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# **python\_ics Documentation**

***Release 4.2***

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Intrepid Control Systems, Inc. open source Python module for interfacing to Intrepid hardware. Basic knowledge of using and installing Python modules is assumed. Please see <https://docs.python.org/3/installing/index.html> for documentation on how to install Python modules.



# CHAPTER 1

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## Versioning Information

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Minor differences can occur between different icsnVC40.h versions. These differences are usually just structures and constant differences. Below is a list of how the python\_ics version correlates to the icsnVC40.h version:

### 1.1 v802

```
pip install 'python_ics>=2.0,<3.0' --force-reinstall
```

**Note:** Refer to platform specific installation if not on Windows

### 1.2 v803

```
pip install 'python_ics>=3.0,<4.0' --force-reinstall
```

**Note:** Refer to platform specific installation if not on Windows

### 1.3 v900

```
pip install 'python_ics>=4.0,<5.0' --force-reinstall
```

**Note:** Refer to platform specific installation if not on Windows



# CHAPTER 2

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## Installation on Windows

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PyPi provides binary packages for Windows. You can simply install the `python_ics` module by running the following command:

```
pip install python_ics
```

**Note:** `pip.exe` is usually located under the `Scripts` directory under the Python installation directory.

### 2.1 Building from source

Building from source on windows is not usually need so it won't really be covered here in detail. As a starting point you'll need to match the compiler version used to build the official Python binaries (MSVC). If the build environment is setup correctly, you should be able to run `python setup.py build` like usual.

### 2.2 Intrepid icsneo40 Library

`python_ics` module looks for `icsneo40.dll` in the normal windows DLL search paths. The module will throw an exception if its not found.



# CHAPTER 3

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## Installation on Linux

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python\_ics does not provide binaries for linux distributions so we will have to compile from source. This can be easily achieved by utilizing Python's PIP. First we need to make sure we have some base packages installed.

### 3.1 Fedora Dependencies (FC28)

```
sudo dnf install redhat-rpm-config gcc g++ python3-devel
```

### 3.2 Debian/Ubuntu Dependencies

```
sudo apt install build-essential python-dev
```

### 3.3 Others (Required dependencies)

- GCC
- G++
- Python Development packages (We Need to link to Python.h)

### 3.4 Installation

After dependencies are installed we can run the following pip command:

```
pip install python_ics
```

**Note:** A lot of distributions have Python 2 and 3 installed side by side. As of this writing without a version suffix the commands still default to version 2 of the Python binaries. In order to utilize the Python 3 binaries you must append a 3 after the binary names (python3 and pip3 instead of just python and pip).

## 3.5 Intrepid libicsneoapi.so Library

Please see <https://github.com/intrepidcs/icsneoapi> for more details.

# CHAPTER 4

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## Getting Started

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Please see [https://github.com/intrepidcs/python\\_ics/tree/master/examples](https://github.com/intrepidcs/python_ics/tree/master/examples) for simple examples on how to use this module. Most function documentation has a simple example on how its intended to be used. Every function was designed to be as close as possible to it's C counterpart unless it was deemed to make the function more pythonic in nature.

For those experienced with the C API `ics.open_device (icsneoOpenNeoDevice())` behavior has been changed the most (no parameters makes it auto utilize `ics.find_devices (icsneoFindNeoDevices())` and open the first device). Also since python is a object oriented language the module utilizes this and auto cleans up device handles when going out of scope so there is usually no need to call `ics.close_device()`.



# CHAPTER 5

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## Module Function List

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<code>ics.close_device</code>	Closes the device.
<code>ics.coremini_clear</code>	Clears the CoreMini into the device.
<code>ics.coremini_get_fblock_status</code>	Gets the status of a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_get_status</code>	Gets the status of the CoreMini in the device.
<code>ics.coremini_load</code>	Loads the CoreMini into the device.
<code>ics.coremini_read_app_signal</code>	Gets the value of a Coremini application signal at <i>index</i> on <i>device</i> .
<code>ics.coremini_read_rx_message</code>	Gets the value of a Coremini Message at <i>index</i> on <i>device</i> .
<code>ics.coremini_read_tx_message</code>	Gets the value of a Coremini Message at <i>index</i> on <i>device</i> .
<code>ics.coremini_start</code>	Starts the CoreMini into the device.
<code>ics.coremini_start_fblock</code>	Starts a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_stop</code>	Stops the CoreMini into the device.
<code>ics.coremini_stop_fblock</code>	Stops a Coremini Function Block at <i>index</i> on <i>device</i> .
<code>ics.coremini_write_app_signal</code>	Sets the value of a Coremini application signal at <i>index</i> on <i>device</i> .
<code>ics.coremini_write_rx_message</code>	TODO
<code>ics.coremini_write_tx_message</code>	TODO
<code>ics.create_neovi_radio_message</code>	Python API only.
<code>ics.find_devices</code>	Finds all connected devices and returns a tuple of <code>ics.NeoDevice</code> for use in <code>ics.open_device()</code>
<code>ics.firmware_update_required</code>	Determines if the device firmware needs flashing.
<code>ics.force_firmware_update</code>	Forces the device to flash firmware.
<code>ics.get_active_vnet_channel</code>	Gets active vnet channel for the device.
<code>ics.get_backup_power_enabled</code>	Returns the device backup power enabled for the device.
<code>ics.get_backup_power_ready</code>	Returns the device backup power is ready for the device.
<code>ics.get_device_settings</code>	Gets the settings in the device.
<code>ics.get_device_status</code>	Returns the device status.

Continued on next page

Table 1 – continued from previous page

<code>ics.get_dll_firmware_info</code>	Returns the DLL firmware info for the device.
<code>ics.get_dll_version</code>	Gets the DLL version.
<code>ics.get_error_messages</code>	Gets the error message(s) on the device.
<code>ics.get_hw_firmware_info</code>	Returns the device firmware info for the device.
<code>ics.get_last_api_error</code>	Gets the error message from the last API call.
<code>ics.get_library_path</code>	
<code>ics.get_messages</code>	Gets the message(s) on the device.
<code>ics.get_performance_parameters</code>	Gets the Performance Parameters on <i>device</i> .
<code>ics.get_RTC</code>	Gets the Real-Time Clock of the device.
<code>ics.get_script_status</code>	Accepts a <code>ics.NeoDevice</code> , exception on error.
<code>ics.get_serial_number</code>	Gets the serial number out of the device.
<code>ics.get_timestamp_for_msg</code>	Calculates the timestamp for a message.
<code>ics.iso15765_disable_networks</code>	Disables ISO15765 networks.
<code>ics.iso15765_enable_networks</code>	Enables ISO15765 networks.
<code>ics.iso15765_receive_message</code>	Setup rx ISO15765 Message.
<code>ics.iso15765_transmit_message</code>	Transmits an ISO15765 Message.
<code>ics.load_default_settings</code>	Load the default settings in the device.
<code>ics.open_device</code>	Opens the device.
<code>ics.override_library_name</code>	Overrides the default search for loading the <code>icsneo40</code> library
<code>ics.read_sdcard</code>	<code>icsneoReadSDCard()</code> , Accepts a <code>ics.NeoDevice</code> and sector index.
<code>ics.request_enter_sleep_mode</code>	Signal neoVI to immediate go to sleep.
<code>ics.set_active_vnet_channel</code>	Sets active vnet channel for the device.
<code>ics.set_backup_power_enabled</code>	Sets the device backup power enabled for the device.
<code>ics.set_bit_rate</code>	Specifies bit rate setting.
<code>ics.set_bit_rate_ex</code>	Sets the bitrate for a given Network ID on the device with extended options.
<code>ics.set_context</code>	Sets the “context” of how <code>icsneoFindNeoDevices(Ex)</code> and <code>icsneoOpenNeoDevice(Ex)</code> function.
<code>ics.set_device_settings</code>	Sets the settings in the device.
<code>ics.set_fd_bit_rate</code>	Sets the FD bitrate for a given Network ID on the device..
<code>ics.set_reflash_callback</code>	Sets the reflash display callback.
<code>ics.set_RTC</code>	Sets the Real-Time Clock of the device.
<code>ics.transmit_messages</code>	Transmits message(s) on the device.
<code>ics.validate_hobject</code>	Validates the handle is valid for a <i>device</i> .
<code>ics.write_sdcard</code>	<code>icsneoReadSDCard()</code> , Accepts a <code>ics.NeoDevice</code> , sector index, and a bytearray of 512 bytes.
<code>ics.ClosePort</code>	

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**Note:** Compatibility Function

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`ics.FindNeoDevices`

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**Note:** Compatibility Function

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Table 1 – continued from previous page

<i>ics.GetDLLVersion</i>	<b>Note:</b> Compatibility Function
<i>ics.GetErrorMessage</i>	<b>Note:</b> Compatibility Function
<i>ics.GetHWFirmwareInfo</i>	<b>Note:</b> Compatibility Function
<i>ics.GetLastError</i>	<b>Note:</b> Compatibility Function
<i>ics.GetMessages</i>	<b>Note:</b> Compatibility Function
<i>ics.GetPerformanceParameters</i>	<b>Note:</b> Compatibility Function
<i>ics.GetRTC</i>	<b>Note:</b> Compatibility Function
<i>ics.GetSerialNumber</i>	<b>Note:</b> Compatibility Function
<i>ics.OpenNeoDevice</i>	<b>Note:</b> Compatibility Function
<i>ics.RequestEnterSleepMode</i>	<b>Note:</b> Compatibility Function

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Table 1 – continued from previous page

<i>ics.ScriptClear</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptGetFBlockStatus</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptGetScriptStatus</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptLoad</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptReadAppSignal</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptReadRxMessage</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptReadTxMessage</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptStart</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptStartFBLOCK</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptStop</i>	<b>Note:</b> Compatibility Function

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Table 1 – continued from previous page

<i>ics.ScriptStopFBLOCK</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptWriteAppSignal</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptWriteRxMessage</i>	<b>Note:</b> Compatibility Function
<i>ics.ScriptWriteTxMessage</i>	<b>Note:</b> Compatibility Function
<i>ics.SetRTC</i>	<b>Note:</b> Compatibility Function
<i>ics.SetReflashDisplayCallback</i>	<b>Note:</b> Compatibility Function
<i>ics.TxMessages</i>	<b>Note:</b> Compatibility Function
<i>ics.ValidateHObject</i>	<b>Note:</b> Compatibility Function
<i>ics.base36enc</i>	Converts a decimal serial number to base36.
<i>ics.icsneoFirmwareUpdateRequired</i>	<b>Note:</b> Compatibility Function
<i>ics.icsneoForceFirmwareUpdate</i>	<b>Note:</b> Compatibility Function

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*ics.icsneoGetActiveVNETChannel*

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**Note:** Compatibility Function

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*ics.icsneoGetBackupPowerEnabled*

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**Note:** Compatibility Function

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*ics.icsneoGetBackupPowerReady*

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**Note:** Compatibility Function

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*ics.icsneoGetDLLFirmwareInfo*

---

**Note:** Compatibility Function

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*ics.icsneoGetDeviceStatus*

---

**Note:** Compatibility Function

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*ics.icsneoGetFireSettings*

---

**Note:** Compatibility Function

---

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*ics.icsneoGetTimeStampForMsg*

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**Note:** Compatibility Function

