN_ERR_TX_RX_MISMATCH = 33554432
ics.ics.SPY_STATUS2_LIN_ID_FRAME_ERROR = 268435456
ics.ics.SPY_STATUS2_LIN_NO_SLAVE_DATA = -2147483648
ics.ics.SPY_STATUS2_LIN_SLAVE_BYTE_ERROR = 536870912
ics.ics.SPY_STATUS2_LIN_SYNC_FRAME_ERROR = 134217728
ics.ics.SPY_STATUS2_LONG_MESSAGE = 8
ics.ics.SPY_STATUS2_MOST_CHANGED_PAR = -2147483648
ics.ics.SPY_STATUS2_MOST_CONTROL_DATA = 16777216
ics.ics.SPY_STATUS2_MOST_I2S_DUMP = 134217728
ics.ics.SPY_STATUS2_MOST_LOW_LEVEL = 8388608
ics.ics.SPY_STATUS2_MOST_MHP_CONTROL_DATA = 67108864
ics.ics.SPY_STATUS2_MOST_MHP_USER_DATA = 33554432
ics.ics.SPY_STATUS2_MOST_MOST150 = 1073741824
ics.ics.SPY_STATUS2_MOST_MOST50 = 536870912
ics.ics.SPY_STATUS2_MOST_PACKET_DATA = 2097152
ics.ics.SPY_STATUS2_MOST_STATUS = 4194304
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ics.ics.SPY_STATUS2_MOST_TOO_SHORT = 268435456
ics.ics.SPY_STATUS2_RX_TIMEOUT_ERROR = 1073741824
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ics.ics.SPY_STATUS2_WBMS_NODE_DISCONNECTED = 2097152
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ics.ics.SPY_STATUS3_CANFD_ESI = 1
ics.ics.SPY_STATUS3_CANFD_FDF = 8
ics.ics.SPY_STATUS3_CANFD_IDE = 2
ics.ics.SPY_STATUS3_CANFD_RTR = 4
ics.ics.SPY_STATUS3_LIN_JUST_BREAK_SYNC = 1
ics.ics.SPY_STATUS3_LIN_ONLY_UPDATE_SLAVE_TABLE_ONCE = 4
ics.ics.SPY_STATUS3_LIN_SLAVE_DATA_TOO_SHORT = 2
ics.ics.SPY_STATUS_A2B_CONTROL = 524288
ics.ics.SPY_STATUS_A2B_MONITOR = 536870912
ics.ics.SPY_STATUS_A2B_SCF_VALID_WAITING = 8
ics.ics.SPY_STATUS_A2B_UPSTREAM = 1073741824
ics.ics.SPY_STATUS_ANALOG_DIGITAL_INPUT = 16777216
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ics.ics.SPY_STATUS_BUS_RECOVERED = 1024
ics.ics.SPY_STATUS_BUS_SHORTED_GND = 4096
ics.ics.SPY_STATUS_BUS_SHORTED_PLUS = 2048
ics.ics.SPY_STATUS_CANFD = 536870912
ics.ics.SPY_STATUS_CAN_BUS_OFF = 512
ics.ics.SPY_STATUS_CAN_ERROR_PASSIVE = 32
ics.ics.SPY_STATUS_CHECKSUM_ERROR = 8192
ics.ics.SPY_STATUS_COMM_IN_OVERFLOW = 65536
ics.ics.SPY_STATUS_CRC_ERROR = 16
ics.ics.SPY_STATUS_EXPECTED_LEN_MISMATCH = 131072
ics.ics.SPY_STATUS_EXTENDED = -2147483648
ics.ics.SPY_STATUS_FLEXRAY_PDU = 268435456
ics.ics.SPY_STATUS_FLEXRAY_PDU_NO_UPDATE_BIT = 8
ics.ics.SPY_STATUS_FLEXRAY_PDU_UPDATE_BIT_SET = 1073741824
ics.ics.SPY_STATUS_GLOBAL_ERR = 1
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ics.ics.SPY_STATUS_GPS_DATA = 8388608
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ics.ics.SPY_STATUS_HIGH_SPEED = 1073741824
ics.ics.SPY_STATUS_INCOMPLETE_FRAME = 64
ics.ics.SPY_STATUS_INIT_MESSAGE = 536870912
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ics.ics.SPY_STATUS_REMOTE_FRAME = 8
ics.ics.SPY_STATUS_TEST_TRIGGER = 2097152
ics.ics.SPY_STATUS_TEXT_COMMENT = 33554432
ics.ics.SPY_STATUS_TX_MSG = 2
ics.ics.SPY_STATUS_TX_NOMATCH = 32768
ics.ics.SPY_STATUS_UNDEFINED_ERROR = 256
ics.ics.SPY_STATUS_VSI_IFR_CRC_BIT = 268435456
ics.ics.SPY_STATUS_VSI_TX_UNDERRUN = 134217728
ics.ics.SPY_STATUS_XTD_FRAME = 4
ics.ics.SWCAN_AUTOSWITCH_DISABLED = 0
ics.ics.SWCAN_AUTOSWITCH_DISABLED_RESISTOR_ENABLED = 3
ics.ics.SWCAN_AUTOSWITCH_NO_RESISTOR = 1
ics.ics.SWCAN_AUTOSWITCH_WITH_RESISTOR = 2
ics.ics.SWCAN_SETTINGS_SIZE = 14
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