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*ics.icsneoGetVCAN3Settings*

---

**Note:** Compatibility Function

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*ics.icsneoISO15765\_DisableNetworks*

---

**Note:** Compatibility Function

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---

*ics.icsneoISO15765\_EnableNetworks*

---

**Note:** Compatibility Function

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Table 1 – continued from previous page

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*ics.icsneoISO15765\_ReceiveMessage*

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**Note:** Compatibility Function

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*ics.icsneoISO15765\_TransmitMessage*

---

**Note:** Compatibility Function

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*ics.icsneoLoadDefaultSettings*

---

**Note:** Compatibility Function

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*ics.icsneoReadSDCard*

---

**Note:** Compatibility Function

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*ics.icsneoScriptGetScriptStatusEx*

---

**Note:** Compatibility Function

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*ics.icsneoSetActiveVNETChannel*

---

**Note:** Compatibility Function

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*ics.icsneoSetBackupPowerEnabled*

---

**Note:** Compatibility Function

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*ics.icsneoSetBitRate*

---

**Note:** Compatibility Function

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*ics.icsneoSetBitRateEx*

---

**Note:** Compatibility Function

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*ics.icsneoSetContext*

---

**Note:** Compatibility Function

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<i>ics.icsneoSetFDBitRate</i>	<b>Note:</b> Compatibility Function
<i>ics.icsneoSetFireSettings</i>	<b>Note:</b> Compatibility Function
<i>ics.icsneoSetVCAN3Settings</i>	<b>Note:</b> Compatibility Function
<i>ics.icsneoWriteSDCard</i>	<b>Note:</b> Compatibility Function

# CHAPTER 6

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## Module Documentation

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Python C Code module for interfacing to the icsneo40 dynamic library. Code tries to respect PEP 8 (<http://python.org/dev/peps/pep-0008>). Function naming convention does not follow the tradition c style icsneo40 naming convention as pyics module name acts as the namespace (icsneo portion of the function) and function names are suppose to be lowercase with underscores instead of mixedCase like icsneo API.

**C API can be mimiced almost identically by doing the following:**

```
>>> import ics as icsneo
>>> devices = icsneo.FindNeoDevices()
>>> for device in devices:
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

**Recommended Python way by doing the following:**

```
>>> import ics
>>> devices = ics.find_devices()
>>> for device in devices:
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

It should be noted that `ics.NeoDevice` is used a little bit differently than the C API. `ics.NeoDevice` contains two extra members:

`ics.NeoDevice.AutoHandleClose` and `ics.NeoDevice._Handle`

The handle normally returned from `icsneoOpenNeoDevice()` is stored inside `_Handle` and setting `AutoHandleClose` to True (Default) will automatically close the handle when the `ics.NeoDevice` goes out of scope.

Installation:

`pip install python_ics`

<https://pypi.python.org/pypi/python-ics>

```
exception ics.ArgumentError
    Bases: Exception

exception ics.RuntimeError
    Bases: Exception

class ics.ApiFirmwareInfo
    Bases: object

    ApiFirmwareInfo object

    iAppMajor
    iAppMinor
    iBoardRevMajor
    iBoardRevMinor
    iBootLoaderVersionMajor
    iBootLoaderVersionMinor
    iMainFirmChkSum
    iMainFirmDateDay
    iMainFirmDateHour
    iMainFirmDateMin
    iMainFirmDateMonth
    iMainFirmDateSecond
    iMainFirmDateYear
    iMainVnetHWrevMajor
    iMainVnetHWrevMinor
    iMainVnetSRAMSize
    iManufactureDay
    iManufactureMonth
    iManufactureYear
    iTyPe

class ics.CanFdSettings
    Bases: object

    CanFdSettings object

    FD_BRP
    FD_Baudrate
    FD_Mode
    FD_Tq_Prop
    FD_Tq_Seg1
    FD_Tq_Seg2
    FD_Tq_Sync
```

**class ics.CanSettings**

Bases: object

CanSettings object

**BRP****Baudrate**

The bit rate of a CAN channel can be selected from a list of common bit rates Write the correct enumeration for the desired bit rate and ensure that SetBaudrate is 1(auto)

**Mode**

CAN controller mode when the neoVI device goes online or runs a CoreMini script. Normal=0 Disabled=1 Listen Only=3 Listen All=7

**SetBaudrate**

The bit rate of a CAN channel can be selected one of two ways. It can either be selected from a list of common bit rates (SetBaudrate=1) or the user can specify the CAN timing parameters (SetBaudrate=0)

**TqProp**

Propagation delay

**TqSeg1**

Phase 1 segment

**TqSeg2**

Phase 2 segment

**TqSync**

Syncro jump width

**auto\_baud**

Enables the auto bitrate feature. 1 = enable, 0 = disable.

**innerFrameDelay25us****transceiver\_mode**

Currently Not used.

**class ics.CmISO157652RxMessage**

Bases: object

CmISO157652RxMessage object

**blockSize**

Overrides the block size that the receiver reports, see overrideBlockSize. Set to J2534's BS\_TX if <= 0xFF

**cf\_timeout**

max timeout (ms) for waiting on consecutive frame. Set this to N\_CR\_MAX's value in J2534

**extendedAddress**

Extended Address byte of transmitter. see ext\_address\_enable, not supported

**fc\_id**

flow control arbId to transmit in flow control (from neoVI to ECU)

**flags****flowControlExtendedAddress**

Expected Extended Address byte of response from receiver. see fc\_ext\_address\_enable, not supported

**id**

arbId of transmitted frames (CAN id to transmit to)

**id\_mask**  
ArbId filter mask for frames from transmitter (from ECU to neoVI)

**padding**  
The padding byte to use to fill the unused portion of \* transmitted CAN frames (flow control), see paddingEnable.

**reserved**

**stMin**  
Minimum separation time (between consecutive frames) to report in flow control response

**vs\_netid**  
The netid of the message (determines which network to decode receives), not supported

**class ics.CmISO157652TxMessage**  
Bases: object  
CmISO157652TxMessage object

**blockSize**  
Overrides the block size that the receiver reports, see overrideBlockSize. Set to J2534's BS\_TX if <= 0xFF

**data**  
The data

**extendedAddress**  
Extended Address byte of transmitter. see ext\_address\_enable, not supported

**fc\_id**  
flow control arb id filter value (response id from receiver)

**fc\_id\_mask**  
The flow control arb filter mask (response id from receiver)

**flags**

**flowControlExtendedAddress**  
Expected Extended Address byte of response from receiver. see fc\_ext\_address\_enable, not supported

**fs\_timeout**  
max timeout (ms) for waiting on flow control response. Set this to N\_BS\_MAX's value if J2534

**fs\_wait**  
max timeout (ms) for waiting on flow control response after receiving flow control \* with flow status set to WAIT. Set this to N\_BS\_MAX's value if J2534.

**id**  
arbId of transmitted frames (CAN id to transmit to)

**num\_bytes**  
Number of data bytes

**padding**  
The padding byte to use to fill the unused portion of \* transmitted CAN frames (single frame, first frame, consecutive frame) \*

**stMin**  
Overrides the stMin that the receiver reports, see overrideSTmin. Set to J2534's STMIN\_TX if <= 0xFF

**tx\_index**

**vs\_netid**  
The netid of the message (determines which network to transmit on), not supported

```
class ics.CyanSettings
    Bases: object

    CyanSettings object

    ain_sample_period
    ain_threshold

    can1
        ics.CanSettings Object

    can2
        ics.CanSettings Object

    can3
        ics.CanSettings Object

    can4
        ics.CanSettings Object

    can5
        ics.CanSettings Object

    can6
        ics.CanSettings Object

    can7
        ics.CanSettings Object

    can8
        ics.CanSettings Object

    can_switch_mode

    canfd1
        ics.CanFdSettings Object

    canfd2
        ics.CanFdSettings Object

    canfd3
        ics.CanFdSettings Object

    canfd4
        ics.CanFdSettings Object

    canfd5
        ics.CanFdSettings Object

    canfd6
        ics.CanFdSettings Object

    canfd7
        ics.CanFdSettings Object

    canfd8
        ics.CanFdSettings Object

    digitalIoThresholdEnable
    digitalIoThresholdTicks
    disableUsbCheckOnBoot
    enableLatencyTest
```

```
ethernet
    ics.EthernetSettings Object

idle_wakeup_network_enables_3

iso15765_separation_time_offset

iso9141_kwp_settings_1
    Iso9141Keyword2000Settings Object

iso9141_kwp_settings_2
    Iso9141Keyword2000Settings Object

iso9141_kwp_settings_3
    Iso9141Keyword2000Settings Object

iso9141_kwp_settings_4
    Iso9141Keyword2000Settings Object

iso_msg_termination_1
    0 - use inner frame time, 1 - GME CIM-SCL

iso_msg_termination_2
    0 - use inner frame time, 1 - GME CIM-SCL

iso_msg_termination_3
    0 - use inner frame time, 1 - GME CIM-SCL

iso_msg_termination_4
    0 - use inner frame time, 1 - GME CIM-SCL

iso_parity_1
    0 - no parity, 1 - event, 2 - odd

iso_parity_2
    0 - no parity, 1 - event, 2 - odd

iso_parity_3
    0 - no parity, 1 - event, 2 - odd

iso_parity_4
    0 - no parity, 1 - event, 2 - odd

lin1
    ics.LinSettings Object

lin2
    ics.LinSettings Object

lin3
    ics.LinSettings Object

lin4
    ics.LinSettings Object

lin5
    ics.LinSettings Object

lin6
    ics.LinSettings Object

lsft1
    ics.CanSettings Object
```

```
lsft2
    ics.CanSettings Object

misc_io_analog_enable
misc_io_initial_ddr
misc_io_initial_latch
misc_io_on_report_events
misc_io_report_period
network_enabled_on_boot
network_enables
network_enables_2
network_enables_3
perf_en
pwr_man_enable
pwr_man_timeout
reserved
slaveVnetA
slaveVnetB
swcan1
    ics.SWCanSettings Object
swcan2
    ics.SWCanSettings Object
termination_enables
text_api
    ics.TextApiSettings Object

class ics.DeviceSettings
    Bases: object
    DeviceSettings object
    DeviceSettingType
cyan
    ics.CyanSettings Object
fire
    ics.FireSettings Object
radgalaxy
    ics.RadGalaxySettings Object
radstar2
    ics.RadStar2Settings Object
vcan3
    ics.Vcan3Settings Object
vcan4
    ics.Vcan4Settings Object
```

```
vcan4_12
    ics.Vcan412Settings Object

vividcan
    ics.VividCANSettings Object

class ics.EthernetSettings
    Bases: object

    EthernetSettings object

auto_neg
duplex
led_mode
link_speed
rsvd

class ics.Fire2DeviceStatus
    Bases: object

    Fire2DeviceStatus object

backupPowerEnabled
backupPowerGood
ethernetActivationLineEnabled
usbHostPowerEnabled

class ics.FireSettings
    Bases: object

    FireSettings object

ain_sample_period
ain_threshold
can1
    ics.CanSettings Object

can2
    ics.CanSettings Object

can3
    ics.CanSettings Object

can4
    ics.CanSettings Object

cgi_baud
cgi_chksum_enable
cgi_enable_reserved
cgi_rx_ifs_bit_times
cgi_tx_ifs_bit_times
fast_init_network_enables_1
fast_init_network_enables_2
```

```
iso15765_separation_time_offset
iso9141_kwp_enable_reserved
iso9141_kwp_settings
    Iso9141Keyword2000Settings Object
iso9141_kwp_settings_2
    Iso9141Keyword2000Settings Object
iso9141_kwp_settings_3
    Iso9141Keyword2000Settings Object
iso9141_kwp_settings_4
    Iso9141Keyword2000Settings Object
iso_msg_termination
    0 - use inner frame time, 1 - GME CIM-SCL
iso_msg_termination_2
    0 - use inner frame time, 1 - GME CIM-SCL
iso_msg_termination_3
    0 - use inner frame time, 1 - GME CIM-SCL
iso_msg_termination_4
    0 - use inner frame time, 1 - GME CIM-SCL
iso_parity
    0 - no parity, 1 - event, 2 - odd
iso_parity_2
    0 - no parity, 1 - event, 2 - odd
iso_parity_3
    0 - no parity, 1 - event, 2 - odd
iso_parity_4
    0 - no parity, 1 - event, 2 - odd
iso_tester_pullup_enable
lin1
    ics.LinSettings Object
lin2
    ics.LinSettings Object
lin3
    ics.LinSettings Object
lin4
    ics.LinSettings Object
lsft
    ics.CanSettings Object
misc_io_analog_enable
misc_io_initial_ddr
misc_io_initial_latch
misc_io_on_report_events
misc_io_report_period
```

```
network_enabled_on_boot
network_enables
network_enables_2
perf_en
pwm_man_timeout
pwr_man_enable
swcan
    ics.SWCanSettings Object
text_api
    ics.TextApiSettings Object
uart
    ics.UartSettings Object
uart2
    ics.UartSettings Object
vnetBits
class ics.IcsDeviceStatus
Bases: object
IcsDeviceStatus object
fire2Status
    ics.Fire2DeviceStatus Object
vcan4Status
    ics.Vcan4DeviceStatus Object
class ics.Iso9141Keyword2000InitSteps
Bases: object
Iso9141Keyword2000InitSteps object
k
l
time_500us
class ics.Iso9141Keyword2000Settings
Bases: object
Iso9141Keyword2000Settings object
Baudrate
brgh
chksum_enabled
init_steps
    Tuple of Iso9141Keyword2000InitSteps
p2_500us
p3_500us
p4_500us
```

```
spbrg
class ics.LinSettings
Bases: object
LinSettings object

Baudrate
MasterResistor
Mode
brgh
spbrg
class ics.NeoDevice
Bases: object
NeoDevice object

AutoHandleClose
    When NeoDevice is freed the handle will automatically be closed, if true.

DeviceType
Handle
IsOpen
    This contains the handle returned from icsneoOpenDevice() API. If uncertain, don't use this.

MaxAllowedClients
Name
    String describing DeviceType, extension to Python api only.

NumberOfClients
SerialNumber

class ics.OpEthGeneralSettings
Bases: object
OpEthGeneralSettings object

bEnReportLinkQuality
bTapEnPtp
bTapEnSwitch
reserved0
tapPair0
tapPair1
tapPair2
tapPair3
tapPair4
tapPair5
ucInterfaceType
```

```
class ics.OpEthSettings
    Bases: object

    OpEthSettings object

    preemption_en
    reserved0
    ucConfigMode

class ics.RadGalaxySettings
    Bases: object

    RadGalaxySettings object

    ain_sample_period
    ain_threshold

    can1
        ics.CanSettings Object

    can2
        ics.CanSettings Object

    can3
        ics.CanSettings Object

    can4
        ics.CanSettings Object

    can5
        ics.CanSettings Object

    can6
        ics.CanSettings Object

    can7
        ics.CanSettings Object

    can8
        ics.CanSettings Object

    can_switch_mode

    canfd1
        ics.CanFdSettings Object

    canfd2
        ics.CanFdSettings Object

    canfd3
        ics.CanFdSettings Object

    canfd4
        ics.CanFdSettings Object

    canfd5
        ics.CanFdSettings Object

    canfd6
        ics.CanFdSettings Object

    canfd7
        ics.CanFdSettings Object
```

```
canfd8
    ics.CanFdSettings Object

idle_wakeup_network_enables_1
idle_wakeup_network_enables_2
idle_wakeup_network_enables_3
iso15765_separation_time_offset
iso9141_kwp_settings_1
    Iso9141Keyword2000Settings Object

iso_msg_termination_1
    0 - use inner frame time, 1 - GME CIM-SCL

iso_parity_1
    0 - no parity, 1 - event, 2 - odd

lin1
    ics.LinSettings Object

misc_io_analog_enable
misc_io_initial_ddr
misc_io_initial_latch
misc_io_on_report_events
misc_io_report_period
network_enabled_on_boot
network_enables
network_enables_2
network_enables_3

opEth1
    ics.OpEthSettings Object

opEth10
    ics.OpEthSettings Object

opEth11
    ics.OpEthSettings Object

opEth12
    ics.OpEthSettings Object

opEth2
    ics.OpEthSettings Object

opEth3
    ics.OpEthSettings Object

opEth4
    ics.OpEthSettings Object

opEth5
    ics.OpEthSettings Object

opEth6
    ics.OpEthSettings Object
```

```
opEth7
    ics.OpEthSettings Object

opEth8
    ics.OpEthSettings Object

opEth9
    ics.OpEthSettings Object

opEthGen
    ics.OpEthGeneralSettings Object

perf_en

pwr_man_enable

pwr_man_timeout

swcan1
    ics.SWCanSettings Object

swcan2
    ics.SWCanSettings Object

text_api
    ics.TextApiSettings Object

class ics.RadStar2Settings
Bases: object

RadStar2Settings object

ain_sample_period

ain_threshold

can1
    ics.CanSettings Object

can2
    ics.CanSettings Object

can_switch_mode

canfd1
    ics.CanFdSettings Object

canfd2
    ics.CanFdSettings Object

hwComLatencyTestEn

idle_wakeup_network_enables_1

idle_wakeup_network_enables_2

idle_wakeup_network_enables_3

iso15765_separation_time_offset

iso9141_kwp_settings_1
    Iso9141Keyword2000Settings Object

iso_9141_kwp_enable_reserved

iso_msg_termination_1
    0 - use inner frame time, 1 - GME CIM-SCL
```

```
iso_parity_1
    0 - no parity, 1 - event, 2 - odd

lin1
    ics.LinSettings Object

misc_io_analog_enable

misc_io_initial_ddr

misc_io_initial_latch

misc_io_on_report_events

misc_io_report_period

network_enabled_on_boot

network_enables

network_enables_2

network_enables_3

opEth1
    ics.OpEthSettings Object

opEth2
    ics.OpEthSettings Object

opEthGen
    ics.OpEthGeneralSettings Object

pc_com_mode

perf_en

pwr_man_enable

pwr_man_timeout

text_api
    ics.TextApiSettings Object

timeSyncSettings
    ics.TimesyncSettings Object

class ics.SWCanSettings
Bases: object
SWCanSettings object

BRP

Baudrate
The bit rate of a CAN channel can be selected from a list of common bit rates Write the correct enumeration for the desired bit rate and ensure that SetBaudrate is 1(auto)

Mode
CAN controller mode when the neoVI device goes online or runs a CoreMini script. Normal=0 Disabled=1 Listen Only=3 Listen All=7

RESERVED

SetBaudrate
The bit rate of a CAN channel can be selected one of two ways. It can either be selected from a list of common bit rates (SetBaudrate=1) or the user can specify the CAN timing parameters (SetBaudrate=0)
```

**TqProp**  
Propagation delay

**TqSeg1**  
Phase 1 segment

**TqSeg2**  
Phase 2 segment

**TqSync**  
Syncro jump width

**auto\_baud**  
Enables the auto bitrate feature. 1 = enable, 0 = disable.

**high\_speed\_auto\_switch**

**transceiver\_mode**  
Currently Not used.

**class ics.SpyMessage**  
Bases: object  
SpyMessage object

**AckBytes**

**ArbIDOrHeader**

**Data**

**DescriptionID**  
Not Used

**ExtraDataPtr**

**ExtraDataPtrEnabled**

**MessagePieceID**  
Not Used

**MiscData**

**NetworkID**  
This value is used to identify which network this message was received on.

**NetworkID2**  
This value is used to identify which network this message was received on.

**NodeID**  
Not Used

**NumberBytesData**  
Holds the number of bytes in the Data(1 to 8) array or the number of bytes in a CAN remote frame (The DLC).

**NumberBytesHeader**  
Used for J1850/ISO messages. It indicates how many bytes are stored in the Header(1 to 4) array.

**Protocol**  
Valid values are SPY\_PROTOCOL\_CAN, SPY\_PROTOCOL\_J1850VPW, and SPY\_PROTOCOL\_ISO9141.

**StatusBitField**

**StatusBitField2**

**StatusBitField3**

**StatusBitField4**

**TimeHardware**  
Hardware time stamp. The TimeStamp is reset on device open

**TimeHardware2**  
Hardware time stamp. The TimeStamp is reset on device open

**TimeStampHardwareID**  
This is an identifier of what type of hardware timestamp is used. Since neoVI's timestamp is always the same, this doesn't change.

**TimeStampSystemID**  
This is an identifier of what type of system timestamp is used. Since WIN32 neoVI's timestamp is always the same, from the timeGetTime API, this doesn't change.

**TimeSystem**  
TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

**TimeSystem2**  
TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

**noExtraDataPtrCleanup**  
Tells Python to not clean up ExtraDataPtrMemory, If this is enabled. Ignore, if unsure.

**class ics.SpyMessageJ1850**  
Bases: object

SpyMessageJ1850 object

**AckBytes**

**Data**

**DescriptionID**  
Not Used

**ExtraDataPtr**

**ExtraDataPtrEnabled**

**Header**

**MessagePieceID**  
Not Used

**MiscData**

**NetworkID**  
This value is used to identify which network this message was received on.

**NetworkID2**  
This value is used to identify which network this message was received on.

**NodeID**  
Not Used

**NumberBytesData**  
Holds the number of bytes in the Data(1 to 8) array or the number of bytes in a CAN remote frame (The DLC).

**NumberBytesHeader**  
Used for J1850/ISO messages. It indicates how many bytes are stored in the Header(1 to 4) array.

**Protocol**  
Valid values are SPY\_PROTOCOL\_CAN, SPY\_PROTOCOL\_J1850VPW, and SPY\_PROTOCOL\_ISO9141.

**StatusBitField**

**StatusBitField2**

**StatusBitField3**

**StatusBitField4**

**TimeHardware**

Hardware time stamp. The TimeStamp is reset on device open

**TimeHardware2**

Hardware time stamp. The TimeStamp is reset on device open

**TimeStampHardwareID**

This is an identifier of what type of hardware timestamp is used. Since neoVI's timestamp is always the same, this doesn't change.

**TimeStampSystemID**

This is an identifier of what type of system timestamp is used. Since WIN32 neoVI's timestamp is always the same, from the timeGetTime API, this doesn't change.

**TimeSystem**

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

**TimeSystem2**

TimeSystem is loaded with the value received from the timeGetTime call in the WIN32 multimedia API.

**noExtraDataPtrCleanup**

Tells Python to not clean up ExtraDataPtrMemory, If this is enabled. Ignore, if unsure.

**class ics.TextApiSettings**

Bases: object

TextApiSettings object

**can1\_options**

Sets the length of the Arbitration ID's. Set to 1 for Extended and 0 for Standard

**can1\_rx\_id**

Sets or Reads the Arbitration ID for Sending Receiving API commands

**can1\_tx\_id**

Sets or Reads the Arbitration ID for Sending Text API commands

**can2\_options**

**can2\_rx\_id**

**can2\_tx\_id**

**can3\_options**

**can3\_rx\_id**

**can3\_tx\_id**

**can4\_options**

**can4\_rx\_id**

**can4\_tx\_id**

```
network_enables
    Bitfield telling which netowrk to support Text API.

class ics.TimesyncSettings
    Bases: object
    TimesyncSettings object

MasterEnable
MasterNetwork
SlaveEnable
SlaveNetwork

class ics.UartSettings
    Bases: object
    UartSettings object

Baudrate
    Holds the baud rate for the UART Connection. An example value could be 10417 or 9600

bOptions
    Bitfield containing UART Options Invert TX=1, Invert RX=2, Half Duplex=4

brgh
flow_control
    Set to 0 for no flow control and 1 for simple CTS RTS

parity
    Sets the Parity type. Valid values are None=0, Even=1, Odd=2

reserved_1
spbrg
stop_bits
    Sets the number of stop bits to use. Valid values are One=1, Two=2

class ics.Vcan3Settings
    Bases: object
    Vcan3Settings object

can1
    ics.CanSettings Object

can2
    ics.CanSettings Object

iso15765_separation_time_offset
misc_io_initial_ddr
misc_io_initial_latch
misc_io_on_report_events
misc_io_report_period
network_enabled_on_boot
network_enables
perf_en
```

```
class ics.Vcan412Settings
Bases: object

Vcan412Settings object

can1
    ics.CanSettings Object

can2
    ics.CanSettings Object

canfd1
    ics.CanFdSettings Object

canfd2
    ics.CanFdSettings Object

disableUsbCheckOnBoot
    flags

enableLatencyTest
    flags

iso15765_separation_time_offset

network_enabled_on_boot

network_enables

perf_en

pwr_man_enable

pwr_man_timeout

reserved
    flags

termination_enables

text_api
    ics.TextApiSettings Object

class ics.Vcan4DeviceStatus
Bases: object

Vcan4DeviceStatus object

ethernetActivationLineEnabled

class ics.Vcan4Settings
Bases: object

Vcan4Settings object

can1
    ics.CanSettings Object

can2
    ics.CanSettings Object

can3
    ics.CanSettings Object

can4
    ics.CanSettings Object
```

```
canfd1
    ics.CanFdSettings Object

canfd2
    ics.CanFdSettings Object

canfd3
    ics.CanFdSettings Object

canfd4
    ics.CanFdSettings Object

enableLatencyTest
    flags

enablePcEthernetComm
    flags

ethernet
    ics.EthernetSettings Object

iso15765_separation_time_offset

iso9141_kwp_settings_1
    Iso9141Keyword2000Settings Object

iso_9141_kwp_enable_reserved

iso_msg_termination_1

iso_parity_1

lin1
    ics.LinSettings Object

network_enabled_on_boot

network_enables

network_enables_2

network_enables_3

perf_en

pwr_man_enable

pwr_man_timeout

reserved
    flags

termination_enables

text_api
    ics.TextApiSettings Object

class ics.VcanRFSettings
Bases: object

VcanRFSettings object

can1
    ics.CanSettings Object

can2
    ics.CanSettings Object
```

```
can3
    ics.CanSettings Object

can4
    ics.CanSettings Object

idle_wakeup_network_enables_1
idle_wakeup_network_enables_2
iso15765_separation_time_offset
iso9141_kwp_enable_reserved
iso9141_kwp_settings
    ics.Iso9141Keyword2000Settings Object

iso9141_kwp_settings_2
    ics.Iso9141Keyword2000Settings Object

iso_msg_termination
    0 - use inner frame time, 1 - GME CIM-SCL

iso_msg_termination_2
    0 - use inner frame time, 1 - GME CIM-SCL

iso_parity
    0 - no parity, 1 - event, 2 - odd

iso_parity_2
    0 - no parity, 1 - event, 2 - odd

iso_tester_pullup_enable

lin1
    ics.LinSettings Object

lin2
    ics.LinSettings Object

misc_io_analog_enable
misc_io_initial_ddr
misc_io_initial_latch
misc_io_on_report_events
misc_io_report_period
network_enabled_on_boot
network_enables
network_enables_2
perf_en

pwr_man_enable
    0 - off, 1 - sleep enabled, 2- idle enabled (fast wakeup)

pwr_man_timeout

class ics.VividCANSettings
    Bases: object

    VividCANSettings object
```

```
can1
    ics.CanSettings Object

can_switch_mode

disableUsbCheckOnBoot
    flags

ecu_id

enableLatencyTest
    flags

iso15765_separation_time_offset

lsftcan1
    ics.CanSettings Object

network_enabled_on_boot

network_enables

perf_en

pwr_man_enable

pwr_man_timeout

reserved
    flags

swcan1
    ics.CanSettings Object

termination_enables

ics.ClosePort()
```

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.close_device()` method.

```
ics.EnableBusVoltageMonitor()
```

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.enable_bus_voltage_monitor()` method.

```
ics.EnableNetworkCom()
```

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.enable_network_com()` method.

```
ics.FindNeoDevices()
```

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.find_devices()` method.

`ics.FirmwareUpdateRequired()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.firmware_update_required()` method.

---

`ics.ForceFirmwareUpdate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.force_firmware_update()` method.

---

`ics.GetActiveVNETChannel()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_active_vnet_channel()` method.

---

`ics.GetBackupPowerEnabled()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_backup_power_enabled()` method.

---

`ics.GetBackupPowerReady()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_backup_power_ready()` method.

---

`ics.GetBusVoltage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_bus_voltage()` method.

---

`ics.GetDLLFirmwareInfo()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_dll_firmware_info()` method.

---

`ics.GetDLLVersion()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_dll_version()` method.

---

`ics.GetDeviceStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_status()` method.

---

`ics.GetErrorMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_error_messages()` method.

---

`ics.GetFireSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_settings()` method.

---

`ics.GetHWFirmwareInfo()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_hw_firmware_info()` method.

---

`ics.GetLastError()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_last_api_error()` method.

---

`ics.GetMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_messages()` method.

---

`ics.GetPerformanceParameters()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_performance_parameters()` method.

---

`ics.GetRTC()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_rtc()` method.

---

`ics.GetSerialNumber()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_serial_number()` method.

---

`ics.GetTimeStampForMsg()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_timestamp_for_msg()` method.

---

`ics.GetVCAN3Settings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_settings()` method.

---

`ics.ISO15765_DisableNetworks()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_disable_networks()` method.

---

`ics.ISO15765_EnableNetworks()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_enable_networks()` method.

---

`ics.ISO15765_ReceiveMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_receive_message()` method.

---

`ics.ISO15765_TransmitMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_transmit_message()` method.

---

`ics.LoadDefaultSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.load_default_settings()` method.

---

`ics.OpenNeoDevice()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.open_device()` method.

---

`ics.ReadSSDCard()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.read_sdcard()` method.

---

`ics.RequestEnterSleepMode()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.request_enter_sleep_mode()` method.

---

`ics.ScriptClear()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_clear()` method.

---

`ics.ScriptGetFBlockStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_get_fblock_status()` method.

---

`ics.ScriptGetScriptStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_get_status()` method.

---

`ics.ScriptGetScriptStatusEx()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_script_status()` method.

---

`ics.ScriptLoad()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_load()` method.

---

`ics.ScriptReadAppSignal()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_app_signal()` method.

---

`ics.ScriptReadRxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_rx_message()`

---

method.

---

`ics.ScriptReadTxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_tx_message()` method.

---

`ics.ScriptStart()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_start()` method.

---

`ics.ScriptStartFBlock()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_start_fblock()` method.

---

`ics.ScriptStop()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_stop()` method.

---

`ics.ScriptStopFBlock()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_stop_fblock()` method.

---

`ics.ScriptWriteAppSignal()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_app_signal()` method.

---

`ics.ScriptWriteRxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_rx_message()` method.

---

`ics.ScriptWriteTxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_tx_message()` method.

---

`ics.SetActiveVNETChannel()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_active_vnet_channel()` method.

---

`ics.SetBackupPowerEnabled()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_backup_power_enabled()` method.

---

`ics.SetBitRate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_bit_rate()` method.

---

`ics.SetBitRateEx()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_bit_rate_ex()` method.

---

`ics.SetContext()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_context()` method.

---

`ics.SetFDBitRate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_fd_bit_rate()` method.

---

`ics.SetFireSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_device_settings()` method.

---

`ics.SetRTC()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_rtc()` method.

---

`ics.SetReflashDisplayCallback()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_reflash_callback()` method.

---

`ics.SetVCAN3Settings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_device_settings()` method.

---

`ics.TxMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.transmit_messages()` method.

---

`ics.ValidateHObject()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.validate_hobject()` method.

---

`ics.WriteSDCard()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.write_sdcards()` method.

---

`ics.base36enc(serial)`

Converts a decimal serial number to base36.

**Args:** serial (int): serial number.

**Raises:** `ics.RuntimeError`

**Returns:** Str: Serial Number

```
>>> ics.base36enc(device.SerialNumber)
CY0024
```

`ics.close_device(device)`

Closes the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Error Count (int)

```
>>> for device in ics.find_devices():
...     ics.open_device(device)
...     # Do something with the device...
...     ics.close_device(device)
... 
```

---

**Note:** `ics.NeoDevice` will automatically close the device when it goes out of scope.

---

`ics.coremini_clear(device, location)`

Clears the CoreMini into the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`location (int):` Accepts `ics.SCRIPT_LOCATION_FLASH_MEM`, `ics.SCRIPT_LOCATION_SDCARD`, or `ics.SCRIPT_LOCATION_VCAN3_MEM`

**Raises:** `ics.RuntimeError`

**Returns:** None.

```
>>> device = ics.open_device()
>>> ics.coremini_clear(device, ics.SCRIPT_LOCATION_SDCARD)
```

`ics.coremini_get_fblock_status(device, index)`

Gets the status of a Coremini Function Block at `index` on `device`.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`index (int):` Index of the function block.

**Raises:** `ics.RuntimeError`

**Returns:** None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_get_fblock_status(device, 1)
True
```

`ics.coremini_get_status(device)`

Gets the status of the CoreMini in the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** True if running, otherwise False.

```
>>> device = ics.open_device()
>>> ics.coremini_get_status(device)
>>>
```

`ics.coremini_load(device, coremini, location)`

Loads the CoreMini into the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`coremini (str/tuple):` Use string to load from file, Use Tuple if file data.

`location (int):` Accepts `ics.SCRIPT_LOCATION_FLASH_MEM`, `ics.SCRIPT_LOCATION_SDCARD`, or `ics.SCRIPT_LOCATION_VCAN3_MEM`

**Raises:** `ics.RuntimeError`

**Returns:** None.

```
>>> device = ics.open_device()
>>> ics.coremini_load(device, 'cmvspy.vs3cmb', ics.SCRIPT_LOCATION_SDCARD)
```

`ics.coremini_read_app_signal(device, index)`

Gets the value of a Coremini application signal at `index` on `device`.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

index (int): Index of the application signal.

**Raises:** *ics.RuntimeError*

**Returns:** int on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_read_app_signal(device, 1)
52
```

**ics.coremini\_read\_rx\_message** (device, index, j1850=False)

Gets the value of a Coremini Message at *index* on *device*.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

index (int): Index of the application signal.

j1850 (bool): Use *ics.SpyMessageJ1850* instead.

**Raises:** *ics.RuntimeError*

**Returns:** *ics.SpyMessage* Success.

```
>>> device = ics.open_device()
>>> msg = ics.coremini_read_tx_message(device, 0)
```

**ics.coremini\_read\_tx\_message** (device, index, j1850=False)

Gets the value of a Coremini Message at *index* on *device*.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

index (int): Index of the application signal.

j1850 (bool): Use *ics.SpyMessageJ1850* instead.

**Raises:** *ics.RuntimeError*

**Returns:** *ics.SpyMessage* Success.

```
>>> device = ics.open_device()
>>> msg = ics.coremini_read_tx_message(device, 0)
```

**ics.coremini\_start** (device, location)

Starts the CoreMini into the device.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

location (int): Accepts *ics.SCRIPT\_LOCATION\_FLASH\_MEM*, *ics.SCRIPT\_LOCATION\_SDCARD*, or *ics.SCRIPT\_LOCATION\_VCAN3\_MEM*

**Raises:** *ics.RuntimeError*

**Returns:** None.

```
>>> device = ics.open_device()
>>> ics.coremini_start(device, ics.SCRIPT_LOCATION_SDCARD)
```

**ics.coremini\_start\_fblock** (device, index)

Starts a Coremini Function Block at *index* on *device*.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

index (int): Index of the function block.

**Raises:** `ics.RuntimeError`

**Returns:** None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_start_fblock(device, 1)
```

`ics.coremini_stop(device)`

Stops the CoreMini into the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** None.

```
>>> device = ics.open_device()
>>> ics.coremini_stop(device)
```

`ics.coremini_stop_fblock(device, index)`

Stops a Coremini Function Block at `index` on `device`.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`index (int): Index of the function block.`

**Raises:** `ics.RuntimeError`

**Returns:** None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_stop_fblock(device, 1)
```

`ics.coremini_write_app_signal(device, index, value)`

Sets the value of a Coremini application signal at `index` on `device`.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`index (int): Index of the application signal.`

`value (int): New value of the application signal.`

**Raises:** `ics.RuntimeError`

**Returns:** None on Success.

```
>>> device = ics.open_device()
>>> ics.coremini_write_app_signal(device, 1, 52)
>>>
```

`ics.coremini_write_rx_message(device, index, TODO)`

TODO

`ics.coremini_write_tx_message(device, index, msg)`

TODO

`ics.create_neovi_radio_message(Relay1, Relay2, Relay3, Relay4, Relay5, LED6,  
LED5, MSB_report_rate, LSB_report_rate, ana-  
log_change_report_rate, relay_timeout)`

Python API only. Generates data bytes for use with neoVI RADI/O CAN Messages

**Kwargs:** `Relay1 (boolean): Enable/Disable Relay1`

`Relay2 (boolean): Enable/Disable Relay2`

Relay3 (boolean): Enable/Disable Relay3  
Relay4 (boolean): Enable/Disable Relay4  
Relay5 (boolean): Enable/Disable Relay5  
LED5 (boolean): Enable/Disable LED5  
LED6 (boolean): Enable/Disable LED6  
MSB\_report\_rate (int): MSB Report Rate in ms (0-255)  
LSB\_report\_rate (int): LSB Report Rate in ms (0-255)  
analog\_change\_report\_rate (int): Analog change report rate  
relay\_timeout (int): Relay Timeout (0-255)\*255ms

Returns:

Tuple of data bytes for use with `ics.SpyMessage`

**Raises:** `ics.RuntimeError`

```
>>> msg = ics.SpyMessage()  
>>> msg.Data = ics.create_neovi_radio_message(Relay1=True, Relay4=False,  
    LED6=True, MSB_report_rate=10)  
>>> msg.Data  
(65, 10, 0, 0, 0)
```

`ics.enable_bus_voltage_monitor(device, enable, reserved)`

Enable or disable bus voltage monitoring.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

enable (bool): int

reserved (int): int: Optional. Should be set to zero. Don't set, if unsure.

**Raises:** `ics.RuntimeError`

Returns: None.

```
>>> import ics  
>>> d = ics.open_device()  
>>> status = ics.enable_bus_voltage_monitor(d, 1)  
>>>
```

`ics.enable_network_com(device, enable, net_id)`

Enable or disable network communication.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

enable (bool): bool

net\_id (int): int: Optional. If left blank, disables/enables all networks.

**Raises:** `ics.RuntimeError`

Returns: None.

```
>>> import ics  
>>> d = ics.open_device()  
>>> status = ics.enable_network_com(d, True)  
>>>
```

**ics.find\_devices (device\_type=ics.NEODEVICE\_ALL)**

Finds all connected devices and returns a tuple of `ics.NeoDevice` for use in `ics.open_device()`

**Args:** device\_type (int): Accepts ics.NEODEVICE\_\* Macros

*New in 3.0 (803):*

device\_type (List/Tuple): Accepts a Container of ics.NEODEVICE\_\* Macros

stOptionsOpenNeoEx (int): Usually ics.NETID\_CAN, if needed

**Raises:** `ics.RuntimeError`

**Returns:** Tuple of `ics.NeoDevice` for use in `ics.open_device()`

```
>>> for device in ics.find_devices():
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

*New in 3.0 (803):*

```
>>> for device in ics.find_devices([ics.NEODEVICE_FIRE, ics.NEODEVICE_VCAN3]):
...     print(device.Name, device.SerialNumber)
...
neoVI FIRE 59886
```

**ics.firmware\_update\_required(device)**

Determines if the device firmware needs flashing.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

```
>>> ics.force_firmware_update(device)
True
```

**ics.force\_firmware\_update(device)**

Forces the device to flash firmware.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

```
>>> ics.force_firmware_update(device)
True
```

**ics.get\_active\_vnet\_channel(device)**

Gets active vnet channel for the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Int: Returns active vnet channel.

**ics.get\_backup\_power\_enabled(device)**

Returns the device backup power enabled for the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.get_backup_power_ready(device)`

Returns the device backup power is ready for the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.get_bus_voltage(device, reserved)`

Reads bus voltage. (`ics.enable_bus_voltage_monitor`) needs to be called first.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`reserved (int): int`: Optional. Should be set to zero. Don't set, if unsure.

**Raises:** `ics.RuntimeError`

**Returns:** Int: value returned is in mV.

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.enable_bus_voltage_monitor(d, 1)
>>> ics.get_bus_voltage(d)
12000
>>>
```

`ics.get_device_settings(device, vnet_slot)`

Gets the settings in the device. `vnet_slot` defaults to `ics.PlasmaIonVnetChannelMain`

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** `ics.DeviceSettings`

```
>>> d = ics.open_device()
>>> d.Name
'neoVI ION'
>>> d.SerialNumber
404444
>>> s = ics.get_device_settings(d)
>>> s.DeviceSettingType
2
>>> s.cyan
<ics.CyanSettings object at 0x01E61B40>
>>> s.cyan.canfd1.FDMode
4
>>> s2.cyan
<ics.CyanSettings object at 0x02B113C8>
>>> s2 = ics.get_device_settings(d, ics.PlasmaIonVnetChannelA)
>>> s2.DeviceSettingType
2
>>> s2.cyan.canfd1.FDMode
4
```

`ics.get_device_status(device)`

Returns the device status.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** (`ics.IcsDeviceStatus`).

```
>>> import ics
>>> d = ics.open_device()
>>> status = ics.get_device_status(d)
>>> status.fire2Status.ethernetActivationLineEnabled
0
```

`ics.get_dll_firmware_info(device)`

Returns the DLL firmware info for the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** (`ics.ApiFirmwareInfo`)

```
>>> device = ics.open_device()
>>> info = ics.get_dll_firmware_info(device)
>>> info.iAppMajor
7
>>> info.iAppMinor
55
>>>
```

`ics.get_dll_version(device)`

Gets the DLL version.

**Args:** None

**Raises:** `ics.RuntimeError`

**Returns:** Int: DLL Version

```
>>> ics.get_dll_version()
700
```

`ics.get_error_messages(device[, j1850, timeout])`

Gets the error message(s) on the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** list of tuple's. :class:`tuple` contents: (error\_number, description\_short, description\_long, severity, restart\_needed)

```
>>> device = ics.open_device()
>>> errors = ics.get_error_messages(device)
```

`ics.get_hw_firmware_info(device)`

Returns the device firmware info for the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** (`ics.ApiFirmwareInfo`)

```
>>> device = ics.open_device()
>>> info = ics.get_hw_firmware_info(device)
>>> info.iAppMajor
7
>>> info.iAppMinor
55
>>>
```

**ics.get\_last\_api\_error (device)**

Gets the error message from the last API call.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

**Raises:** *ics.RuntimeError*

**Returns:** Tuple: (error, description short, description long, severity, restart needed)

```
>>> device = ics.open_device()
>>> try:
...     msg = ics.coremini_read_tx_message(device, 0)
... except ics.RuntimeError as ex:
...     print(ex)
...     print(ics.get_last_api_error(device))
...
Error: coremini_read_tx_message(): icsneoScriptReadTxMessage() Failed
(224, 'Invalid Message Index for script.', 'Invalid Message Index for script.
˓→', 16, 0)
```

**ics.get\_library\_path()**

**ics.get\_messages (device[, j1850, timeout])**

Gets the message(s) on the device.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

j1850 (bool): Return *ics.SpyMessageJ1850* instead.

timeout (float): Optional timeout to wait for messages in seconds (0.1 = 100ms).

**Raises:** *ics.RuntimeError*

**Returns:** tuple of two items. First item is a tuple of *ics.SpyMessage* and second is the error count.

```
>>> device = ics.open_device()
>>> messages, errors = ics.get_messages(device)
>>> len(messages)
14
>>> hex(messages[0].ArbIDOrHeader)
'0x160'
>>> messages[0].Data
(36, 11, 11, 177, 37, 3, 11, 199)
>>> errors
0
```

**ics.get\_performance\_parameters (device)**

Gets the Performance Parameters on *device*.

**Args:** device (*ics.NeoDevice*): *ics.NeoDevice*

**Raises:** *ics.RuntimeError*

**Returns:** Tuple on Success: (buffer count, buffer max, overflow count, reserved, reserved, reserved, reserved)

```
>>> device = ics.open_device()
>>> ics.get_performance_parameters(device)
(0, 24576, 0, 0, 0, 0, 0, 0)
```

`ics.get_rtc(device)`

Gets the Real-Time Clock of the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Tuple: (datetime.datetime object, offset in seconds)

```
>>> device = ics.open_device()
>>> ics.get_rtc(device)
(datetime.datetime(2014, 9, 10, 17, 45, 45), 3)
```

`ics.get_script_status()`

Accepts a `ics.NeoDevice`, exception on error. Returns a list of values of what ulParameters would hold

`ics.get_serial_number(device)`

Gets the serial number out of the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Int: Serial Number Version

```
>>> ics.get_serial_number(device)
53123
```

`ics.get_timestamp_for_msg(device, msg)`

Calculates the timestamp for a message.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`msg (ics.SpyMessage): ics.SpyMessage`

**Raises:** `ics.RuntimeError`

**Returns:** Float: Timestamp for the message.

```
>>> import ics
>>> d = ics.open_device()
>>> msgs, error_count = ics.get_messages(d)
>>> ics.get_timestamp_for_msg(d, msgs[0])
354577568.9145524
```

`ics.icsneoClosePort()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.close_device()` method.

---

`ics.icsneoEnableBusVoltageMonitor()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.enable_bus_voltage_monitor()` method.

---

`ics.icsneoEnableNetworkCom()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.enable_network_com()` method.

---

`ics.icsneoFindNeoDevices()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.find_devices()` method.

---

`ics.icsneoFirmwareUpdateRequired()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.firmware_update_required()` method.

---

`ics.icsneoForceFirmwareUpdate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.force_firmware_update()` method.

---

`ics.icsneoGetActiveVNETChannel()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_active_vnet_channel()` method.

---

`ics.icsneoGetBackupPowerEnabled()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_backup_power_enabled()` method.

---

`ics.icsneoGetBackupPowerReady()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_backup_power_ready()` method.

---

`ics.icsneoGetBusVoltage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_bus_voltage()` method.

---

`ics.icsneoGetDLLFirmwareInfo()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_dll_firmware_info()` method.

---

`ics.icsneoGetDLLVersion()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_dll_version()` method.

---

`ics.icsneoGetDeviceStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_status()` method.

---

`ics.icsneoGetErrorMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_error_messages()` method.

---

`ics.icsneoGetFireSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_settings()` method.

---

`ics.icsneoGetHWFirmwareInfo()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_hw_firmware_info()` method.

---

`ics.icsneoGetLastError()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_last_api_error()` method.

---

`ics.icsneoGetMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_messages()` method.

---

`ics.icsneoGetPerformanceParameters()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_performance_parameters()` method.

---

`ics.icsneoGetRTC()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_rtc()` method.

---

`ics.icsneoGetSerialNumber()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_serial_number()` method.

---

`ics.icsneoGetTimeStampForMsg()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_timestamp_for_msg()` method.

---

`ics.icsneoGetVCAN3Settings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_device_settings()` method.

---

`ics.icsneoISO15765_DisableNetworks()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_disable_networks()` method.

---

`ics.icsneoISO15765_EnableNetworks()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_enable_networks()` method.

---

`ics.icsneoISO15765_ReceiveMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_receive_message()` method.

---

`ics.icsneoISO15765_TransmitMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.iso15765_transmit_message()` method.

---

`ics.icsneoLoadDefaultSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.load_default_settings()` method.

---

`ics.icsneoOpenNeoDevice()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.open_device()` method.

---

`ics.icsneoReadSDCard()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.read_sdcard()` method.

---

`ics.icsneoRequestEnterSleepMode()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.request_enter_sleep_mode()` method.

---

`ics.icsneoScriptClear()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_clear()` method.

---

`ics.icsneoScriptGetFBlockStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_get_fblock_status()` method.

---

`ics.icsneoScriptGetScriptStatus()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_get_status()` method.

---

`ics.icsneoScriptGetScriptStatusEx()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.get_script_status()` method.

---

`ics.icsneoScriptLoad()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_load()` method.

---

`ics.icsneoScriptReadAppSignal()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_app_signal()` method.

---

`ics.icsneoScriptReadRxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_rx_message()` method.

---

`ics.icsneoScriptReadTxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_read_tx_message()` method.

---

`ics.icsneoScriptStart()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_start()` method.

---

`ics.icsneoScriptStartFBlock()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_start_fblock()` method.

---

`ics.icsneoScriptStop()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_stop()` method.

---

`ics.icsneoScriptStopFBlock()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_stop_fblock()` method.

---

`ics.icsneoScriptWriteAppSignal()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_app_signal()` method.

---

`ics.icsneoScriptWriteRxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_rx_message()` method.

---

`ics.icsneoScriptWriteTxMessage()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.coremini_write_tx_message()` method.

---

`ics.icsneoSetActiveVNETChannel()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_active_vnet_channel()` method.

---

`ics.icsneoSetBackupPowerEnabled()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_backup_power_enabled()` method.

---

`ics.icsneoSetBitRate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_bit_rate()` method.

---

`ics.icsneoSetBitRateEx()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_bit_rate_ex()` method.

---

`ics.icsneoSetContext()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_context()` method.

---

`ics.icsneoSetFDBitRate()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_fd_bit_rate()` method.

---

`ics.icsneoSetFireSettings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_device_settings()` method.

---

`ics.icsneoSetRTC()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_rtc()` method.

---

`ics.icsneoSetReflashDisplayCallbacks()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_reflash_callback()` method.

---

`ics.icsneoSetVCAN3Settings()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.set_device_settings()` method.

---

`ics.icsneoTxMessages()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.transmit_messages()` method.

---

`ics.icsneoValidateHObject()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.validate_hobject()` method.

---

`ics.icsneoWriteSDCard()`

---

**Note:** Compatibility Function Identical to PEP8 compliant `ics.write_sdcard()` method.

---

`ics.iso15765_disable_networks(device)`

Disables ISO15765 networks.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** None

`ics.iso15765_enable_networks(device, networks)`

Enables ISO15765 networks.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** None

`ics.iso15765_receive_message(device, netid, rx_msg)`

Setup rx ISO15765 Message.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`prx_msg (ics.CmISO15765RxMessage): ics.CmISO15765RxMessage`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.iso15765_transmit_message(device, ulNetworkID, pMsg, ulBlockingTimeout)`

Transmits an ISO15765 Message.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`pMsg (ics.CmISO15765TxMessage): ics.CmISO15765TxMessage`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.load_default_settings(device)`

Load the default settings in the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** None.

```
>>> device = ics.open_device()  
>>> settings = ics.load_default_settings(device)  
>>>
```

`ics.open_device(device)`

Opens the device. `device` can be omitted to return a `ics.NeoDevice` of the first free available device, a `ics.NeoDevice`, or a serial number of the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`device (int): Serial Number of the device`

`bNetworkIDs (int): Network Enables`

`bConfigRead (int): Config Read`

`iOptions (int): DEVICE_OPTION_* defines`

`stOptionsOpenNeoEx (int): Usually ics.NETID_CAN, if needed`

**Raises:** `ics.RuntimeError`

**Returns:** If `ics.NeoDevice` is passed as a parameter, None. If serial number is passed as a parameter, a `ics.NeoDevice` will be returned. If `device` parameter is omitted, a `ics.NeoDevice` will be returned with the first available free device.

```
>>> for device in ics.find_devices():
...     ics.open_device(device)
...
```

---

**Note:** `ics.NeoDevice` will automatically close the device when it goes out of scope.

---

**ics.override\_library\_name(new\_name)**

Overrides the default search for loading the icsneo40 library

**Args:** name: Absolute path or relative path including filename.

**Raises:** `ics.RuntimeError`

**Returns:** None

```
>>> import ics
>>> ics.find_devices()
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
ics.RuntimeError: Error: find_devices(): Failed to open library: 'icsneo40.dll'
 ↵' with error code: #126
>>> ics.override_library_name(r"C:\Windows\SysWOW64\icsneo40-different.dll")
>>> ics.find_devices()
(<ics.NeoDevice object at 0x00284C50>, <ics.NeoDevice object at 0x007C9A10>)
```

**ics.read\_sdcard()**

icsneoReadSDCard(), Accepts a `ics.NeoDevice` and sector index. Returns a bytearray of 512 bytes max. Exception on error.

**ics.request\_enter\_sleep\_mode(device, timeout\_ms, mode, reserved\_zero)**

Signal neoVI to immediate go to sleep. Currently only supported by FIREVNET/PLASMA. If using over USB this will likely return true but never cause PLASMA to sleep since USB insertion keeps it alive. This API allows Android/Linux applications to invoke power management.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

timeout\_ms (int): 16bit word for how long to wait on idle bus before going to sleep. If caller does not want to change it pass in 65535 (0xFFFF) and it will stay whatever it was set to in explorer/coremini.

mode (int): 16bit word for power mode to enter. If caller does not want to change it pass in 65535 (0xFFFF) and it will stay whatever it was set to in explorer/coremini. If it is zero then neoVI will do ‘normal sleep’. 0 - power mode off but calling this function will do ‘normal sleep’. 1 - normal sleep. 2 - instant sleep. 3 - comatose sleep.

reserved\_zero (int): Reserved, Keep as zero.

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

```
>>> ics.request_enter_sleep_mode(device, 1, 0)
True
```

**ics.set\_active\_vnet\_channel(device, channel)**

Sets active vnet channel for the device.

**Args:** device (`ics.NeoDevice`): `ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.set_backup_power_enabled(device, enable)`  
Sets the device backup power enabled for the device.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

`ics.set_bit_rate(device, BitRate, NetworkID)`  
Specifies bit rate setting. Valid values depend on the network specified.

For the networks NETID\_HSCAN, NETID\_MSCAN, NETID\_SWCAN, NETID\_FIRE\_HSCAN2, NETID\_HSCAN3, NETID\_LSFTCAN, valid bit rates are 2000, 33333, 50000, 62500, 83333, 100000, 125000, 250000, 500000, 800000, 1000000

For the networks NETID\_LIN, NETID\_ISO2, NETID\_FIRE\_LIN2, NETID\_FIRE\_LIN3, NETID\_FIRE\_LIN4, valid bit rates are

For the network NETID\_FIRE\_CGI valid bit rates are 625000 and 115200

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Int: None.

`ics.set_bit_rate_ex(device, BitRate, NetworkID, iOptions)`  
Sets the bitrate for a given Network ID on the device with extended options.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Int: None.

`ics.set_context(device)`

Sets the “context” of how icsneoFindNeoDevices(Ex) and icsneoOpenNeoDevice(Ex) function. If the context is 0 (null) than icsneoFindNeoDevices(Ex) will be system wide, searching USB and other supported computer interfaces. icsneoFindNeoDevices can then be used to connect to devices found in this manner. If the context is a handle to connected CAN tool than icsneoFindNeoDevices(Ex) will search a specific CAN bus for supported IntrepidCS CAN Nodes. Again icsneoOpenNeoDevice(Ex) would be used create logical connections to found CAN Nodes.

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

**Raises:** `ics.RuntimeError`

**Returns:** Boolean: True on success, False on failure.

```
>>> ics.set_context(device)
True
```

`ics.set_device_settings(device, settings, save_to_eeprom, vnet_slot)`  
Sets the settings in the device. vnet\_slot defaults to ics.PlasmaIonVnetChannelMain

**Args:** `device (ics.NeoDevice): ics.NeoDevice`

`settings (ics.DeviceSettings): ics.DeviceSettings`

**Raises:** `ics.RuntimeError`

**Returns:** None.

```
>>> d = ics.open_device()
>>> d.Name
'neoVI ION'
>>> d.SerialNumber
404444
>>> s = ics.get_device_settings(d, ics.PlasmaIonVnetChannelA) # Get Slave_
→settings, channel selection not needed if not a Plasma/Ion
>>> s.DeviceSettingType
2
>>> s.cyan.can_switch_mode
1
>>> s.cyan.can_switch_mode = 2
>>> ics.set_device_settings(d, s, True, ics.PlasmaIonVnetChannelA)
>>>
```

**ics.set\_fd\_bit\_rate**(*device*, *BitRate*, *NetworkID*)  
Sets the FD bitrate for a given Network ID on the device..

**Args:** *device* (*ics.NeoDevice*): *ics.NeoDevice*

**Raises:** *ics.RuntimeError*

**Returns:** Int: None.

**ics.set\_reflash\_callback**(*callback*)  
Sets the reflash display callback.

**Args:** *callback* (function): Must be a callable Python function (*def callback(msg, progress)*)

**Raises:** *ics.RuntimeError*

**Returns:** None.

```
>>> def callback(msg, progress):
...     print(msg, progress)
...
>>> ics.set_reflash_callback(callback)
>>>
```

**ics.set\_rtc**(*device*[, *time*])  
Sets the Real-Time Clock of the device.

**Args:** *device* (*ics.NeoDevice*): *ics.NeoDevice*

*ime* (*datetime.datetime*): Optional. Sets to current time, if omitted.

**Raises:** *ics.RuntimeError*

**Returns:** None.

```
>>> device = ics.open_device()
>>> ics.set_rtc(device)
```

**ics.transmit\_messages**(*device*, *messages*)  
Transmits message(s) on the device. *messages* can be a tuple of *ics.SpyMessage*

**Args:** *device* (*ics.NeoDevice*): *ics.NeoDevice*

*messages* (*ics.SpyMessage*): *ics.SpyMessage*

**Raises:** *ics.RuntimeError*

**Returns:** None.

```
>>> device = ics.open_device()
>>> msg = ics.SpyMessage()
>>> msg.ArbIDOrHeader = 0xFF
>>> msg.NetworkID = ics.NETID_HSCAN
>>> msg.Data = (0,1,2,3,4,5,6,7)
>>> ics.transmit_messages(device, msg)
>>>
```

**ics.validate\_hobject(*device*)**

Validates the handle is valid for a *device*. Handles are only valid when the device is open.

**Args:** *device* (*ics.NeoDevice*): *ics.NeoDevice*

or:

*device* (int): c style integer handle to the device.

**Raises:** *ics.RuntimeError*

**Returns:** Boolean: True if valid, false otherwise.

```
>>> device = ics.open_device()
>>> ics.validate_hobject(device)
1
>>> ics.validate_hobject(device._Handle)
1
```

**ics.write\_sdcard()**

icsneoReadSDCard(), Accepts a *ics.NeoDevice*, sector index, and a bytearray of 512 bytes. Exception on error.



# CHAPTER 7

---

## Module Variables

---

```
ics.AUTO = 0
ics.BPS100 = 5
ics.BPS1000 = 10
ics.BPS100000 = 7
ics.BPS10400 = 1
ics.BPS117647 = 8
ics.BPS125 = 6
ics.BPS20 = 0
ics.BPS2000 = 12
ics.BPS250 = 7
ics.BPS33 = 1
ics.BPS3333 = 2
ics.BPS4000 = 13
ics.BPS50 = 2
ics.BPS500 = 8
ics.BPS5000 = 0
ics.BPS50000 = 3
ics.BPS62 = 3
ics.BPS62500 = 4
ics.BPS666 = 11
ics.BPS71429 = 5
ics.BPS800 = 9
```

```
    ics.BPS83 = 4
    ics.BPS83333 = 6
    ics.BUILD_DATETIME = May 29 2018 16:04:26
    ics.CANFD_BRS_ENABLED = 2
    ics.CANFD_BRS_ENABLED_ISO = 4
    ics.CANFD_ENABLED = 1
    ics.CANFD_ENABLED_ISO = 3
    ics.CANFD_SETTINGS_SIZE = 10
    ics.CANTERM_SETTINGS_SIZE = 6
    ics.CAN_BPS10000 = 17
    ics.CAN_BPS5000 = 14
    ics.CAN_BPS6667 = 15
    ics.CAN_BPS8000 = 16
    ics.CAN_SETTINGS_SIZE = 12
    ics.DISABLE = 1
    ics.ETHERNET_SETTINGS_SIZE = 8
    ics.FAST_MODE = 3
    ics.GLOBAL_SETTINGS_SIZE = 908
    ics.GS_VERSION = 5
    ics.ISO15765_2_NETWORK_HSCAN = 1
    ics.ISO15765_2_NETWORK_HSCAN2 = 4
    ics.ISO15765_2_NETWORK_HSCAN3 = 8
    ics.ISO15765_2_NETWORK_HSCAN4 = 20
    ics.ISO15765_2_NETWORK_HSCAN5 = 24
    ics.ISO15765_2_NETWORK_HSCAN6 = 28
    ics.ISO15765_2_NETWORK_HSCAN7 = 32
    ics.ISO15765_2_NETWORK_MSCAN = 2
    ics.ISO15765_2_NETWORK_SWCAN = 16
    ics.ISO15765_2_NETWORK_SWCAN2 = 36
    ics.ISO9141_KEYWORD2000_SETTINGS_SIZE = 114
    ics.ISO9141_KEYWORD2000_INIT_STEP_SIZE = 6
    ics.J1708_SETTINGS_SIZE = 2
    ics.LIN_SETTINGS_SIZE = 10
    ics.LISTEN_ALL = 7
    ics.LISTEN_ONLY = 3
    ics.LOOPBACK = 2
```

```
ics.NEODEVICE_ALL = -16385
ics.NEODEVICE_ANY_ION = 1310720
ics.NEODEVICE_ANY_PLASMA = 208896
ics.NEODEVICE_BLUE = 1
ics.NEODEVICE_CMPROBE = 8388608
ics.NEODEVICE_CT_OBD = 32768
ics.NEODEVICE_DW_VCAN = 4
ics.NEODEVICE_ECU = 128
ics.NEODEVICE_ECUCHIP_UART = 2048
ics.NEODEVICE_EEVB = 16777216
ics.NEODEVICE_FIRE = 8
ics.NEODEVICE_FIRE2 = 67108864
ics.NEODEVICE_FIRE_VNET = 8192
ics.NEODEVICE_FLEX = 134217728
ics.NEODEVICE_IEVB = 256
ics.NEODEVICE_ION_2 = 262144
ics.NEODEVICE_ION_3 = 1048576
ics.NEODEVICE_NEOANALOG = 16384
ics.NEODEVICE_NEOECUCHIP = 256
ics.NEODEVICE_OBD2_PRO = 1024
ics.NEODEVICE_OBD2_SIM = -2147483648
ics.NEODEVICE_PENDANT = 512
ics.NEODEVICE_PLASMA_1_11 = 4096
ics.NEODEVICE_PLASMA_1_12 = 65536
ics.NEODEVICE_PLASMA_1_13 = 131072
ics.NEODEVICE_RADGALAXY = 268435456
ics.NEODEVICE_RADSTAR = 524288
ics.NEODEVICE_RADSTAR2 = 536870912
ics.NEODEVICE_RED = 64
ics.NEODEVICE_SW_VCAN = 2
ics.NEODEVICE_UNKNOWN = 0
ics.NEODEVICE_VCAN3 = 16
ics.NEODEVICE_VCAN4 = 2097152
ics.NEODEVICE_VCAN4_12 = 4194304
ics.NEODEVICE_VCANRF = 33554432
ics.NEODEVICE_VIVIDCAN = 1073741824
```

```
    ics.NEOVI6_VCAN_TIMESTAMP_1 = 1e-06
    ics.NEOVI6_VCAN_TIMESTAMP_2 = 0.065536
    ics.NEOVIPRO_VCAN_TIMESTAMP_1 = 1e-06
    ics.NEOVIPRO_VCAN_TIMESTAMP_2 = 0.065536
    ics.NEOVI_3G_MAX_SETTINGS_SIZE = 908
    ics.NEOVI_COMMTYPE_FIRE_USB = 5
    ics.NEOVI_COMMTYPE_RS232 = 0
    ics.NEOVI_COMMTYPE_TCPIP = 3
    ics.NEOVI_COMMTYPE_USB_BULK = 1
    ics.NEOVI_RED_TIMESTAMP_1_10NS = 1e-08
    ics.NEOVI_RED_TIMESTAMP_1_25NS = 2.5e-08
    ics.NEOVI_RED_TIMESTAMP_2_10NS = 429.4967296
    ics.NEOVI_RED_TIMESTAMP_2_25NS = 107.3741824
    ics.NEOVI_TIMESTAMP_1 = 1.6e-06
    ics.NEOVI_TIMESTAMP_2 = 0.1048576
    ics.NEO_CFG_MPIC_HS_CAN_CNF1 = 522
    ics.NEO_CFG_MPIC_HS_CAN_CNF2 = 521
    ics.NEO_CFG_MPIC_HS_CAN_CNF3 = 520
    ics.NEO_CFG_MPIC_HS_CAN_MODE = 566
    ics.NEO_CFG_MPIC_LSFT_CAN_CNF1 = 558
    ics.NEO_CFG_MPIC_LSFT_CAN_CNF2 = 557
    ics.NEO_CFG_MPIC_LSFT_CAN_CNF3 = 556
    ics.NEO_CFG_MPIC_MS_CAN_CNF1 = 534
    ics.NEO_CFG_MPIC_MS_CAN_CNF2 = 533
    ics.NEO_CFG_MPIC_MS_CAN_CNF3 = 532
    ics.NEO_CFG_MPIC_SW_CAN_CNF1 = 546
    ics.NEO_CFG_MPIC_SW_CAN_CNF2 = 545
    ics.NEO_CFG_MPIC_SW_CAN_CNF3 = 544
    ics.NETID_3G_APP_SIGNAL_STATUS = 56
    ics.NETID_3G_FB_STATUS = 55
    ics.NETID_3G_LOGGING_OVERFLOW = 59
    ics.NETID_3G_READ_DATALINK_CM_RX_MSG = 58
    ics.NETID_3G_READ_DATALINK_CM_TX_MSG = 57
    ics.NETID_3G_READ_SETTINGS_EX = 60
    ics.NETID_3G_RESET_STATUS = 54
    ics.NETID_AUX = 7
```

```
    ics.NETID_CGI = 53
    ics.NETID_DATA_TO_HOST = 70
    ics.NETID_DEVICE = 0
    ics.NETID_DEVICE_STATUS = 513
    ics.NETID_ETHERNET = 93
    ics.NETID_ETHERNET_DAQ = 69
    ics.NETID_FLEXRAY = 85
    ics.NETID_FLEXRAY1A = 80
    ics.NETID_FLEXRAY1B = 81
    ics.NETID_FLEXRAY2 = 86
    ics.NETID_FLEXRAY2A = 82
    ics.NETID_FLEXRAY2B = 83
    ics.NETID_FORDSCP = 5
    ics.NETID_GMFSA = 94
    ics.NETID_HSCAN = 1
    ics.NETID_HSCAN2 = 42
    ics.NETID_HSCAN3 = 44
    ics.NETID_HSCAN4 = 61
    ics.NETID_HSCAN5 = 62
    ics.NETID_HSCAN6 = 96
    ics.NETID_HSCAN7 = 97
    ics.NETID_HW_COM_LATENCY_TEST = 512
    ics.NETID_I2C1 = 71
    ics.NETID_INVALID = 65535
    ics.NETID_ISO = 9
    ics.NETID_ISO14230 = 15
    ics.NETID_ISO2 = 14
    ics.NETID_ISO3 = 41
    ics.NETID_ISO4 = 47
    ics.NETID_ISOPIC = 10
    ics.NETID_J1708 = 6
    ics.NETID_JVPW = 8
    ics.NETID_LIN = 16
    ics.NETID_LIN2 = 48
    ics.NETID_LIN3 = 49
    ics.NETID_LIN4 = 50
```

```
    ics.NETID_LIN5 = 84
    ics.NETID_LIN6 = 98
    ics.NETID_LSFTCAN = 4
    ics.NETID_LSFTCAN2 = 99
    ics.NETID_MAIN51 = 11
    ics.NETID_MAX = 100
    ics.NETID_MOST = 51
    ics.NETID_MOST150 = 92
    ics.NETID_MOST25 = 90
    ics.NETID_MOST50 = 91
    ics.NETID_MSCAN = 2
    ics.NETID_OP_ETHERNET1 = 17
    ics.NETID_OP_ETHERNET10 = 78
    ics.NETID_OP_ETHERNET11 = 79
    ics.NETID_OP_ETHERNET12 = 87
    ics.NETID_OP_ETHERNET2 = 18
    ics.NETID_OP_ETHERNET3 = 19
    ics.NETID_OP_ETHERNET4 = 45
    ics.NETID_OP_ETHERNET5 = 46
    ics.NETID_OP_ETHERNET6 = 73
    ics.NETID_OP_ETHERNET7 = 75
    ics.NETID_OP_ETHERNET8 = 76
    ics.NETID_OP_ETHERNET9 = 77
    ics.NETID_RED = 12
    ics.NETID_RED_APP_ERROR = 52
    ics.NETID_RED_VBAT = 74
    ics.NETID_RS232 = 63
    ics.NETID_SCI = 13
    ics.NETID_SPI1 = 72
    ics.NETID_SWCAN = 3
    ics.NETID_SWCAN2 = 68
    ics.NETID_TCP = 95
    ics.NETID_TEXTAPI_TO_HOST = 71
    ics.NETID_UART = 64
    ics.NETID_UART2 = 65
    ics.NETID_UART3 = 66
```

```
    ics.NETID_UART4 = 67
    ics.NORMAL = 0
    ics.NORMAL_MODE = 2
    ics.NO_CANFD = 0
    ics.OPETH_FUNC_MEDIA CONVERTER = 1
    ics.OPETH_FUNC_TAP = 0
    ics.OPETH_FUNC_TAP_LOW_LATENCY = 2
    ics.OPETH_LINK_AUTO = 0
    ics.OPETH_LINK_MASTER = 1
    ics.OPETH_LINK_SLAVE = 2
    ics.OPETH_MAC_SPOOF_DST_ADDR = 0
    ics.OPETH_MAC_SPOOF_SRC_ADDR = 1
    ics.OP_ETH_GENERAL_SETTINGS_SIZE = 20
    ics.OP_ETH_SETTINGS_SIZE = 16
    ics.PLASMA_SLAVE1_OFFSET = 100
    ics.PLASMA_SLAVE1_OFFSET_RANGE2 = 4608
    ics.PLASMA_SLAVE2_OFFSET = 200
    ics.PLASMA_SLAVE2_OFFSET_RANGE2 = 8704
    ics.PLASMA_SLAVE3_OFFSET_RANGE2 = 12800
    ics.PLASMA_SLAVE_NUM = 51
    ics.REPORT_ON_GPS = 15
    ics.REPORT_ON_KLINE = 9
    ics.REPORT_ON_LED1 = 7
    ics.REPORT_ON_LED2 = 8
    ics.REPORT_ON_MISC1 = 1
    ics.REPORT_ON_MISC2 = 2
    ics.REPORT_ON_MISC3 = 3
    ics.REPORT_ON_MISC3_AIN = 10
    ics.REPORT_ON_MISC4 = 4
    ics.REPORT_ON_MISC4_AIN = 11
    ics.REPORT_ON_MISC5 = 5
    ics.REPORT_ON_MISC5_AIN = 12
    ics.REPORT_ON_MISC6 = 6
    ics.REPORT_ON_MISC6_AIN = 13
    ics.REPORT_ON_PERIODIC = 0
    ics.REPORT_ON_PWM_IN1 = 14
```

```
    ics.ICS_RESISTOR_OFF = 1
    ics.ICS_RESISTOR_ON = 0
    ics.ICS_SCRIPT_LOCATION_FLASH_MEM = 0
    ics.ICS_SCRIPT_LOCATION_INTERNAL_FLASH = 2
    ics.ICS_SCRIPT_LOCATION_SDCARD = 1
    ics.ICS_SCRIPT_LOCATION_VCAN3_MEM = 4
    ics.ICS_SCRIPT_STATUS_RUNNING = 1
    ics.ICS_SCRIPT_STATUS_STOPPED = 0
    ics.ICS_SLEEP_MODE = 0
    ics.ICS_SLOW_MODE = 1
    ics.ICS_SPY_PROTOCOL_BEAN = 11
    ics.ICS_SPY_PROTOCOL_CAN = 1
    ics.ICS_SPY_PROTOCOL_CANFD = 30
    ics.ICS_SPY_PROTOCOL_CGI = 18
    ics.ICS_SPY_PROTOCOL_CHRYSLER_CCD = 8
    ics.ICS_SPY_PROTOCOL_CHRYSLER_JVPW = 14
    ics.ICS_SPY_PROTOCOL_CHRYSLER_SCI = 9
    ics.ICS_SPY_PROTOCOL_CUSTOM = 0
    ics.ICS_SPY_PROTOCOL_DALLAS_1WIRE = 25
    ics.ICS_SPY_PROTOCOL_ETHERNET = 29
    ics.ICS_SPY_PROTOCOL_FLEXRAY = 16
    ics.ICS_SPY_PROTOCOL_FORD_UBP = 10
    ics.ICS_SPY_PROTOCOL_GENERIC_MANCHSESTER = 26
    ics.ICS_SPY_PROTOCOL_GENERIC_UART = 22
    ics.ICS_SPY_PROTOCOL_GME_CIM_SCL_KLINE = 19
    ics.ICS_SPY_PROTOCOL_GMFSA = 31
    ics.ICS_SPY_PROTOCOL_GMLAN = 2
    ics.ICS_SPY_PROTOCOL_GM_ALDL_UART = 7
    ics.ICS_SPY_PROTOCOL_I2C = 21
    ics.ICS_SPY_PROTOCOL_ISO9141 = 5
    ics.ICS_SPY_PROTOCOL_J1708 = 13
    ics.ICS_SPY_PROTOCOL_J1850PWM = 4
    ics.ICS_SPY_PROTOCOL_J1850VPW = 3
    ics.ICS_SPY_PROTOCOL_J1939 = 15
    ics.ICS_SPY_PROTOCOL_JTAG = 23
    ics.ICS_SPY_PROTOCOL_LIN = 12
```

```
    ics.SPY_PROTOCOL_MOST = 17
    ics.SPY_PROTOCOL_SENT_PROTOCOL = 27
    ics.SPY_PROTOCOL_SPI = 20
    ics.SPY_PROTOCOL_TCP = 32
    ics.SPY_PROTOCOL_UART = 28
    ics.SPY_PROTOCOL_UNIO = 24
    ics.SPY_STATUS2_CAN_HAVE_LINK_DATA = 4194304
    ics.SPY_STATUS2_CAN_ISO15765_LOGICAL_FRAME = 2097152
    ics.SPY_STATUS2_END_OF_LONG_MESSAGE = 1048576
    ics.SPY_STATUS2_ERROR_FRAME = 131072
    ics.SPY_STATUS2_ETHERNET_CRC_ERROR = 2097152
    ics.SPY_STATUS2_ETHERNET_FCS_AVAILABLE = 8388608
    ics.SPY_STATUS2_ETHERNET_FRAME_TOO_SHORT = 4194304
    ics.SPY_STATUS2_ETHERNET_NO_PADDING = 16777216
    ics.SPY_STATUS2_ETHERNET_PREEMPTION_ENABLED = 33554432
    ics.SPY_STATUS2_FLEXRAY_NO_CRC = 33554432
    ics.SPY_STATUS2_FLEXRAY_NO_HEADERCRC = 67108864
    ics.SPY_STATUS2_FLEXRAY_TX_AB = 2097152
    ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_A = 4194304
    ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_B = 8388608
    ics.SPY_STATUS2_FLEXRAY_TX_AB_NO_MATCH = 16777216
    ics.SPY_STATUS2_GLOBAL_CHANGE = 65536
    ics.SPY_STATUS2_HAS_VALUE = 1
    ics.SPY_STATUS2_HIGH_VOLTAGE = 4
    ics.SPY_STATUS2_ISO_FRAME_ERROR = 134217728
    ics.SPY_STATUS2_ISO_OVERFLOW_ERROR = 268435456
    ics.SPY_STATUS2_ISO_PARITY_ERROR = 536870912
    ics.SPY_STATUS2_LIN_ERR_MSG_ID_PARITY = 67108864
    ics.SPY_STATUS2_LIN_ERR_RX_BREAK_NOT_0 = 2097152
    ics.SPY_STATUS2_LIN_ERR_RX_BREAK_TOO_SHORT = 4194304
    ics.SPY_STATUS2_LIN_ERR_RX_DATA_GREATER_8 = 16777216
    ics.SPY_STATUS2_LIN_ERR_RX_SYNC_NOT_55 = 8388608
    ics.SPY_STATUS2_LIN_ERR_TX_RX_MISMATCH = 33554432
    ics.SPY_STATUS2_LIN_ID_FRAME_ERROR = 268435456
    ics.SPY_STATUS2_LIN_NO_SLAVE_DATA = -2147483648
    ics.SPY_STATUS2_LIN_SLAVE_BYTE_ERROR = 536870912
```

```
    ics.SPY_STATUS2_LIN_SYNC_FRAME_ERROR = 134217728
    ics.SPY_STATUS2_LONG_MESSAGE = 8
    ics.SPY_STATUS2_MOST_CHANGED_PAR = -2147483648
    ics.SPY_STATUS2_MOST_CONTROL_DATA = 16777216
    ics.SPY_STATUS2_MOST_I2S_DUMP = 134217728
    ics.SPY_STATUS2_MOST_LOW_LEVEL = 8388608
    ics.SPY_STATUS2_MOST_MHP_CONTROL_DATA = 67108864
    ics.SPY_STATUS2_MOST_MHP_USER_DATA = 33554432
    ics.SPY_STATUS2_MOST_MOST150 = 1073741824
    ics.SPY_STATUS2_MOST_MOST50 = 536870912
    ics.SPY_STATUS2_MOST_PACKET_DATA = 2097152
    ics.SPY_STATUS2_MOST_TOO_SHORT = 268435456
    ics.SPY_STATUS2_RX_TIMEOUT_ERROR = 1073741824
    ics.SPY_STATUS2_VALUE_IS_BOOLEAN = 2
    ics.SPY_STATUS3_CANFD_BRS = 16
    ics.SPY_STATUS3_CANFD_ESI = 1
    ics.SPY_STATUS3_CANFD_FDF = 8
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